

SLWS211B-JULY 2008-REVISED OCTOBER 2008

14/12-Bit, 250/210 MSPS ADCs With DDR LVDS and Parallel CMOS Outputs

FEATURES

- Maximum Sample Rate: 250 MSPS
- 14-Bit Resolution ADS614X
- 12-Bit Resolution ADS612X
- 687 mW Total Power Dissipation at 250 MSPS
- Double Data Rate (DDR) LVDS and Parallel CMOS Output Options
- Programmable Fine Gain up to 6dB for SNR/SFDR Trade-Off
- DC Offset Correction
- Supports Input Clock Amplitude Down to 400
 mV_{PP} Differential
- Internal and External Reference Support
- 48-QFN Package (7mm × 7mm)
- Pin Compatible with ADS5547 Family

APPLICATIONS

- Multicarrier, Wide Band-Width
 Communications
- Wireless Multi-carrier Communications
 Infrastructure
- Software Defined Radio
- Power Amplifier Linearization
- 802.16d/e
- Test and Measurement Instrumentation
- High Definition Video
- Medical Imaging
- Radar Systems

DESCRIPTION

ADS614X (ADS612X) is a family of 14-bit (12-bit) A/D converters with sampling rates up to 250 MSPS. It combines high dynamic performance and low power consumption in a compact 48 QFN package. This makes it well-suited for multicarrier, wide band-width communications applications.

ADS614X/2X has fine gain options that can be used to improve SFDR performance at lower full-scale input ranges. It includes a dc offset correction loop that can be used to cancel the ADC offset. Both DDR LVDS (Double Data Rate) and parallel CMOS digital output interfaces are available. At lower sampling rates, the ADC automatically operates at scaled down power with no loss in performance.

It includes internal references while the traditional reference pins and associated decoupling capacitors have been eliminated. Nevertheless, the device can also be driven with an external reference. The device is specified over the industrial temperature range $(-40^{\circ}\text{C to } 85^{\circ}\text{C})$.

| | 250 MSPS | 210 MSPS |
|--------------------------|----------|----------|
| ADS614X 14-Bit Family | ADS6149 | ADS6148 |
| ADS612X 12-Bit Family | ADS6129 | ADS6128 |



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

SLWS211B-JULY 2008-REVISED OCTOBER 2008

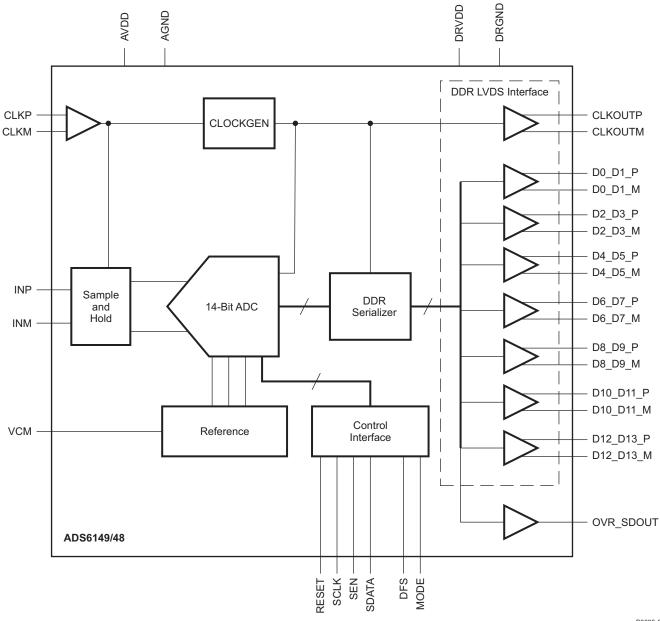


www.ti.com



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

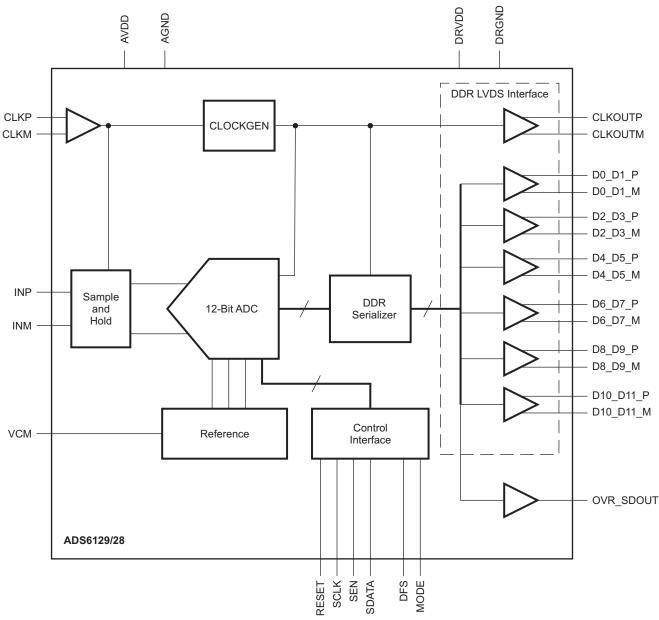
ADS614X BLOCK DIAGRAM





SLWS211B-JULY 2008-REVISED OCTOBER 2008

ADS612X BLOCK DIAGRAM



B0095-07

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

PACKAGE/ORDERING INFORMATION⁽¹⁾⁽²⁾

| PRODUCT | PACKAGE-LEAD | PACKAGE DESIGNATOR | SPECIFIED TEMPERATURE RANGE | LEAD/BALL FINISH | PACKAGE MARKING | ORDERING NUMBER | TRANSPORT MEDIA, QUANTITY |
|---------|--------------|-----------------------|-----------------------------------|---------------------|--------------------|--------------------|------------------------------|
| ADS614x | | | · | • | | | |
| 4000140 | | | | | AZ6149 | ADS6149IRGZR | |
| ADS6149 | QFN-48 | RGZ | –40°C to 85°C | Cu NiPdAu | | ADS6149IRGZT | Topo and real |
| ADS6148 | QFIN-46 | RGZ | -40°C 10 85°C | CUINPOAU | | ADS6148IRGZR | Tape and reel |
| AD50140 | | | | | | ADS6148IRGZT | |
| ADS612x | | | | | | | |
| ADS6129 | | | | | A 76120 | ADS6129IRGZR | |
| AD56129 | | DO7 | 10%C to 05%C | | AZ6129 | ADS6129IRGZT | Topo and real |
| 4000400 | QFN-48 | RGZ | –40°C to 85°C | Cu NiPdAu | | ADS6128IRGZR | Tape and reel |
| ADS6128 | | | | | AZ6128 | ADS6128IRGZT | |

(1) For thermal pad size on the package, see the mechanical drawings at the end of this data sheet. $\theta_{JA} = 25.41^{\circ}$ C/W (0LFM air flow), $\theta_{JC} = 16.5^{\circ}$ C/W when used with 2oz. copper trace and pad soldered directly to a JEDEC standard four layer 3 in x 3 in (7.62 cm x 7.62 cm) PCB.

(2) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

| | | VALUE | UNIT |
|------------------|---|--|------|
| | Supply voltage range, AVDD | -0.3 V to 3.9 | V |
| | Supply voltage range, DRVDD | -0.3 V to 2.2 | V |
| | Voltage between AGND and DRGND | -0.3 to 0.3 | V |
| | Voltage between AVDD to DRVDD (when AVDD leads DRVDD) | 0 to 3.3 | V |
| VI | Voltage between DRVDD to AVDD (when DRVDD leads AVDD) | -1.5 to 1.8 | V |
| | Voltage applied to external pin, VCM (in external reference mode) | -0.3 to 2.0 | V |
| | Voltage applied to analog input pins - INP, INM | -0.3V to minimum (3.6, AVDD + 0.3V) | V |
| | Voltage applied to input pins - CLKP, CLKM $^{\rm (2)}$, RESET, SCLK, SDATA, SEN, DFS and MODE | -0.3V to AVDD + 0.3V | V |
| T _A | Operating free-air temperature range | -40 to 85 | °C |
| TJ | Operating junction temperature range | 125 | °C |
| T _{stg} | Storage temperature range | -65 to 150 | °C |

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

(2) When AVDD is turned off, it is recommended to switch off the input clock (or ensure the voltage on CLKP, CLKM is < |0.3V|. This prevents the ESD protection diodes at the clock input pins from turning on.



SLWS211B-JULY 2008-REVISED OCTOBER 2008

www.ti.com

RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

| | | | MIN | TYP | MAX | UNIT |
|----------------|--|--|-----|------------|-----|-----------------|
| SUPPLIE | ES | | | | | |
| AVDD | Analog supply voltage | | 3 | 3.3 | 3.6 | V |
| DRVDD | Digital supply voltage | | 1.7 | 1.8 | 1.9 | V |
| ANALOG | G INPUTS | | | | | |
| | Differential input voltage range | | | 2 | | V _{pp} |
| | Input common-mode voltage | | | 1.5 ±0.1 | | V |
| | Voltage applied on CM in external refer | ence mode | | 1.5 ± 0.05 | | V |
| | Maximum analog input frequency with 2 | 2 V _{PP} input amplitude ⁽¹⁾ | | 500 | | MHz |
| | Maximum analog input frequency with 1 | I V _{PP} input amplitude ⁽¹⁾ | | 800 | | MHz |
| CLOCK | INPUT | | | | | |
| | land de la consta acta | ADS6149 / ADS6129 | 1 | | 250 | MODO |
| | Input clock sample rate | ADS6148 / ADS6128 | 1 | | 210 | MSPS |
| | | Sine wave, ac-coupled | 0.3 | 1.5 | | |
| | Input Clock amplitude differential | LVPECL, ac-coupled | | 1.6 | | V _{pp} |
| | (V _{CLKP} -V _{CLKM}) | LVDS, ac-coupled | | 0.7 | | |
| | | LVCMOS, single-ended, ac-coupled | | 3.3 | | V |
| | Input clock duty cycle | | 40% | 50% | 60% | |
| DIGITAL | OUTPUTS | | | | | |
| CL | Maximum external load capacitance fro | m each output pin to DRGND | | 5 | | pF |
| R _L | Differential load resistance between the | e LVDS output pairs (LVDS mode) | | 100 | | Ω |
| T _A | Operating free-air temperature | | -40 | | 85 | °C |

(1) See the Theory of Operation in the application section.

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

ELECTRICAL CHARACTERISTICS – ADS614X and ADS612X

Typical values are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, 50% clock duty cycle, -1dBFS differential analog input, internal reference mode unless otherwise noted.

Min and max values are across the full temperature range $T_{MIN} = -40^{\circ}$ C to $T_{MAX} = 85^{\circ}$ C, AVDD = 3.3 V, DRVDD = 1.8 V

| | PARAMETER | ADS61 25 | 49/ADS 0 MSPS | | | 148/ADS 10 MSPS | | UNIT |
|--------------------|---|-------------|------------------|------|-------|--------------------|------|-----------------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| ANALOG | INPUT | | | | | | | |
| | Differential input voltage range | | 2 | | | 2 | | V _{PP} |
| | Differential input resistance (at dc), See Figure 97 | | >1 | | | >1 | | MΩ |
| | Differential input capacitance, See Figure 98 | | 3.5 | | | 3.5 | | pF |
| | Analog Input Bandwidth | | 700 | | | 700 | | MHz |
| | Analog Input common mode current (per input pin) | | 2 | | | 2 | | μA/MSPS |
| | VCM Common mode output voltage | | 1.5 | | | 1.5 | | V |
| | VCM output current capability | | ±4 | | | ±4 | | mA |
| DC ACCL | JRACY | | | | | | | |
| | Offset error | -15 | ±2 | 15 | -15 | ±2 | 15 | mV |
| | Temperature coefficient of offset error | | 0.005 | | | 0.005 | | mV/°C |
| | Variation of offset error with supply | | 0.3 | | | 0.3 | | mV/V |
| E _{GREF} | Gain error due to internal reference inaccuracy alone | -1.25 | ±0.2 | 1.25 | -1.25 | ±0.2 | 1.25 | %FS |
| E _{GCHAN} | Gain error of channel alone | | 0.2 | | | 0.2 | | %FS |
| | Temperature coefficient of E _{GCHAN} | | .001 | | | .001 | | ∆%/°C |
| POWER S | SUPPLY | | | | | | | |
| I _{AVDD} | Analog supply current | | 170 | | | 155 | | mA |
| | Output buffer supply current, LVDS interface with 100 Ω external termination | | 70 | | | 65 | | mA |
| IDRVDD | Output buffer supply current, CMOS interface Fin = 3 MHz ⁽¹⁾ , 10-pF external load capacitance | | 56 | | | 48 | | mA |
| | Analog power | | 561 | 630 | | 510 | 570 | mW |
| | Digital power LVDS interface | | 126 | 160 | | 118 | 153 | mW |
| | Digital power CMOS interface, Fin = 3 MHz ⁽²⁾ , 10-pF external load capacitance | | 101 | | | 87 | | mW |
| | Global power down | | 20 | 50 | | 20 | 50 | mW |
| | Standby | | 120 | | | 120 | | mW |

(1) In CMOS mode, the DRVDD current scales with the sampling frequency, the load capacitance on output pins, input frequency and the supply voltage (see Figure 91 and CMOS interface power dissipation in application section).

(2) The maximum DRVDD current with CMOS interface depends on the actual load capacitance on the digital output lines. Note that the maximum recommended load capacitance on each digital output line is 10 pF.

6

Copyright © 2008, Texas Instruments Incorporated



SLWS211B-JULY 2008-REVISED OCTOBER 2008

www.ti.com

ELECTRICAL CHARACTERISTICS – ADS6149 and ADS6148

Typical values are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, 50% clock duty cycle, -1dBFS differential analog input, internal reference mode unless otherwise noted.

Min and max values are across the full temperature range $T_{MIN} = -40^{\circ}$ C to $T_{MAX} = 85^{\circ}$ C, AVDD = 3.3 V, DRVDD = 1.8 V

| PARAM | ETER | | DS6149 0 MSP | - | ADS6148 210 MSPS | | | UNIT |
|---|---------------|-------|-----------------|-----|---------------------|------|-----|------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| | Fin = 20 MHz | | 73.4 | | | 73.4 | | |
| | Fin = 80 MHz | | 72.7 | | | 72.7 | | |
| SNR Signal to noise ratio, LVDS | Fin = 100 MHz | | 72.3 | | | 72.3 | | dBFS |
| | Fin = 170 MHz | 69 | 71.3 | | 69.7 | 71.2 | | |
| | Fin = 300 MHz | | 69 | | | 69 | | |
| | Fin = 20 MHz | | 73.2 | | | 73.3 | | dBFS |
| | Fin = 80 MHz | | 72.4 | | | 72.4 | | |
| SINAD Signal to noise and distortion ratio, LVDS | Fin = 100 MHz | | 71.9 | | | 71.8 | | |
| | Fin = 170 MHz | 68 | 70.6 | | 68.7 | 70.9 | | |
| | Fin = 300 MHz | | 68 | | | 68.2 | | |
| ENOB Effective number of bits | Fin = 170 MHz | 11 | 11.4 | | 11.1 | 11.5 | | LSB |
| DNL Differential non-linearity | | -0.95 | ±0.4 | 2 | -0.95 | ±0.4 | 2 | LSB |
| INL Integrated non-linearity | | -5 | ±2 | 5 | -5 | ±2 | 5 | LSB |

ELECTRICAL CHARACTERISTICS – ADS6129 and ADS6128

Typical values are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, 50% clock duty cycle, -1dBFS differential analog input, internal reference mode unless otherwise noted.

Min and max values are across the full temperature range $T_{MIN} = -40^{\circ}C$ to $T_{MAX} = 85^{\circ}C$, AVDD = 3.3 V, DRVDD = 1.8 V

| PARAM | ETER | | 0S6129 0 MSPS | | | DS6128 0 MSP | | UNIT |
|---|---------------|------|------------------|-----|------|-----------------|-----|------|
| | | MIN | TYP | MAX | MIN | TYP | MAX | |
| | Fin = 20 MHz | | 70.7 | | | 70.9 | | |
| | Fin = 80 MHz | | 70.5 | | | 70.5 | | |
| SNR, Signal to noise ratio, LVDS | Fin = 100 MHz | | 70.1 | | | 70.1 | | dBFS |
| | Fin = 170 MHz | 67.5 | 69.5 | | 67.7 | 69.5 | | |
| | Fin = 300 MHz | | 67.8 | | | 67.9 | | |
| | Fin = 20 MHz | | 70.6 | | | 70.8 | | dBFS |
| | Fin = 80 MHz | | 70.4 | | | 70.4 | | |
| SINAD Signal to noise and distortion ratio, LVDS | Fin = 100 MHz | | 69.8 | | | 69.8 | | |
| | Fin = 170 MHz | 66.5 | 69.2 | | 66.7 | 69.3 | | |
| | Fin = 300 MHz | | 67.2 | | | 67.3 | | |
| ENOB , Effective number of bits | Fin = 170 MHz | 10.8 | 11.2 | | 10.8 | 11.2 | | LSB |
| DNL Differential non-linearity | | -0.5 | ±0.2 | 1 | -0.5 | ±0.2 | 1.0 | LSB |
| INL Integrated non-linearity | | -2.5 | ±1 | 2.5 | -2.5 | ±1 | 2.5 | LSB |

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

ELECTRICAL CHARACTERISTICS – ADS614x and ADS612x

Typical values are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, 50% clock duty cycle, -1dBFS differential analog input, internal reference mode unless otherwise noted.

Min and max values are across the full temperature range $T_{MIN} = -40$ °C to $T_{MAX} = 85$ °C, AVDD = 3.3 V, DRVDD = 1.8 V

| PA | RAMETER | ADS61 25 | 49/AD3 0 MSP3 | | | | | UNIT | |
|--|---|-------------|------------------|-----|---|---|-----|-----------------|--|
| | | MIN | TYP | MAX | MIN | TYP | MAX | | |
| | Fin = 20 MHz | | 92 | | | 92 | | | |
| | Fin = 80 MHz | | 86 | | | 82 | | | |
| SFDR Spurious Free Dynamic Range | Fin = 100 MHz | | 85 | | | 81 | | dBc | |
| opunous rice Dynamic Range | Fin = 170 MHz | 74 | 82 | | 74 | 83 | | | |
| | Fin = 300 MHz | | 76 | | | 92 82 81 | | | |
| | Fin = 10 MHz | | 89 | | | 88.5 | | | |
| | Fin = 20 MHz | | 83 | | | 80 | | | |
| THD Total Harmonic Distortion | Fin = 80 MHz | | 82 | | | 79 | | dBc | |
| AD HD Matal Harmonic Distortion D2, Accond Harmonic Distortion | Fin = 170 MHz | 71 | 79 | | 71 | 80 | | | |
| | Fin = 300 MHz | | 73 | | | 73 | | | |
| | Fin = 20 MHz | | 94 | | | 94 | | | |
| | Fin = 80 MHz | | 90 | | | 88 | | | |
| HD2, Second Harmonic Distortion | Fin = 100 MHz | | 88 | | | 88 | | dBc | |
| econd Harmonic Distortion Fin = 100 MHz Fin = 170 MHz Fin = 300 MHz Fin = 20 MHz | Fin = 170 MHz | 74 | 84 | | 74 | 84 | | | |
| | Fin = 300 MHz | | 76 | | 76 | | | | |
| | Fin = 20 MHz | | 93 | | 92 | | | | |
| | Fin = 80 MHz | | 86 | | | 82 | | dBc | |
| HD3 Third Harmonic Distortion | Fin = 100 MHz | | 85 | | | 81 | | | |
| | Fin = 170 MHz | 74 | 82 | | 74 | 83 | | | |
| | Fin = 300 MHz | | 76 | | 82 81 74 83 76 88.5 80 79 71 80 73 94 88 88 74 83 74 84 76 92 82 81 74 83 74 83 74 83 76 96 94 94 92 90 95 90 | | | | |
| | Fin = 20 MHz | | 96 | | | 96 | | | |
| | Fin = 80 MHz | | 94 | | | 94 | | | |
| | Fin = 100 MHz | | 94 | | | 94 | | dBc | |
| | Fin = 170 MHz | | 92 | | | 92 | | | |
| | Fin = 300 MHz | | 90 | | | TYP 92 82 81 4 83 76 88.5 80 79 1 80 73 94 88 88 4 81 4 83 84 84 84 84 84 83 84 84 84 84 84 84 84 84 84 83 76 96 94 92 94 92 90 92 90 95 90 1 | | | |
| IMD | F1 = 46 MHz, F2 = 50 MHz, Each tone at -7 dBFS | | 94 | | | 95 | | | |
| 2-Tone inter-modulation distortion | F1 = 185 MHz, F2 = 190 MHz, Each tone at -7 dBFS | | 90 | | | 90 | | dBFS | |
| Input overload recovery | Recovery to within 1% (of final value) for 6-dB overload with sine wave input | | 1 | | | 1 | | clock cycles | |
| PSRR AC power supply rejection ratio | For 100 mV _{PP} signal on AVDD supply | | 25 | | | 25 | | dB | |



SLWS211B-JULY 2008-REVISED OCTOBER 2008

www.ti.com

DIGITAL CHARACTERISTICS – ADS614x and ADS612x

The DC specifications refer to the condition where the digital outputs are not switching, but are permanently at a valid logic level 0 or 1. AVDD = 3.3 V, DRVDD = 1.8 V

| PARAM | ETER | TEST CONDITIONS | ADS6149/ADS61 ADS6129/ADS6 ² | | | UNIT |
|---------------------------------------|----------------------------|---|--|-------|------|------|
| | | | MIN | TYP | MAX | |
| DIGITAL INPUTS - RES | SET, SCLK, SDATA, | SEN ⁽¹⁾ | | | | |
| High-level input voltage | | All digital inputs support 1.8V and 3.3V CMOS logic 1.3 | | 1.3 | | V |
| Low-level input voltage | | levels | | | 0.4 | V |
| | SDATA, SCLK ⁽²⁾ | VHIGH = 3.3V | 16 | | | |
| High-level input current | SEN ⁽³⁾ | VHIGH = 3.3V | | 10 | | μA |
| Low-level input current | SDATA, SCLK | VLOW = 0V | 0 -20 | | | |
| Low-level input current | SEN | VLOW = 0V | | | | μA |
| Input capacitance | | | | 4 | | pF |
| DIGITAL OUTPUTS - C | MOS INTERFACE (F | ins D0 to D13 and OVR_SDOUT) | | | | |
| High-level output voltage | 9 | | I | DRVDD | | V |
| Low-level output voltage | | | | 0 | | V |
| Output capacitance (inte | ernal to device) | | | 2 | | pF |
| DIGITAL OUTPUTS – L | VDS INTERFACE (P | ns D0_D1_P/M to D12_D13_P/M) ⁽⁴⁾ | | | | |
| V _{ODH} , High-level output | voltage ⁽⁵⁾ | | 275 | 350 | 425 | mV |
| V _{ODL} , Low-level output v | oltage ⁽⁵⁾ | | -425 | -350 | -275 | mV |
| V _{OCM} , Output common-r | node voltage | | 1 1.2 1.3 | | V | |
| Output capacitance | | Capacitance inside the device, from either output to ground | | 2 | | pF |

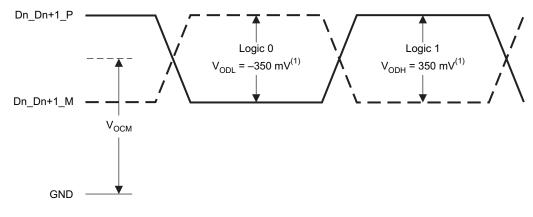
(1) SCLK, SDATA, SEN function as digital input pins in serial configuration mode.

(2) SDATA, SCLK have internal 200 k Ω pull-down resistor

(3) SEN has internal 100 kΩ pull-up resistor to AVDD. Since the pull-up is weak, SEN can also be driven by 1.8V or 3.3V CMOS buffers.

(4) OVR_SDOUT has CMOS output logic levels, determined by DRVDD voltage.

(5) With external 100 Ω termination



T0399-01

Figure 1. LVDS Voltage Levels

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

TIMING REQUIREMENTS – LVDS AND CMOS MODES⁽¹⁾

Typical values are at 25°C, AVDD = 3.3V, DRVDD = 1.8V, sampling frequency = 250 MSPS, sine wave input clock, $C_{LOAD} = 5pF^{(2)}$, $R_{LOAD} = 100\Omega^{(3)}$, LOW SPEED mode disabled, unless otherwise noted.

Min and max values are across the full temperature range $T_{MIN} = -40^{\circ}C$ to $T_{MAX} = 85^{\circ}C$, AVDD = 3.3V, DRVDD = 1.7V to 1.9V.

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT | | |
|--|---|--|-------|------------------------------------|------|------------------------------|--|----|
| ta | Aperture delay | The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs | 0.7 | 1.2 | 1.7 | ns | | |
| tj | Aperture jitter | | | 170 | | fs rms | | |
| | | Time to valid data after coming out of STANDBY mode | | 0.3 | 1 | | | |
| | Wake-up time | Time to valid data after coming out of PDN GLOBAL mode | | 25 | 100 | μs | | |
| | | Time to valid data after stopping and restarting the input clock | | 10 | | clock cycles | | |
| | ADC Latency ⁽⁴⁾ | Default, after reset | | 18 | | clock cycles | | |
| DDR LVD | S MODE ⁽⁵⁾ | | | | | | | |
| t _{su} | Data setup time | Data valid ⁽⁶⁾ to zero-crossing of CLKOUTP | 0.8 | 1.2 | | ns | | |
| t _h | Data hold time | Zero-crossing of CLKOUT to data becoming invalid ⁽⁶⁾ | 0.25 | 0.6 | | ns | | |
| t _{PDI} | Clock propagation delay | Input clock rising edge cross-over to output clock rising edge cross-over | 0.2 > | $0.2 \times t_s + t_{dela}$ | | $0.2 \times t_s + t_{delay}$ | | ns |
| | t _{delay} | 100 MSPS ≤ Sampling frequency ≤ 250 MSPS | 5.0 | 6.2 | 7.5 | ns | | |
| | LVDS bit clock duty cycle | Duty cycle of differential clock, (CLKOUTP–CLKOUTM) 100 MSPS ≤ Sampling frequency ≤ 250 MSPS | 52% | | | | | |
| t _{RISE} , t _{FALL} | Data rise time, Data fall time | Rise time measured from −100 mV to 100 mV Fall time measured from 100 mV to −100 mV 1 MSPS ≤ Sampling frequency ≤ 250 MSPS | 0.08 | 0.14 | 0.2 | ns | | |
| t _{CLKRISE} , t _{CLKFALL} | Output clock rise time, Output clock fall time | Rise time measured from –100 mV to 100 mV Fall time measured from 100 mV to –100 mV 1 MSPS ≤ Sampling frequency ≤ 250 MSPS | 0.08 | 0.14 | 0.2 | ns | | |
| t _{OE} | Output enable (OE) to data delay | Time to valid data after OE becomes active | | 40 | | ns | | |
| PARALLE | EL CMOS MODE ⁽⁷⁾ | · | L | | | | | |
| t _{START} | Input clock to data delay | Input clock rising edge cross-over to start of data valid ⁽⁸⁾ | | | 3.2 | ns | | |
| t _{DV} | Data valid time | Time interval of valid data ⁽⁸⁾ | 0.7 | 1.5 | | ns | | |
| t _{PDI} | Clock propagation delay | Input clock rising edge cross-over to output clock rising edge cross-over | 0.78 | × t _s + t _{de} | elay | | | |
| | t _{delay} | 100 MSPS ≤ Sampling frequency ≤ 150 MSPS | 5 | 6.5 | 8 | ns | | |
| | Output clock duty cycle | Duty cycle of differential clock, (CLKOUT) 100 MSPS ≤ Sampling frequency ≤ 150 MSPS | | 50% | | | | |
| t _{RISE} , t _{FALL} | Data rise time, Data fall time | Rise time measured from 20% to 80% of DRVDD, Fall time measured from 80% to 20% of DRVDD, 1 MSPS ≤ Sampling frequency ≤ 250 MSPS | 0.7 | 1.2 | 2 | ns | | |
| t _{CLKRISE} , t _{CLKFALL} | Output clock rise time, Output clock fall time | Rise time measured from 20% to 80% of DRVDD, Fall time measured from 80% to 20% of DRVDD, 1 MSPS ≤ Sampling frequency ≤ 150 MSPS | 0.5 | 1 | 1.5 | ns | | |
| t _{OE} | Output enable (OE) to data delay | Time to valid data after OE becomes active | | 20 | | ns | | |

(1) Timing parameters are specified by design and characterization and not tested in production.

(2) C_{LOAD} is the effective external single-ended load capacitance between each output pin and ground

R_{LOAD} is the differential load resistance between the LVDS output pair.

(4) At higher frequencies, t_{PDI} is greater than one clock period and overall latency = ADC latency + 1.

(5) Measurements are done with a transmission line of 100Ω characteristic impedance between the device and the load. Setup and hold time specifications take into account the effect of jitter on the output data and clock.

(6) Data valid refers to LOGIC HIGH of +100mV and LOGIC LOW of -100mV.

(7) For Fs> 150 MSPS, it is recommended to use external clock for data capture and NOT the device output clock signal (CLKOUT).

(8) Data valid refers to LOGIC HIGH of 1.26V and LOGIC LOW of 0.54V.



ADS6149/ADS6129 ADS6148/ADS6128

SLWS211B-JULY 2008-REVISED OCTOBER 2008

| | S | SETUP TIME | , ns | HOLD TIME, ns | | ns |
|--|-----|------------|------|---------------|-------------------------|-----|
| SAMPLING FREQUENCY, MSPS | MIN | TYP | MAX | MIN | TYP | MAX |
| 210 | 1.0 | 1.4 | | 0.4 | 0.8 | |
| 190 | 1.1 | 1.5 | | 0.5 | 0.9 | |
| 170 | 1.3 | 1.7 | | 0.7 | 1.1 | |
| 150 | 1.6 | 1.9 | | 0.9 | 1.2 | |
| 125 | 1.9 | 2.2 | | 1.1 | 1.4 | |
| <100 Enable LOW SPEED mode | 2.5 | | | 2.0 | | |
| 4.45.4400 | | | | | t_{PDI} , ns $^{(1)}$ | |
| 1 ≤ Fs ≤ 100, Enable LOW SPEED mode | | | | MIN | TYP | MAX |
| | | | | | 8.2 | |

LVDS Timings at Lower Sampling Frequencies

(1) Ts = 1/Sampling frequency

CMOS Timings at Lower Sampling Frequencies

| | Timings specified with respect to input clock | | | | | | | |
|---------------------------------------|---|-------------------------|----------------|--------------|--------------------------------------|--------|--|--|
| SAMPLING FREQUENCY, MSPS | | t _{START} , ns | | DATA | A VALID TIM | IE, ns | | |
| | MIN | TYP | MAX | MIN | TYP | MAX | | |
| 210 | | | 1.7 | 1.6 | 2.4 | | | |
| 190 | | | 0.4 | 2.2 | 3.0 | | | |
| 170 | | | 5.1 | 2.4 | 3.6 | | | |
| 150 | | | 4.8 | 3.0 | 4.3 | | | |
| | | Timings s | specified with | n respect to | respect to CLKOUT | | | |
| SAMPLING FREQUENCY, MSPS | S | ETUP TIME, | ns | Н | ns | | | |
| | MIN | TYP | MAX | MIN | TYP | MAX | | |
| 150 | 2.0 | 3.2 | | 1.5 | 2.2 | | | |
| 125 | 2.9 | 4 | | 2.2 | 2.7 | | | |
| <100 Enable LOW SPEED mode | 5.0 | | | 3.8 | | | | |
| | | 1 | 1 | | t _{PDI} , ns ⁽¹⁾ | 1 | | |
| 1 ≤ Fs ≤ 100 Enable LOW SPEED mode | | | | MIN | TYP | MAX | | |
| | | | | | 14 | | | |

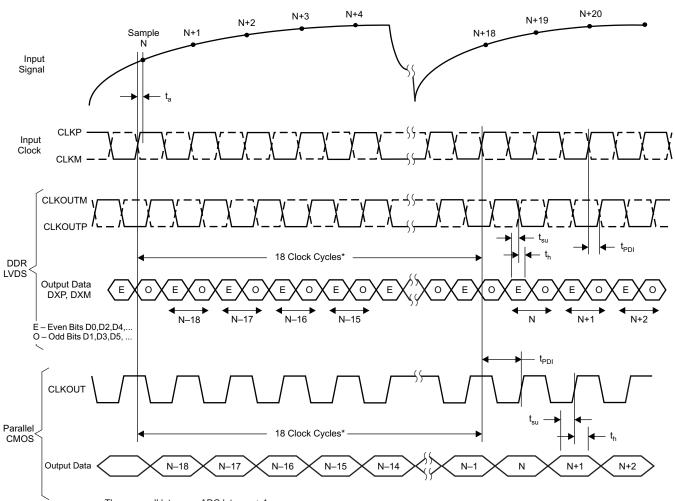
(1) Ts = 1/Sampling frequency

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

T0105-09

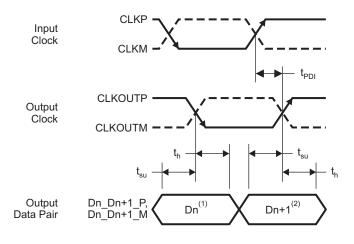


Then, overall latency = ADC latency + 1. ADC latency is 14 clock cycles in low-latency mode.

Figure 2. Latency Diagram

Copyright © 2008, Texas Instruments Incorporated

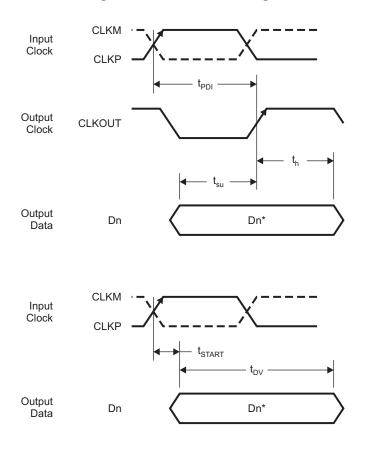




 $^{(1)}$ Dn – Bits D0, D2, D4,... $^{(2)}$ Dn+1 – Bits D1, D3, D5, ...

T0106-07





*Dn – Bits D0, D1, D2, ...

T0107-05





DEVICE CONFIGURATION

ADS614X/2X can be configured independently using either parallel interface control or serial interface programming.

PARALLEL CONFIGURATION ONLY

To put the device in parallel configuration mode, keep RESET tied to HIGH (DRVDD).

Now, pins DFS, MODE, SEN and SDATA can be used to directly control certain modes of the ADC. The device can be easily configured by connecting the parallel pins to the correct voltage levels (as described in Table 3 to Table 6. There is no need to apply reset.

In this mode, SEN and SDATA function as parallel interface control pins. Frequently used functions can be controlled in this mode – standby, selection between LVDS/CMOS output format, internal/external reference, two's complement/straight binary output format and position of the output clock edge.

Table 1 briefly describes the modes controlled by the parallel pins.

| PIN | TYPE OF CONTROL | CONTROLS MODES |
|---------------------|--------------------|--|
| DFS | Analog | Data format and LVDS/CMOS output interface. |
| MODE ⁽¹⁾ | Analog | Internal or external reference, low speed mode enable |
| SEN | Analog | CLKOUT edge programmability. |
| SDATA | Digital | Global power-down (ADC, internal references and output buffers are powered down) |

 Table 1. Parallel Pin Functions

(1) In the next generation pin-compatible ADC family, MODE will be converted to a digital control pin for certain reserved functions. So, the selection of internal or external reference and low speed functions will not be supported using MODE. In the system board using ADS61x9/x8, the MODE pin can be routed to a digital controller. This will avoid board modification while migrating to the next generation ADC.

SERIAL INTERFACE CONFIGURATION ONLY

To exercise this mode, first the serial registers have to be reset to their default values and RESET pin has to be kept LOW.

SEN, SDATA and SCLK function as serial interface pins in this mode and can be used to access the internal registers of the ADC.

The registers can be reset either by applying a pulse on RESET pin or by setting HIGH the **<RESET>** bit (D7 in register 0x00). The serial interface section describes the register programming and register reset in more detail.

Since the parallel pins DFS and MODE are not to be used in this mode, they have to be tied to ground.



CONFIGURATION USING BOTH THE SERIAL INTERFACE AND PARALLEL CONTROLS

For increased flexibility, an additional configuration mode is supported wherein a combination of serial interface registers and parallel pin controls (DFS, MODE) can be used to configure the device.

To exercise this mode, the serial registers have to be reset to their default values and RESET pin has to be kept LOW.

SEN, SDATA and SCLK function as serial interface pins in this mode and can be used to access the internal registers of ADC. The registers can be reset either by applying a pulse on RESET pin or by setting HIGH the <RESET> bit (D7 in register 0x00). The serial interface section describes the register programming and register reset in more detail.

The parallel interface control pins DFS and MODE can be used and their function is determined by the appropriate voltage levels as described in Table 3. The voltage levels can be easily derived, by using a resistor string as illustrated with an example as shown in Figure 5.

Since some functions can be controlled using both the parallel pins and serial registers, the priority between the two is determined by a Priority Table as shown in Table 2.

Table 2. Priority Between Parallel Pins and Serial Registers

| FUNCTION | PRIORITY |
|----------------------------------|---|
| Internal/External reference | MODE pin controls this selection ONLY if the register bits <ref></ref> = 00, otherwise <ref></ref> controls the selection |
| Data format selection | DFS pin controls this selection ONLY if the register bits <data format=""></data> = 00, otherwise <data< b=""> FORMAT> controls the selection</data<> |
| LVDS or CMOS interface selection | DFS pin controls this selection ONLY if the register bits <lvds cmos=""></lvds> = 00, otherwise <lvds< b=""> CMOS> controls the selection</lvds<> |

DESCRIPTION OF PARALLEL PINS

Table 3. SDATA – DIGITAL CONTROL PIN

| SDATA | DESCRIPTION |
|-------|--|
| 0 | Normal operation (default) |
| AVDD | Global power-down. ADC, internal references and the output buffers are powered down. |

Table 4. SEN – ANALOG CONTROL PIN⁽¹⁾

| SEN | DESCRIPTION – Output Clock Edge Programmability |
|-----------|--|
| 0 | LVDS: Data and output clock transitions are aligned CMOS: Setup time increases by (6xTs/26), Hold time reduces by (6xTs/26) |
| (3/8)AVDD | LVDS: Setup time decreases by (4xTs/26), Hold time increases by (4xTs/26) CMOS: Setup time increases by (9xTs/26), Hold time reduces by (9xTs/26) |
| (5/8)AVDD | LVDS: Setup time increases by (4xTs/26), Hold time reduces by (4xTs/26) CMOS : Setup time increases by (3xTs/26), Hold time reduces by (3xTs/26) |
| AVDD | Default output clock position (Setup/hold timings of output data with respect to this clock position is specified in the timing characteristics table). |

(1) Ts = 1/Sampling frequency

Table 5. DFS – ANALOG CONTROL PIN

| DFS | DESCRIPTION | | | | |
|-----------|---|--|--|--|--|
| 0 | 2s complement data and DDR LVDS output | | | | |
| (3/8)AVDD | 2s complement data and parallel CMOS output | | | | |
| (5/8)AVDD | Offset binary data and parallel CMOS output | | | | |
| AVDD | Offset binary data and DDR LVDS output | | | | |

Texas Instruments

www.ti.com

| MODE | DESCRIPTION |
|-----------|---|
| 0 | Internal reference, LOW SPEED mode disabled (for Fs > 100 MSPS) |
| (3/8)AVDD | External reference, LOW SPEED mode disabled (for Fs > 100 MSPS) |
| (5/8)AVDD | External reference, LOW SPEED mode enabled (for Fs ≤ 100 MSPS) |
| AVDD | Internal reference, LOW SPEED mode enabled (for Fs ≤ 100 MSPS) |



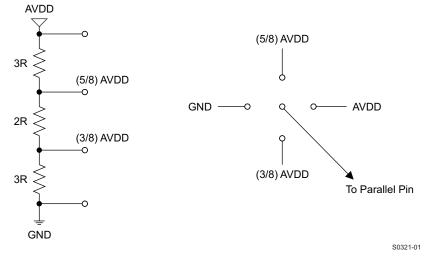


Figure 5. Simple Scheme to Configure Parallel Pins SEN and SCLK

SERIAL INTERFACE

The ADC has a set of internal registers, which can be accessed by the serial interface formed by pins SEN (Serial interface Enable), SCLK (Serial Interface Clock) and SDATA (Serial Interface Data).

Serial shift of bits into the device is enabled when SEN is low. Serial data SDATA is latched at every falling edge of SCLK when SEN is active (low). The serial data is loaded into the register at every 16th SCLK falling edge when SEN is low. In case the word length exceeds a multiple of 16 bits, the excess bits are ignored. Data can be loaded in multiple of 16-bit words within a single active SEN pulse.

The first 8 bits form the register address and the remaining 8 bits are the register data. The interface can work with SCLK frequency from 20 MHz down to low speeds (few Hertz) and also with non-50% SCLK duty cycle.

Register Initialization

After power-up, the internal registers MUST be initialized to their default values. This can be done in one of two ways:

1. Either through hardware reset by applying a high-going pulse on RESET pin (of width greater than 10ns) as shown in Figure 6.

OR

 By applying software reset. Using the serial interface, set the <RESET> bit (D7 in register 0x00) to HIGH. This initializes internal registers to their default values and then self-resets the <RESET> bit to LOW. In this case the RESET pin is kept LOW.



ADS6149/ADS6129 ADS6148/ADS6128

SLWS211B-JULY 2008-REVISED OCTOBER 2008

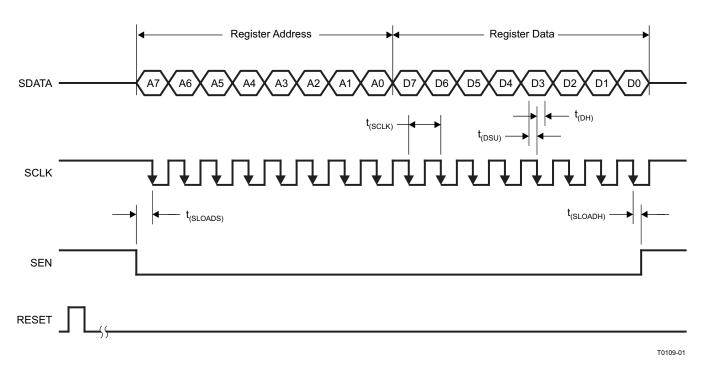


Figure 6. Serial Interface Timing

SERIAL INTERFACE TIMING CHARACTERISTICS

Typical values at 25°C, min and max values across the full temperature range $T_{MIN} = -40^{\circ}C$ to $T_{MAX} = 85^{\circ}C$, AVDD = 3.3V, DRVDD = 1.8V, unless otherwise noted.

| | PARAMETER | MIN | TYP | MAX | UNIT |
|---------------------|-----------------------------|------|-----|-----|------|
| f _{SCLK} | SCLK frequency (= 1/ tSCLK) | > DC | | 20 | MHz |
| t _{SLOADS} | SEN to SCLK setup time | 25 | | | ns |
| t _{SLOADH} | SCLK to SEN hold time | 25 | | | ns |
| t _{DS} | SDATA setup time | 25 | | | ns |
| t _{DH} | SDATA hold time | 25 | | | ns |

SERIAL REGISTER READOUT

The device includes an option where the contents of the internal registers can be read back. This may be useful as a diagnostic check to verify the serial interface communication between the external controller and the ADC.

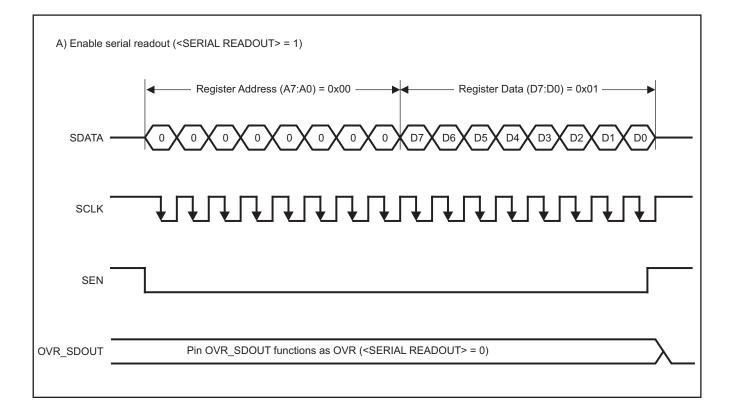
- a. First, set register bit <SERIAL READOUT> = 1. This also disables any further writes into the registers (EXCEPT register bit <SERIAL READOUT> itself).
- b. Initiate a serial interface cycle specifying the address of the register (A7-A0) whose content has to be read.
- c. The device outputs the contents (D7-D0) of the selected register on OVR_SDOUT pin.
- d. The external controller can latch the contents at the falling edge of SCLK.
- e. To enable register writes, reset register bit <SERIAL READOUT> = 0.

Submit Documentation Feedback 17

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com



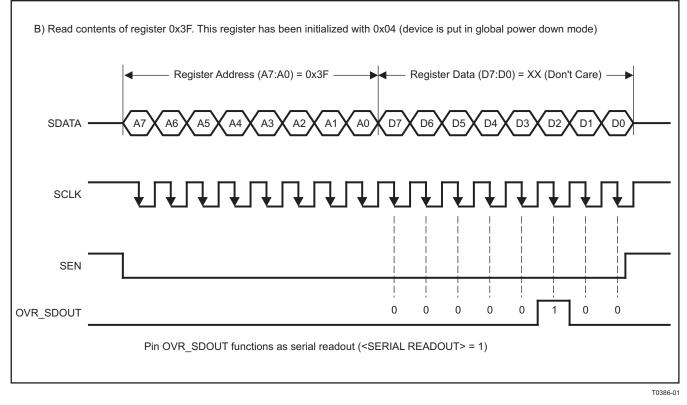


Figure 7. Serial Readout



RESET TIMING

Typical values at 25°C, min and max values across the full temperature range $T_{MIN} = -40$ °C to $T_{MAX} = 85$ °C, unless otherwise noted.

| | PARAMETER | ARAMETER TEST CONDITIONS | | | | UNIT |
|----------------|---------------------|---|-----|---|---|------|
| t ₁ | Power-on delay | Delay from power-up of AVDD and DRVDD to RESET pulse active | | 1 | | ms |
| | t Depet mules width | Dulas width of active DECET simplified will react the partial registers | | | | ns |
| ¹ 2 | Reset pulse width | Pulse width of active RESET signal that will reset the serial registers | | | 1 | μs |
| t ₃ | | Delay from RESET disable to SEN active | 100 | | | ns |

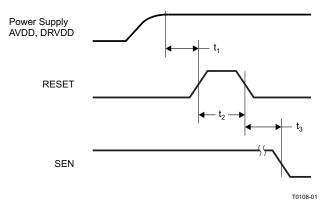


Figure 8. Reset Timing Diagram

SERIAL REGISTER MAP

| REGISTER ADDRESS | | REG | ISTE | R FUN | | NS | | |
|------------------|--|--|-------|-------|-----------------------------|---|---------------------------|------------------------------------|
| A7-A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| 00 | <reset> Software Reset</reset> | 0 | 0 | 0 | 0 | 0 | 0 | <serial READOUT></serial |
| 20 | 0 | 0 | 0 | 0 | 0 | <enable LOW SPEED MODE></enable | 0 | 0 |
| 3F | 0 | 9 | 0 | 0 | <pdn GLOBAL></pdn | <standby></standby> | <pdn OBUF></pdn | |
| 41 | | 0 | 0 | 0 | 0 | 0 | 0 | |
| 44 | | CLKOUT POSI Output clock position | | ol | | | 0 | 0 |
| 50 | 0 | 0 | 0 | 0 | 0 | <pre>>DATA FG 2s compleme bina</pre> | ent or offset | 0 |
| 51 | | <cus< td=""><td>TOM I</td><td>PATT</td><td>ERN L</td><td>-OW></td><td></td><td></td></cus<> | TOM I | PATT | ERN L | -OW> | | |
| 52 | 0 | 0 | | | | CUSTOM PATT | FERN HIGH> | |
| 53 | 0 | ENABLE OFFSET CORR> | 0 | 0 | 0 | 0 0 | | 0 |
| 55 | | | | | | RR TIME CONS | | |
| 62 | 0 | 0 | 0 | 0 | 0 | TE | ST PATTERNS | 5> |
| 63 | 0 0 PROGRAM OFFSET PEDESTAL > | | | | | | > | |

(1) Multiple functions in a register can be programmed in a single write operation.

TEXAS INSTRUMENTS

www.ti.com

DESCRIPTION OF SERIAL REGISTERS

A)

| A7–A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|------------------------------------|----|----|----|----|----|----|---|
| 00 | <reset> Software Reset</reset> | 0 | 0 | 0 | 0 | 0 | 0 | <seria L READO UT></seria |

D7 <RESET>

1 Software reset applied – resets all internal registers and self-clears to 0.

D0 <SERIAL READOUT>

0 Serial readout disabled

1 Serial readout enabled, Pin OVR_SDOUT functions as serial data readout.

A)

| A7–A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|----|----|----|----|----|---|----|----|
| 20 | 0 | 0 | 0 | 0 | 0 | <enable LOW SPEED MODE></enable | 0 | 0 |

D2 <ENABLE LOW SPEED MODE>

0 LOW SPEED mode disabled. Use for sampling frequency > 100 MSPS

1 Enable LOW SPEED mode for sampling frequencies ≤ 100 MSPS.

B)

| A7-A0 IN HEX | D7 | D6 D5 | | D4 | D3 | D2 | D1 | D0 |
|--------------|----|--|-----|----|----|-----------------------------|---------------------|---------------------------|
| 3F | 0 | <ri< td=""><th>EF></th><td>0</td><td>0</td><td><pdn GLOBAL></pdn </td><td><standby></standby></td><td><pdn OBUF></pdn </td></ri<> | EF> | 0 | 0 | <pdn GLOBAL></pdn | <standby></standby> | <pdn OBUF></pdn |

D0 <PDN OBUF> Power down output buffer

- 0 Output buffer enabled
- 1 Output buffer powered down

D1 <STANDBY>

0 Normal operation

1 ADC alone powered down. Internal references, output buffers are active. Quick wake-up time

D2 <PDN GLOBAL>

- 0 Normal operation
- 1 Total power down ADC, internal references and output buffers are powered down. Slow wake-up time.

D6,D5 <REF> Internal or external reference selection

- 00 MODE pin controls reference selection
- 01 Internal reference enabled
- 11 External reference enabled

C)

| A7-A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|--|------|----|----|----|----|----|----|
| 41 | <lvds ci<="" td=""><th>MOS></th><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></lvds> | MOS> | 0 | 0 | 0 | 0 | 0 | 0 |

D7,D6 <LVDS CMOS>

- 00 DFS pin controls LVDS or CMOS interface selection
- 10 DDR LVDS interface
- 11 Parallel CMOS interface



SLWS211B-JULY 2008-REVISED OCTOBER 2008

D)

www.ti.com

| A7–A0 II | N HEX | D7 | D6 | | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|--|---------------|--|-------------|--------------|-------------|-------------------------|------------|-----------------------|----|
| 44 | | | <cl< td=""><td>KOUT P</td><td>OSN> Out</td><td>put clock</td><td>position control</td><td></td><td>0</td><td>0</td></cl<> | KOUT P | OSN> Out | put clock | position control | | 0 | 0 |
| VDS Interfac | e | | | | | | | | | |
| D7-D5 | <clkout i<="" td=""><td>POSN> Out</td><td>tput clock</td><td>c rising e</td><td>edge posit</td><td>ion</td><td></td><td></td><td></td><td></td></clkout> | POSN> Out | tput clock | c rising e | edge posit | ion | | | | |
| 000 | Default outp | out clock po | sition (refe | er to timir | ng specifica | ation table | ·) | | | |
| 100 | Default outp | out clock pos | sition (refe | er to timir | ng specifica | ation table |) | | | |
| 101 | Rising edge | shifted by · | + (4/26)Ts | 6 | | | | | | |
| 110 | Rising edge | aligned wit | h data tra | nsition | | | | | | |
| 111 | Rising edge | shifted by · | - (4/26)Ts | | | | | | | |
| D4-D2 | <clkout i<="" td=""><td>POSN> Out</td><td>tput clock</td><td>c falling o</td><td>edge posi</td><td>tion</td><td></td><td></td><td></td><td></td></clkout> | POSN> Out | tput clock | c falling o | edge posi | tion | | | | |
| 000 | Default outp | out clock pos | sition (refe | er to timir | ng specifica | ation table |) | | | |
| 100 | Default outp | out clock po | sition (refe | er to timir | ng specifica | ation table |) | | | |
| 101 | Falling edge | shifted by | + (4/26)Ts | S | | | | | | |
| 110 | Falling edge | aligned wi | th data tra | nsition | | | | | | |
| 111 | Falling edge | shifted by | - (4/26)Ts | ; | | | | | | |
| CMOS Interfa | ce | | | | | | | | | |
| D7-D5 | <clkout i<="" td=""><td>POSN> Out</td><td>tput clock</td><td>c rising e</td><td>edge posit</td><td>ion</td><td></td><td></td><td></td><td></td></clkout> | POSN> Out | tput clock | c rising e | edge posit | ion | | | | |
| 000 | Default outp | out clock po | sition (refe | er to timir | ng specifica | ation table | ·) | | | |
| 100 | Default outp | out clock pos | sition (refe | er to timir | ng specifica | ation table |) | | | |
| 101 | Rising edge | shifted by · | + (4/26)Ts | 6 | | | | | | |
| 110 | Rising edge | shifted by · | + (6/26)Ts | 6 | | | | | | |
| 111 | Rising edge | aligned wit | h data tra | nsition | | | | | | |
| D4-D2 | <clkout i<="" td=""><td>POSN> Out</td><td>tput clock</td><td>c falling o</td><td>edge posi</td><td>tion</td><td></td><td></td><td></td><td></td></clkout> | POSN> Out | tput clock | c falling o | edge posi | tion | | | | |
| 000 | Default outp | out clock pos | sition (refe | er to timir | ng specifica | ation table |) | | | |
| 100 | Default outp | out clock pos | sition (refe | er to timir | ng specifica | ation table |) | | | |
| 101 | Falling edge | shifted by | + (4/26)Ts | S | | | | | | |
| 110 | Falling edge | shifted by | + (6/26)Ts | S | | | | | | |
| 111 | Falling edge | aligned wi | th data tra | Insition | | | | | | |
| _ = 1/Sam | pling Frequ | ency | | | | | | | | |
| E) | 0 1 | | | | | | | | | |
| - | IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | | D1 | DO |
| | 50 | 0 | 0 | 0 | 0 | 0 | <data format=""></data> | 2s complom | ant ar offerst hinary | 0 |

00 DFS pin controls data format selection

- 10 2's complement
- 11 Offset binary

F)

| A7–A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|----|------------------------------|----|----|---|----------|----|----|
| 51 | | <custom pattern=""></custom> | | | | | | |
| 52 | 0 | 0 | | | <custom< th=""><td>Pattern></td><td></td><td></td></custom<> | Pattern> | | |

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

D7–D0 <CUSTOM LOW>

8 lower bits of custom pattern available at the output instead of ADC data.

D5–D0 <CUSTOM HIGH>

6 upper bits of custom pattern available at the output instead of ADC data

G)

| A7–A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|----|--|----|----|----|----|----|----|
| 53 | 0 | <enable corr="" offset=""> Offset correction enable</enable> | 0 | 0 | 0 | 0 | 0 | 0 |

D6 <ENABLE OFFSET CORR>

0 Offset correction disabled

1 Offset correction enabled

| ۵7. | -A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
|--------------|--|--------------|--|---------------|---------------|---|----------------|---------------|-----------|--|
| | | | | | | <pre><offset corr="" tc=""> Offset correction time</offset></pre> | | | | |
| | 55 | | <fine< th=""><th>GAIN></th><th></th><th></th><th></th><th>stant</th><th></th></fine<> | GAIN> | | | | stant | | |
| D3D0 | <offset corr="" tc=""> section.</offset> | Time consta | ant of correcti | on loop in nu | umber of cloc | k cycles. See | e "Offset Corr | ection" in ap | plication | |
| 0000 | 256 k | | | | | | | | | |
| 0001 | 512 k | | | | | | | | | |
| 0010 | 1 M | | | | | | | | | |
| 0011 | 2 M | | | | | | | | | |
| 0100 | 4 M | | | | | | | | | |
| 0101 | 8 M | | | | | | | | | |
| 0110 | 16 M | | | | | | | | | |
| 0111 | 32 M | | | | | | | | | |
| 1000 | 64 M | | | | | | | | | |
| 1001 | 128 M | | | | | | | | | |
| 1010 | 256 M | | | | | | | | | |
| 1011 | 512 M | | | | | | | | | |
| 1100 to 1111 | RESERVED | | | | | | | | | |
| D7–D4 | <fine gain=""> Gain pr</fine> | ogrammabilit | y in 0.5 dB st | teps | | | | | | |
| 0000 | 0 dB gain, default afte | er reset | | | | | | | | |
| 0001 | 0.5 dB gain | | | | | | | | | |
| 0010 | 1.0 dB gain | | | | | | | | | |
| 0011 | 1.5 dB gain | | | | | | | | | |
| 0100 | 2.0 dB gain | | | | | | | | | |
| 0101 | 2.5 dB gain | | | | | | | | | |
| 0110 | 3.0 dB gain | | | | | | | | | |
| 0111 | 3.5 dB gain | | | | | | | | | |
| 1000 | 4.0 dB gain | | | | | | | | | |
| 1001 | 4.5 dB gain | | | | | | | | | |
| 1010 | 5.0 dB gain | | | | | | | | | |
| 1011 | 5.5 dB gain | | | | | | | | | |
| 1100 | 6.0 dB gain | | | | | | | | | |



SLWS211B-JULY 2008-REVISED OCTOBER 2008

| A | 7–A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------|--|-----------------------|---------------|----------------|---------------------------|---------------|--|---------------|-----|
| | 62 | 0 | 0 | 0 | 0 | 0 | <te< th=""><th>ST PATTER</th><th>NS></th></te<> | ST PATTER | NS> |
| D2-D0 | <test patterns=""></test> | Test Patterns | to verify dat | a capture | | | | | |
| 000 | Normal operation | | | | | | | | |
| 001 | Outputs all zeros | | | | | | | | |
| 010 | Outputs all ones | | | | | | | | |
| 011 | 11 Outputs toggle pattern | | | | | | | | |
| | ADS6149/8: Output da | ata <d13:d0></d13:d0> | alternates b | etween 1010 | 1010101010 | and 0101010 | 01010101 ev | ery clock cyc | e. |
| | ADS6129/8: Output da | ata <d11:d0></d11:d0> | alternates b | etween 1010 | 10101010 ar | nd 010101010 | 0101 every cl | ock cycle. | |
| | Outputs digital ramp | | | | | | | | |
| 100 | | | | 3 (14-hit) ava | ry clock cycle | e from code C |) to code 163 | 83 | |
| 100 | ADS6149/8: Output da | ata increment | S by one LSt | | ly block by blo | | | | |
| 100 | ADS6149/8: Output da ADS6129/8: Output da | | | ``` | | cycle from co | ode 0 to code | 4095 | |
| 100 | • | ata increment | s by one LSE | 3 (124-bit) ev | ery 4 th clock | cycle from co | ode 0 to code | 4095 | |
| | ADS6129/8: Output da | ata increment | s by one LSE | 3 (124-bit) ev | ery 4 th clock | cycle from co | ode 0 to code | 4095 | |

J)

| A7–A0 IN HEX | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|----|----|----|----|--|-----------|----|----|
| 63 | | | | | <offset f<="" th=""><th>PEDESTAL></th><th></th><th></th></offset> | PEDESTAL> | | |

D5-D0 **CFFSET PEDESTAL>** When the offset correction is enabled, the final converged value after the offset is corrected will be the ADC mid-code value.

A pedestal can be added to the final converged value by programming these bits. For example, See "Offset Correction" in application section.

- 011111 Mid-code + 31 LSB
- 011110 Mid-code + 30 LSB
- 011101 Mid-code + 29 LSB

| 000000 | Mid-code |
|--------|------------------|
| 111111 | Mid-code - 1 LSB |

- 111110 Mid-code 2 LSB
- 100000

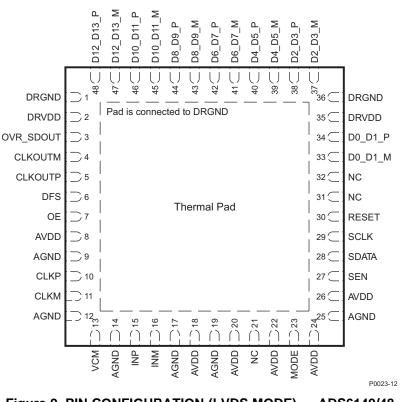
Mid-code - 32 LSB

ADS6148/ADS6128 SLWS211B-JULY 2008-REVISED OCTOBER 2008

ADS6149/ADS6129



www.ti.com



DEVICE INFORMATION

Figure 9. PIN CONFIGURATION (LVDS MODE) — ADS6149/48

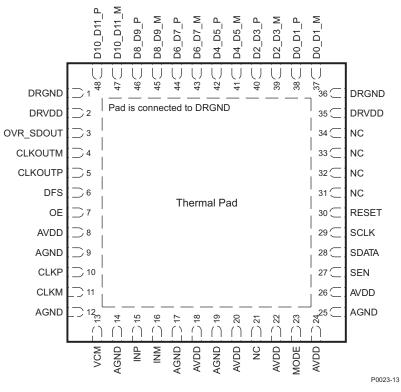


Figure 10. PIN CONFIGURATION (LVDS MODE) — ADS6129/28



Table 8. PIN ASSIGNMENTS (LVDS MODE) — ADS6149/48 and ADS6129/28

| PI | 1 | | NO. | | | | | | |
|---------------------|--------------------------|-----|------------|---|--|--|--|--|--|
| NAME | NO. | I/O | of PINS | DESCRIPTION | | | | | |
| AVDD | 8, 18, 20, 22, 24, 26 | I | 6 | 3.3-V Analog power supply | | | | | |
| AGND | 9, 12, 14, 17, 19, 25 | I | 6 | Analog ground | | | | | |
| CLKP, CLKM | 10, 11 | I | 2 | Differential clock input | | | | | |
| INP, INM | 15, 16 | Т | 2 | Differential analog input | | | | | |
| | | | | Internal reference mode – Common-mode voltage output. | | | | | |
| VCM | 13 | Ю | 1 | External reference mode – Reference input. The voltage forced on this pin sets the internal references | | | | | |
| | | | | Serial interface RESET input. | | | | | |
| RESET | 30 | I | 1 | When using the serial interface mode, the user MUST initialize internal registers through hardware RESET by applying a high-going pulse on this pin or by using software reset option. Refer to <i>SERIAL INTERFACE</i> section. | | | | | |
| | | | | In parallel interface mode, the user has to tie RESET pin permanently HIGH. (SDATA and SEN are used as parallel pin controls in this mode) | | | | | |
| | | | | The pin has an internal 100 k Ω pull-down resistor. | | | | | |
| SCLK | 29 | I | 1 | Serial interface clock input. The pin has an internal 100 k Ω pull-down resistor. | | | | | |
| | | | | This pin functions as serial interface data input when RESET is LOW. It functions as power down control pin when RESET is tied high. | | | | | |
| SDATA | 28 | 1 | 1 | See Table 3 for detailed information. | | | | | |
| | | | | The pin has an internal 100 k Ω pull-down resistor. | | | | | |
| | | | | This pin functions as serial interface enable input when RESET is low. | | | | | |
| SEN | 27 | I | 1 | It functions as output clock edge control when RESET is tied high. See Table 4 for detailed information. | | | | | |
| | | | | The pin has an internal 100 k Ω pull-up resistor to AVDD. | | | | | |
| OE | 7 | Т | 1 | Output buffer enable input, active high. The pin has an internal 100 k Ω pull-up resistor to AVDD. | | | | | |
| DFS | 6 | I | 1 | Data Format Select input. This pin sets the DATA FORMAT (2s complement or Offset binary) and the LVDS/CMOS output interface type. | | | | | |
| | | | | See Table 5 for detailed information. | | | | | |
| MODE ⁽¹⁾ | 23 | I | 1 | Internal or external reference selection and low speed mode control. control. See Table 6 for detailed information. | | | | | |
| CLKOUTP | 5 | 0 | 1 | Differential output clock, true | | | | | |
| CLKOUTM | 4 | 0 | 1 | Differential output clock, complement | | | | | |
| D0_D1_P | | 0 | 1 | Differential output data D0 and D1 multiplexed, true | | | | | |
| D0_D1_M | _ | 0 | 1 | Differential output data D0 and D1 multiplexed, complement | | | | | |
| D2_D3_P | _ | 0 | 1 | Differential output data D2 and D3 multiplexed, true | | | | | |
| D2_D3_M | - | 0 | 1 | Differential output data D2 and D3 multiplexed, complement | | | | | |
| D4_D5_P | _ | 0 | 1 | Differential output data D4 and D5 multiplexed, true | | | | | |
| D4_D5_M | See | 0 | 1 | Differential output data D4 and D5 multiplexed, complement | | | | | |
| D6_D7_P | Figure 9 | 0 | 1 | Differential output data D6 and D7 multiplexed, true | | | | | |
| D6_D7_M | and Figure 10 | 0 | 1 | Differential output data D6 and D7 multiplexed, complement | | | | | |
| D8_D9_P | | 0 | 1 | Differential output data D8 and D9 multiplexed, true | | | | | |
| D8_D9_M | - | 0 | 1 | Differential output data D8 and D9 multiplexed, complement | | | | | |
| D10_D11_P | - | 0 | 1 | Differential output data D10 and D11 multiplexed, true | | | | | |
| D10_D11_M | | 0 | 1 | Differential output data D10 and D11 multiplexed, complement | | | | | |
| D12_D13_P | | 0 | 1 | Differential output data D12 and D13 multiplexed, true | | | | | |
| D12_D13_M | | 0 | 1 | Differential output data D12 and D13 multiplexed, complement | | | | | |
| OVR_SDOUT | 3 | ο | 1 | is a CMOS output with logic levels determined by DRVDD supply. It functions as out-of-range indicator after set and when register bit <serial readout=""> = 0. It functions as serial register readout pin when register SERIAL READOUT> = 1.</serial> | | | | | |

(1) In the next generation pin-compatible ADC family, MODE will be converted to a digital control pin for certain reserved functions. So, the selection of internal or external reference and low speed functions will not be supported using MODE. In the system board using ADS61x9/x8, the MODE pin can be routed to a digital controller. This will avoid board modification while migrating to the next generation ADC.

SLWS211B-JULY 2008-REVISED OCTOBER 2008

26

Table 8. PIN ASSIGNMENTS (LVDS MODE) — ADS6149/48 and ADS6129/28 (continued)

| PIN | | | NO. | | |
|-------|-------------------------------------|-----|------------|--|--|
| NAME | NO. | I/O | of PINS | DESCRIPTION | |
| DRVDD | 2, 35 | I | 2 | 1.8 V Digital and output buffer supply | |
| DRGND | 1, 36, PAD | I | 2 | Digital and output buffer ground | |
| NC | See Figure 9 and Figure 10 | | | Do not connect | |



www.ti.com



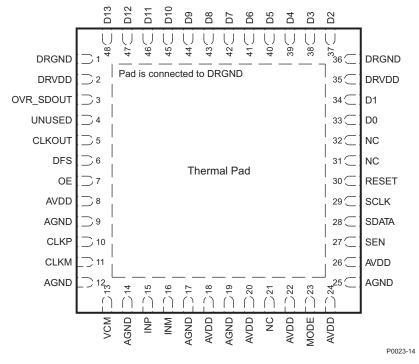


Figure 11. PIN CONFIGURATION (CMOS MODE) – ADS6149/48

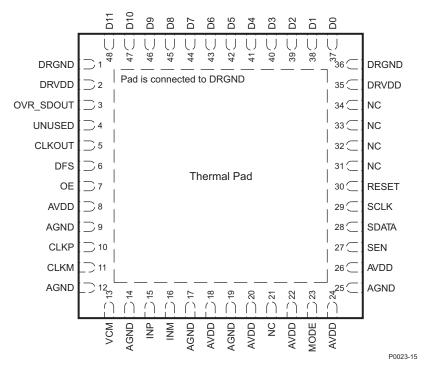


Figure 12. PIN CONFIGURATION (CMOS MODE) – ADS6129/28

SLWS211B-JULY 2008-REVISED OCTOBER 2008



Texas

www.ti.com

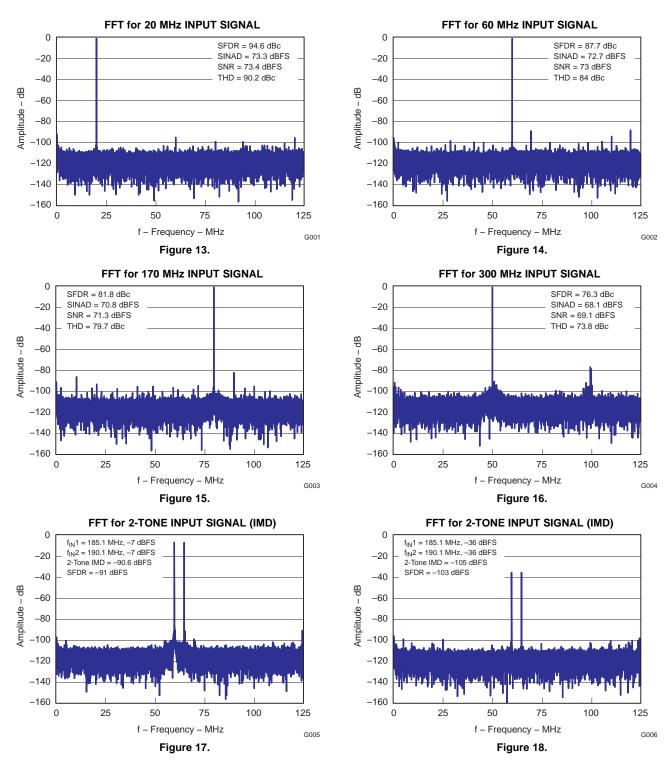
PIN ASSIGNMENTS (CMOS MODE) – ADS6149/48 and ADS6129/28

| PIN | J | | NO of | |
|------------|--------------------------------------|-----|----------------|---|
| NAME | NO. | I/O | NO. of PINS | DESCRIPTION |
| AVDD | 8, 18, 20, 22, 24, 26 | I | 6 | 3.3-V Analog power supply |
| AGND | 9, 12, 14, 17, 19, 25 | I | 6 | Analog ground |
| CLKP, CLKM | 10, 11 | Ι | 2 | Differential clock input |
| INP, INM | 15, 16 | Ι | 2 | Differential analog input |
| | | | | Internal reference mode – Common-mode voltage output. |
| VCM | 13 | 10 | 1 | External reference mode – Reference input. The voltage forced on this pin sets the internal references |
| | | | | Serial interface RESET input. |
| RESET | 30 | I | 1 | When using the serial interface mode, the user MUST initialize internal registers through hardware RESET by applying a high-going pulse on this pin or by using software reset option. Refer to <i>SERIAL INTERFACE</i> section. |
| | | | | In parallel interface mode, the user has to tie RESET pin permanently HIGH. (SDATA and SEN are used as parallel pin controls in this mode) |
| | | | | The pin has an internal 100 kΩ pull-down resistor. |
| SCLK | 29 | I | 1 | Serial interface clock input. The pin has an internal 100 k Ω pull-down resistor. |
| SDATA | 28 | 1 | 1 | This pin functions as serial interface data input when RESET is LOW. It functions as power down control pin when RESET is tied high. |
| OBINIT | 20 | | | See Table 3 for detailed information. |
| | | | | The pin has an internal 100 k Ω pull-down resistor. |
| SEN | 27 | I | 1 | This pin functions as serial interface enable input when RESET is low. It functions as output clock edge control when RESET is tied high. See Table 4 for detailed information. |
| | | | | The pin has an internal 100 k Ω pull-up resistor to AVDD. |
| DFS | 6 | I | 1 | Data Format Select input. This pin sets the DATA FORMAT (2s complement or Offset binary) and the LVDS/CMOS output interface type. |
| | | | | See Table 5 for detailed information. |
| MODE | 23 | I | 1 | Internal or external reference selection control and low speed mode control. See Table 6 for detailed information. |
| CLKOUT | 5 | 0 | 1 | CMOS output clock |
| OE | 7 | Ι | 1 | Output buffer enable input, active high. The pin has an internal 100 k Ω pull-up resistor to AVDD. |
| CLKOUTM | 4 | 0 | 1 | Differential output clock, complement |
| D0D13 | See Figure 11 and Figure 12 | 0 | 14/12 | 14 bit/12 bit CMOS output data |
| OVR_SDOUT | 3 | 0 | 1 | It is a CMOS output with logic levels determined by DRVDD supply. It functions as out-of-range indicator after reset and when register bit <serial readout=""> = 0. It functions as serial register readout pin when <serial readout=""> = 1.</serial></serial> |
| DRVDD | 2, 35 | Ι | 2 | 1.8 V Digital and output buffer supply |
| DRGND | 1, 36, PAD | Ι | 2 | Digital and output buffer ground |
| UNUSED | 4 | | 1 | Unused pin in CMOS mode |
| NC | See Figure 11 and Figure 12 | | | Do not connect |



TYPICAL CHARACTERISTICS - ADS6149

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface, 32K point FFT (unless otherwise noted)

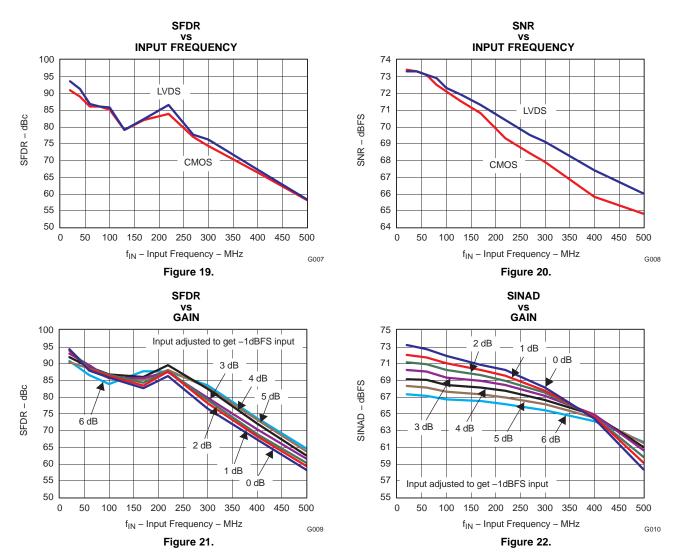


SLWS211B-JULY 2008-REVISED OCTOBER 2008

Copyright © 2008, Texas Instruments Incorporated

TYPICAL CHARACTERISTICS - ADS6149 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface, 32K point FFT (unless otherwise noted)

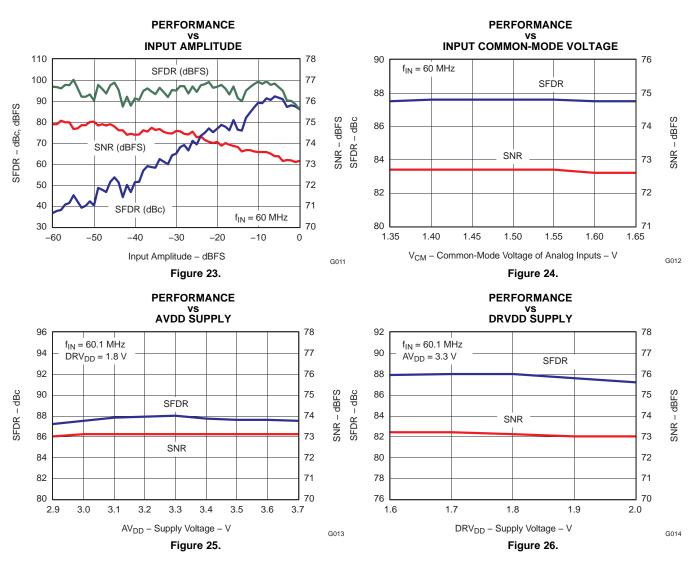


www.ti.com



TYPICAL CHARACTERISTICS - ADS6149 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface, 32K point FFT (unless otherwise noted)

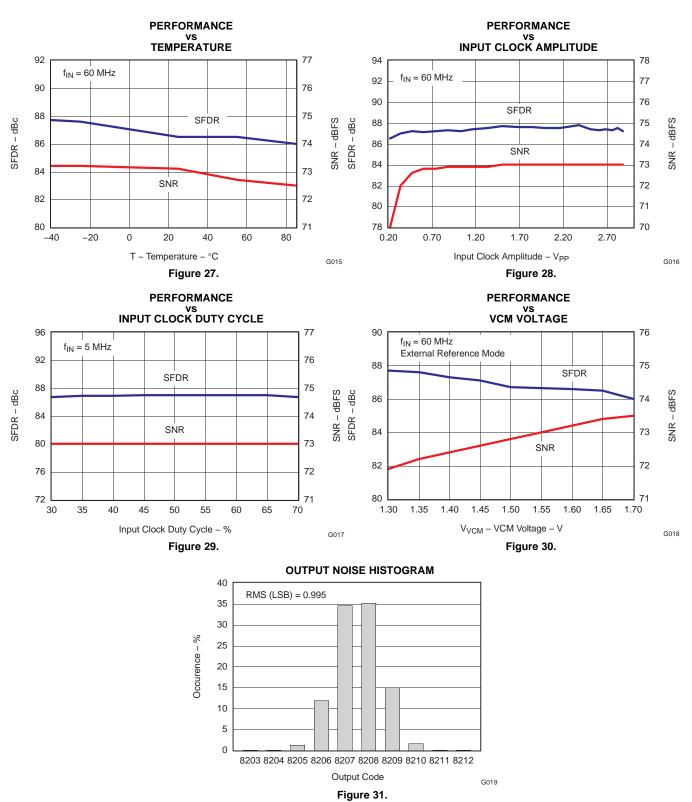


ADS6149/ADS6129 ADS6148/ADS6128 SLWS211B-JULY 2008-REVISED OCTOBER 2008 Texas Instruments

www.ti.com



All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface, 32K point FFT (unless otherwise noted)



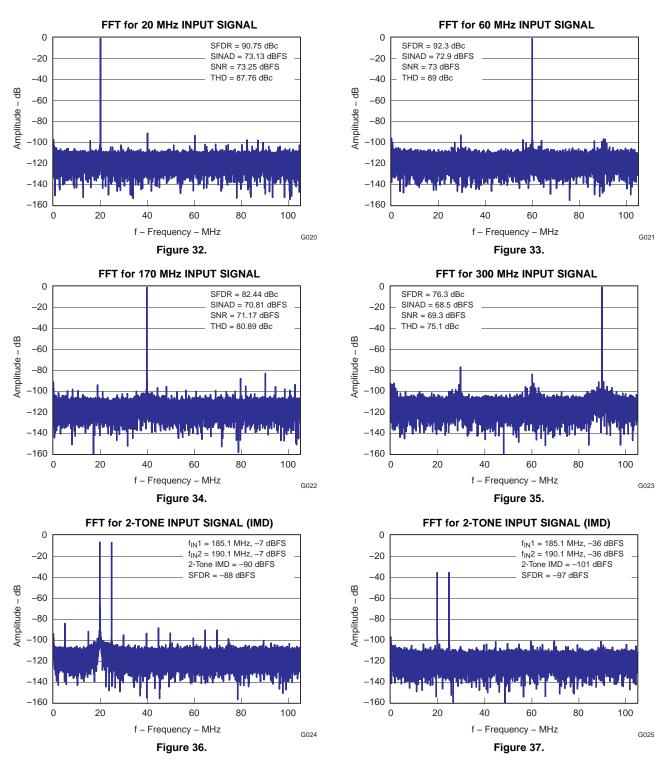
Copyright © 2008, Texas Instruments Incorporated

Product Folder Link(s): ADS6149/ADS6129 ADS6148/ADS6128



TYPICAL CHARACTERISTICS - ADS6148

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)



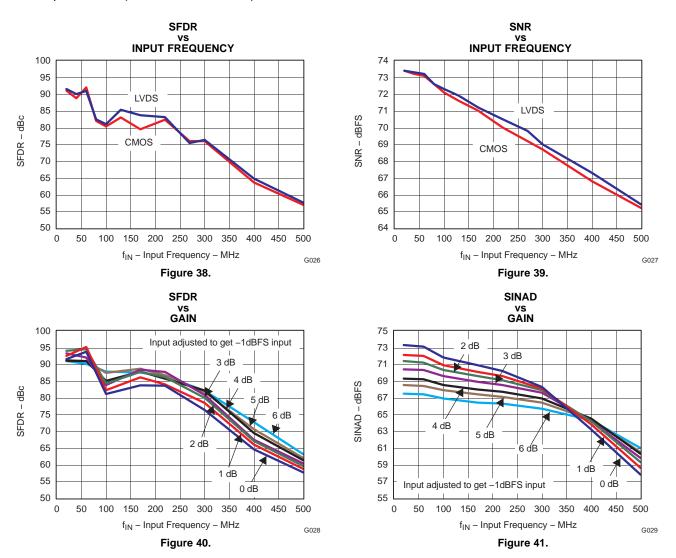
ADS6149/ADS6129 ADS6148/ADS6128 SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

TYPICAL CHARACTERISTICS - ADS6148 (continued)

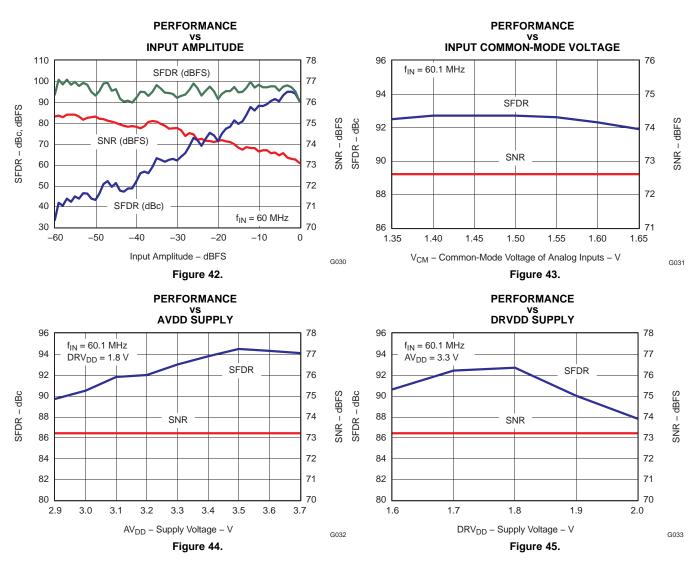
All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)





TYPICAL CHARACTERISTICS - ADS6148 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)

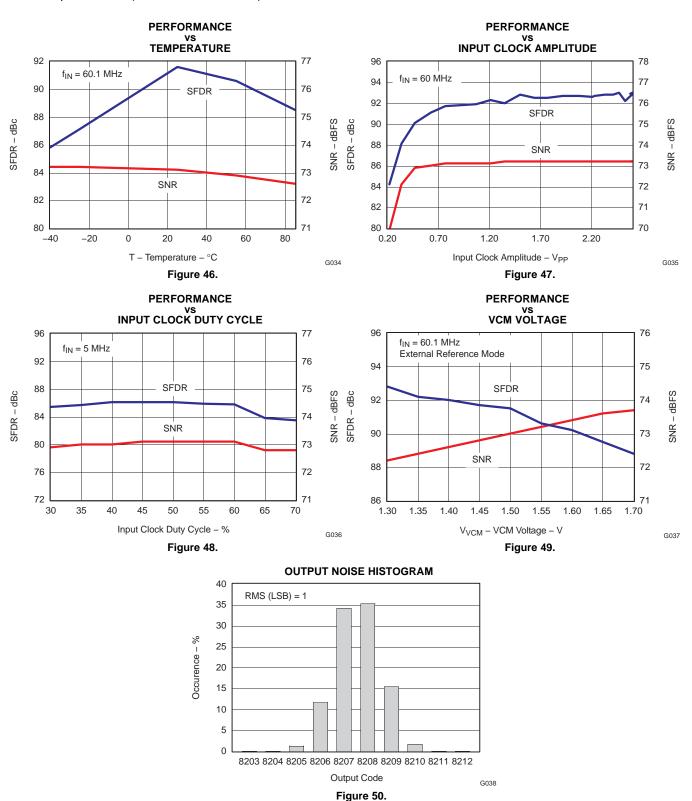


SLWS211B-JULY 2008-REVISED OCTOBER 2008

www.ti.com

TYPICAL CHARACTERISTICS - ADS6148 (continued)

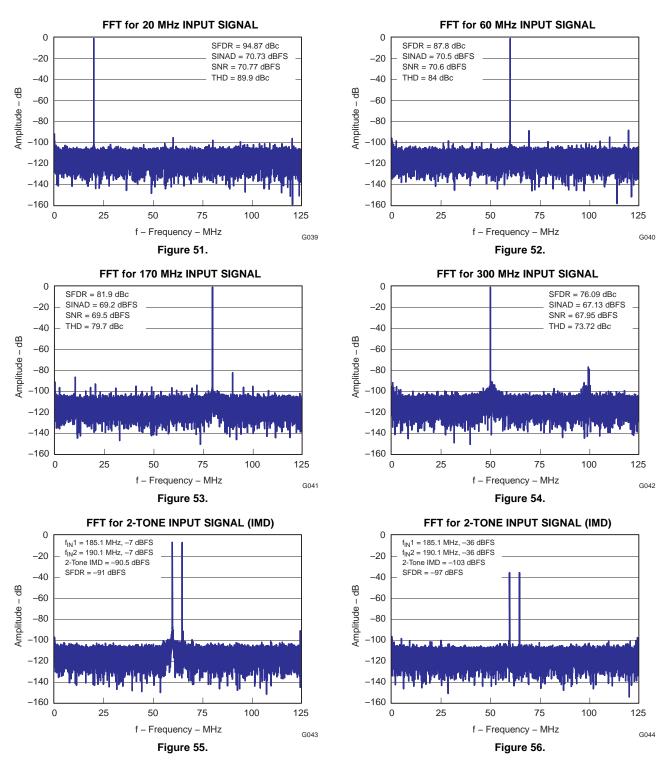
All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)





TYPICAL CHARACTERISTICS - ADS6129

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)



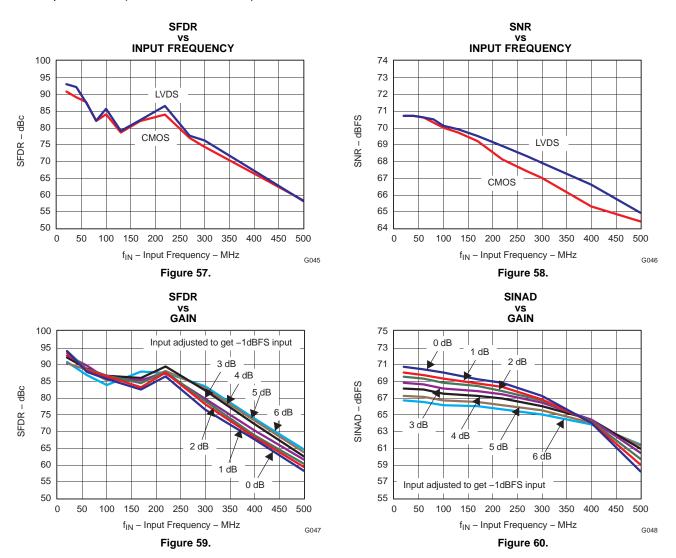
ADS6149/ADS6129 ADS6148/ADS6128 SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

TYPICAL CHARACTERISTICS - ADS6129 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)

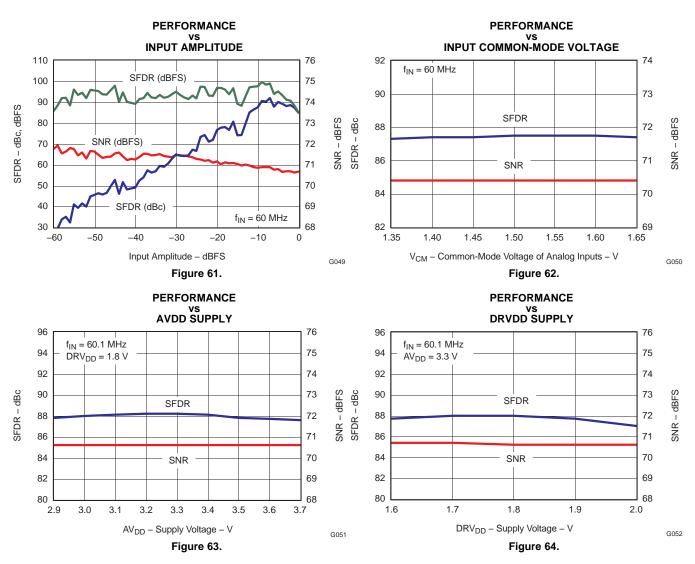




SLWS211B-JULY 2008-REVISED OCTOBER 2008

TYPICAL CHARACTERISTICS - ADS6129 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)



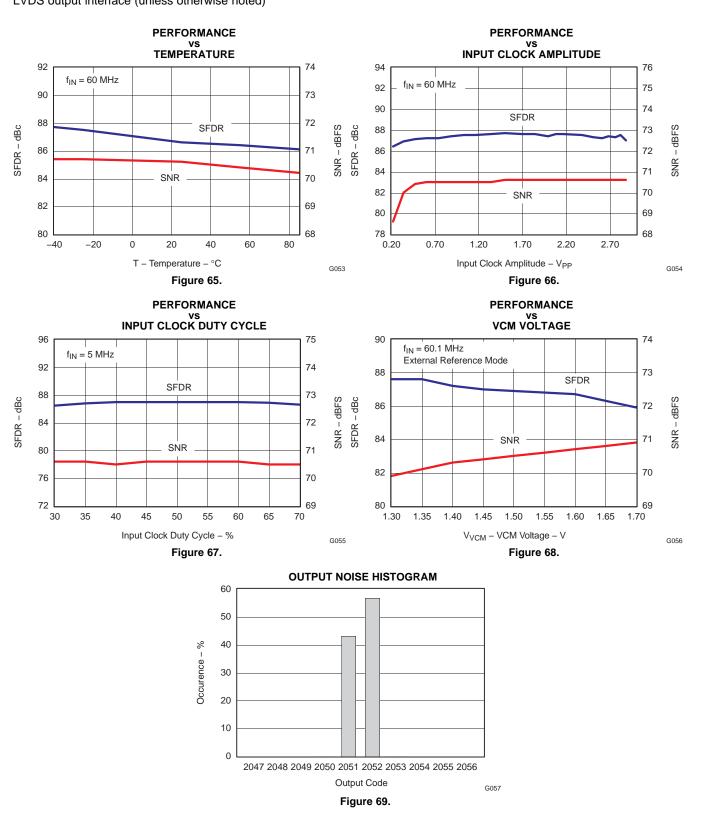
ADS6149/ADS6129 ADS6148/ADS6128

SLWS211B-JULY 2008-REVISED OCTOBER 2008

40



Copyright © 2008, Texas Instruments Incorporated



TYPICAL CHARACTERISTICS - ADS6129 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)

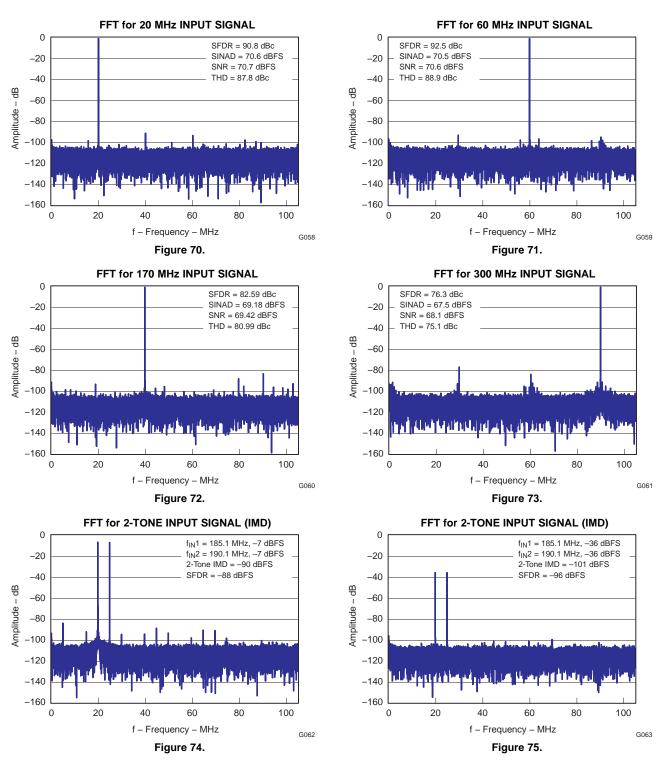
TEXAS INSTRUMENTS

www.ti.com



TYPICAL CHARACTERISTICS - ADS6128

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)



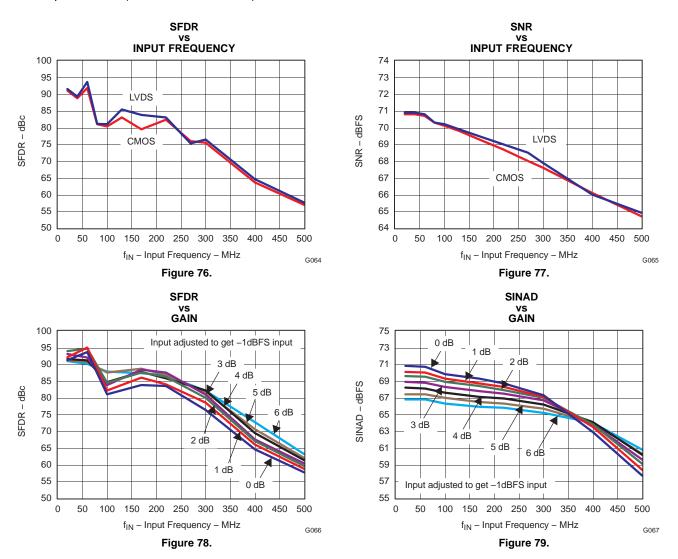
ADS6149/ADS6129 ADS6148/ADS6128 SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com



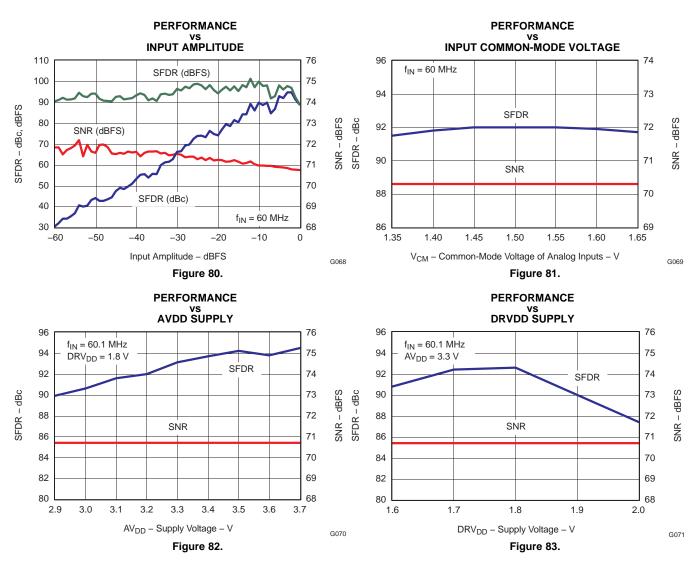
All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)





TYPICAL CHARACTERISTICS - ADS6128 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)



ADS6149/ADS6129 ADS6148/ADS6128

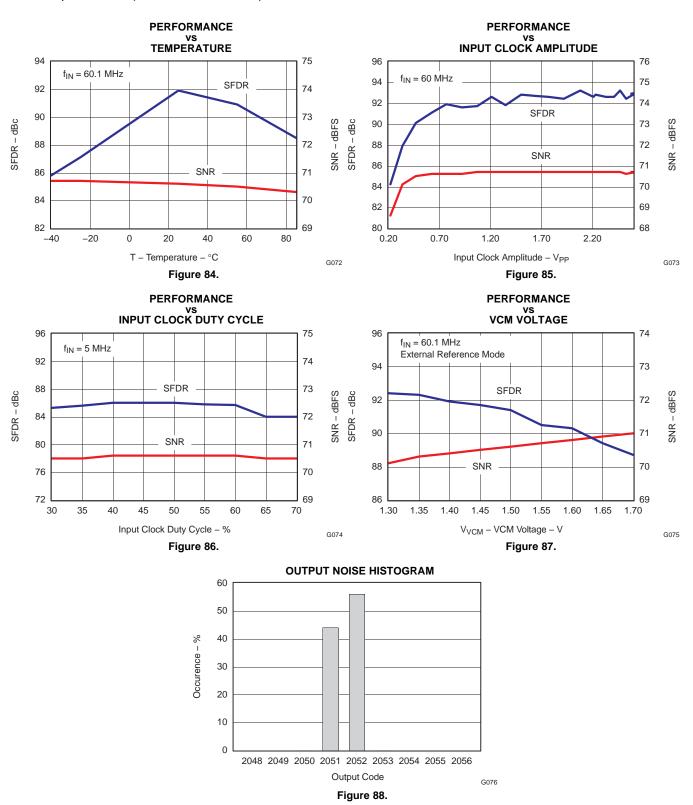
SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com

TYPICAL CHARACTERISTICS - ADS6128 (continued)

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)

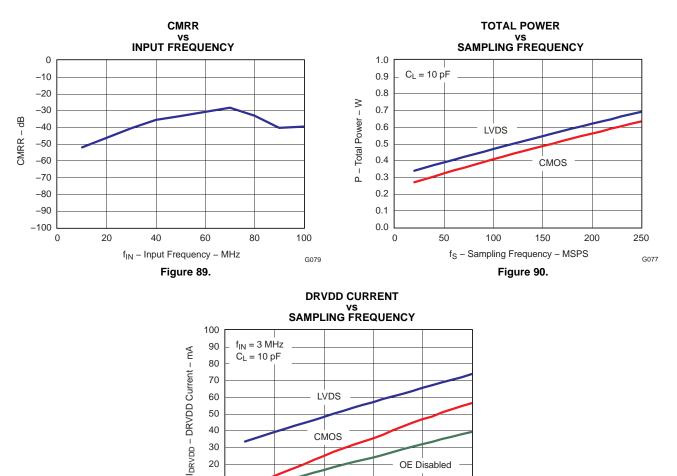


Copyright © 2008, Texas Instruments Incorporated



TYPICAL CHARACTERISTICS - COMMON PLOTS

All plots are at 25°C, AVDD = 3.3 V, DRVDD = 1.8 V, maximum rated sampling frequency, sine wave input clock. 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 DBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)



10

0 L

50

100

150

f_S – Sampling Frequency – MSPS

Figure 91.

200

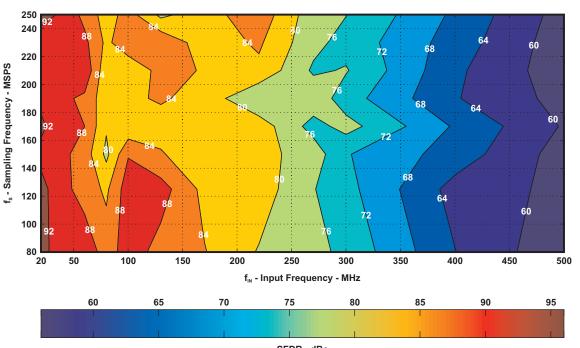
250

G078

SLWS211B-JULY 2008-REVISED OCTOBER 2008

TEXAS INSTRUMENTS

www.ti.com



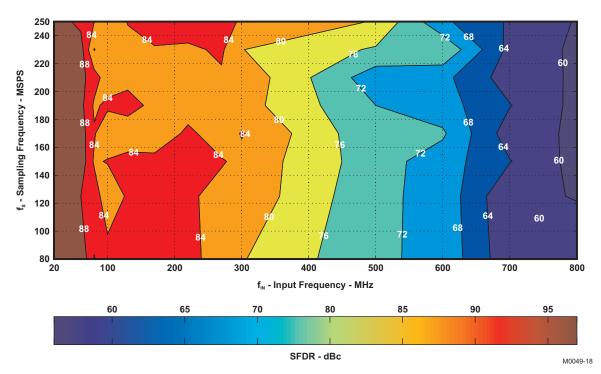
CONTOUR PLOTS - ADS6149/ADS6148/ADS6129/ADS6128

Plots are at 25°C, AVDD = 3.3V, DRVDD = 1.8 V, sine wave input clock, 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)

SFDR - dBc

M0049-17









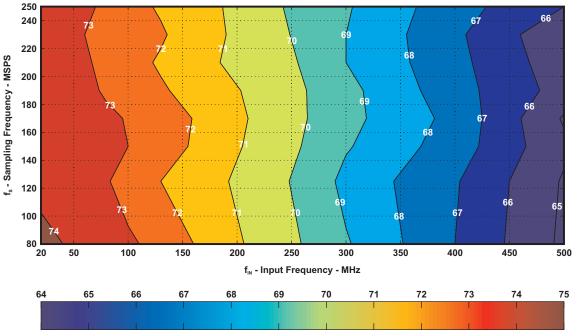
ADS6149/ADS6129 ADS6148/ADS6128

SLWS211B-JULY 2008-REVISED OCTOBER 2008

www.ti.com

CONTOUR PLOTS - ADS6149/ADS6148

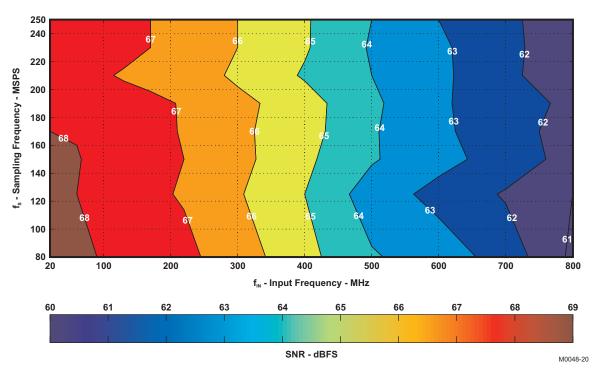
Plots are at 25°C, AVDD = 3.3V, DRVDD = 1.8 V, sine wave input clock, 1.5 V_{PP} differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain, LVDS output interface (unless otherwise noted)



SNR - dBFS

M0048-19









APPLICATION INFORMATION

THEORY OF OPERATION

ADS6149/48 and ADS6129/28 is a family of high performance, low power 14-bit and 12-bit pipeline A/D converters with maximum sampling rate up to 250 MSPS.

At every rising edge of the input clock, the analog input signal is sampled and sequentially converted by a pipeline of low resolution stages. In each stage, the sampled and held signal is converted by a high speed, low resolution flash sub-ADC. The difference (residue) between the stage input and its quantized equivalent is gained and propagates to the next stage. At every clock, each succeeding stage resolves the sampled input with greater accuracy. The digital outputs from all stages are combined in a digital correction logic block to create the final 14 or 12 bit code, after a data latency of 18 clock cycles.

The digital output is available as either DDR LVDS or parallel CMOS and coded in either straight offset binary or binary 2s complement format.

The dynamic offset of the first stage sub-ADC limits the maximum analog input frequency to about 500MHz (with $2V_{PP}$ amplitude) and about 800MHz (with $1V_{PP}$ amplitude).

ANALOG INPUT

The analog input consists of a switched-capacitor based differential sample and hold architecture.

This differential topology results in a good AC performance even for high input frequencies at high sampling rates. The INP and INM pins have to be externally biased around a common-mode voltage of 1.5V, available on VCM pin. For a full-scale differential input, each input pin INP, INM has to swing symmetrically between VCM + 0.5V and VCM – 0.5V, resulting in a 2Vpp differential input swing.

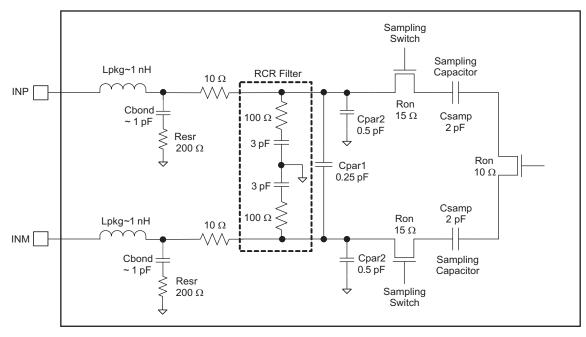


Figure 96. Analog Input Equivalent Circuit

The input sampling circuit has a high 3-dB bandwidth that extends up to 700 MHz (measured from the input pins to the sampled voltage).

Copyright © 2008, Texas Instruments Incorporated



Drive Circuit Requirements

For optimum performance, the analog inputs must be driven differentially. This improves the common-mode noise immunity and even order harmonic rejection. A 5 Ω to 15 Ω resistor in series with each input pin is recommended to damp out ringing caused by package parasitics. It is also necessary to present low impedance (< 50 Ω) for the common mode switching currents. This can be achieved by using two resistors from each input terminated to the common mode voltage (VCM).

Note that the device includes an internal R-C filter from each input to ground. The purpose of this filter is to absorb the glitches caused by the opening and closing of the sampling capacitors. The cut-off frequency of the R-C filter involves a trade-off. A lower cut-off frequency (larger C) absorbs glitches better, but also reduces the input bandwidth and the maximum input frequency that can be supported. On the other hand, with no internal R-C filter, high input frequency can be supported, but now the sampling glitches need to be supplied by the external driving circuit. This has limitations due to the presence of the package bond-wire inductance.

In ADS61x9/x8, the R-C component values have been optimized while supporting high input bandwidth (up to 750 MHz). However, in applications where high input frequency support is not required, the filtering of the glitches can be improved further using an external R-C-R filter (as shown in Figure 99 and Figure 100).

In addition to the above, the drive circuit may have to be designed to provide a low insertion loss over the desired frequency range and matched impedance to the source. While doing this, the ADC input impedance must be considered. Figure 97 and Figure 98 show the impedance ($Zin = Rin \parallel Cin$) looking into the ADC input pins.

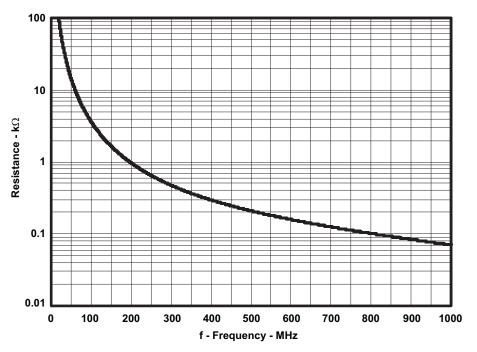


Figure 97. ADC Analog Input Resistance (Rin) Across Frequency



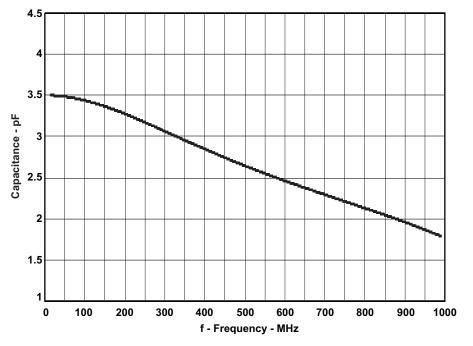


Figure 98. ADC Analog Input Capacitance (Cin) Across Frequency

Driving Circuit

Two example driving circuit configurations are shown in Figure 99 and Figure 100 – one optimized for low bandwidth (low input frequencies) and the other one for high bandwidth to support higher input frequencies.

In Figure 99, an external R-C-R filter using 22pF has been used. Together with the series inductor (39nH), this combination forms a filter and absorbs the sampling glitches. Due to the large capacitor (22pF) in the R-C-R and the 15Ω resistors in series with each input pin, the drive circuit has low bandwidth, and supports low input frequencies (< 100MHz).

To support high input frequencies (up to about 300MHz, see Figure 100), the capacitance used in the R-C-R is reduced to 3.3pF and the series inductors are shorted out. Together with the lower series resistors (5 Ω), this drive circuit provides high bandwidth and supports high input frequencies.

A transformer such as ADT1-1WT or ETC1-1-13 can be used up to 300MHz.

In Figure 100, by dropping the external R-C-R filter, the drive circuit has high bandwidth and can support high input frequencies (> 300MHz). For example, a transformer such as the ADTL2-18 can be used.

Note that both the drive circuits have been terminated by 50Ω near the ADC side. The termination is accomplished using a 25Ω resistor from each input to the 1.5V common-mode (VCM) from the device. This biases the analog inputs around the required common-mode voltage.



SLWS211B-JULY 2008-REVISED OCTOBER 2008

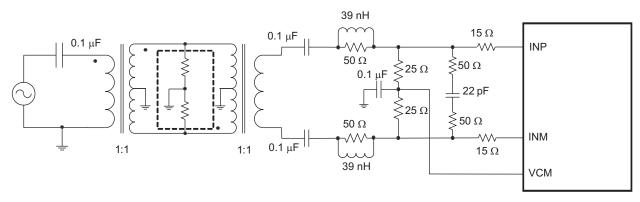


Figure 99. Drive Circuit with Low Bandwidth (for low input frequencies)

The mismatch in the transformer parasitic capacitance (between the windings) results in degraded even-order harmonic performance. Connecting two identical RF transformers back to back helps minimize this mismatch and good performance is obtained for high frequency input signals. An additional termination resistor pair may be required between the two transformers as shown in the figures. The center point of this termination is connected to ground to improve the balance between the P and M sides. The values of the terminations between the transformers and on the secondary side have to be chosen to get an effective 50Ω (in the case of 50Ω source impedance).

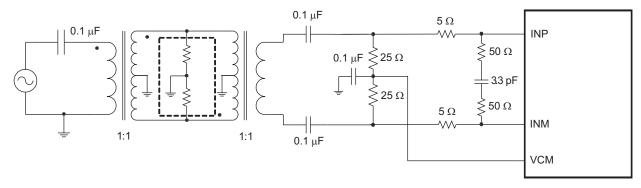


Figure 100. Drive Circuit with High Bandwidth (for high input frequencies)

Input Common-Mode

To ensure a low-noise common-mode reference, the VCM pin is filtered with a 0.1μ F low-inductance capacitor connected to ground. The VCM pin is designed to directly drive the ADC inputs. The input stage of the ADC sinks a common-mode current in the order of 500μ A (per input pin, at 250 MSPS). Equation 1 describes the dependency of the common-mode current and the sampling frequency.

$$\frac{500 \ \mu\text{A} \times \text{Fs}}{250 \ \text{MSPS}} \tag{1}$$

This equation helps to design the output capability and impedance of the CM driving circuit accordingly.

REFERENCE

ADS614X/2X has built-in internal references REFP and REFM, requiring no external components. Design schemes are used to linearize the converter load seen by the references; this and the on-chip integration of the requisite reference capacitors eliminates the need for external decoupling. The full-scale input range of the converter can be controlled in the external reference mode as explained below. The internal or external reference modes can be selected by programming the serial interface register bit **<REF>**.

Copyright © 2008, Texas Instruments Incorporated

SLWS211B-JULY 2008-REVISED OCTOBER 2008

(2)

Figure 101. Reference Section

Internal Reference

When the device is in internal reference mode, the REFP and REFM voltages are generated internally. Common-mode voltage (1.5V nominal) is output on VCM pin, which can be used to externally bias the analog input pins.

External Reference

When the device is in external reference mode, the VCM acts as a reference input pin. The voltage forced on the VCM pin is buffered and gained by 1.33 internally, generating the REFP and REFM voltages. The differential input voltage corresponding to full-scale is given by Equation 2.

Full-scale differential input pp = (Voltage forced on VCM) × 1.33

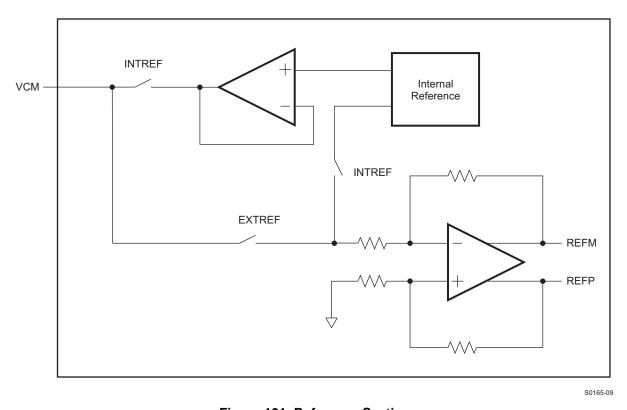
In this mode, the 1.5V common-mode voltage to bias the input pins has to be generated externally.

CLOCK INPUT

ADS614X/2X clock inputs can be driven differentially (sine, LVPECL or LVDS) or single-ended (LVCMOS), with little or no difference in performance between them. The common-mode voltage of the clock inputs is set to VCM using internal 5-k Ω resistors. This allows using transformer-coupled drive circuits for sine wave clock or ac-coupling for LVPECL, LVDS clock sources.



www.ti.com



2 Submit Documentation Feedback

52



ADS6149/ADS6129 ADS6148/ADS6128

SLWS211B-JULY 2008-REVISED OCTOBER 2008

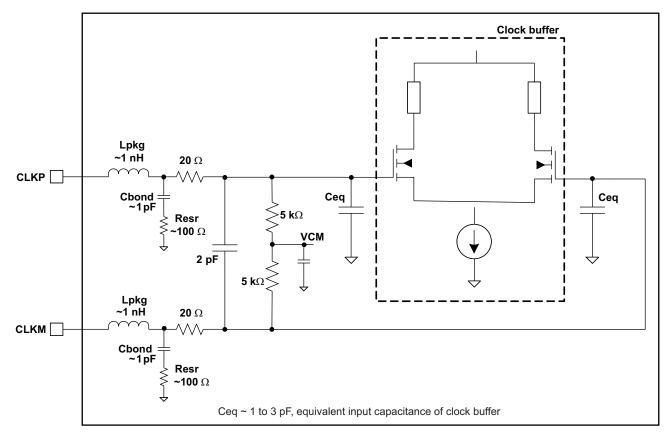
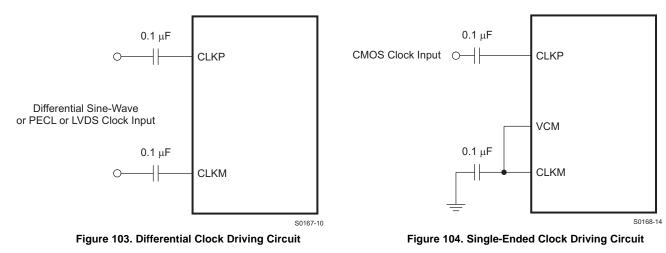


Figure 102. Internal Clock Buffer

Single-ended CMOS clock can be ac-coupled to the CLKP input, with CLKM connected to ground with a $0.1-\mu$ F capacitor, as shown in Figure 104. For best performance, the clock inputs have to be driven differentially, reducing susceptibility to common-mode noise. For high input frequency sampling, it is recommended to use a clock source with low jitter. Band-pass filtering of the clock source can help reduce the effect of jitter. There is no change in performance with a non-50% duty cycle clock input.



TEXAS INSTRUMENTS

FINE GAIN CONTROL

ADS614X/2X includes gain settings that can be used to get improved SFDR performance (compared to no gain). The gain is programmable from 0dB to 6dB (in 0.5 dB steps). For each gain setting, the analog input full-scale range scales proportionally, as shown in Table 9.

The SFDR improvement is achieved at the expense of SNR; for each gain setting, the SNR degrades about 0.5–1dB. The SNR degradation is less at high input frequencies. As a result, the gain is useful at high input frequencies as the SFDR improvement is significant with marginal degradation in SNR.

So, the gain can be used to trade-off between SFDR and SNR. Note that the default gain after reset is 0 dB.

| Gain, dB | Туре | Full-Scale, V _{PP} | | | |
|----------|--|-----------------------------|--|--|--|
| 0 | Default after reset | 2V | | | |
| 1 | | 1.78 | | | |
| 2 | | 1.59 | | | |
| 3 | Fine programmable | 1.42 | | | |
| 4 | Fine, programmable | 1.26 | | | |
| 5 | - | 1.12 | | | |
| 6 | | 1.00 | | | |

Table 9. Full-Scale Range Across Gains

OFFSET CORRECTION

ADS61x9/x8 has an internal offset correction algorithm that estimates and corrects the dc offset up to ±10mV. The correction can be enabled using the serial register bit <ENABLE OFFSET CORR>. Once enabled, the algorithm estimates the channel offset and applies the correction every clock cycle. The time constant of the correction loop is a function of the sampling clock frequency. The time constant can be controlled using register bits <OFFSET CORR TIME CONSTANT> as described inTable 10.

After the offset is estimated, the correction can be locked in by setting $\langle OFFSET CORR TIME CONSTANT \rangle = 0$. Once locked, the last estimated value is used for offset correction every clock cycle. Note that offset correction is disabled by default after reset.

Figure 105 shows the time response of the offset correction algorithm, after it is enabled.

| <offset constant="" corr="" time=""> D3-D0</offset> | Time constant (TCCLK), number of clock cycles | Time constant, sec (=TCCLK x 1/Fs) (1) 1 ms | | |
|---|---|--|--|--|
| 0000 | 256 k | | | |
| 0001 | 512 k | 2 ms | | |
| 0010 | 1 M | 4 ms | | |
| 0011 | 2 M | 8 ms | | |
| 0100 | 4 M | 17 ms | | |
| 0101 | 8 M | 33 ms | | |
| 0110 | 16 M | 67 ms | | |
| 0111 | 32 M | 134 ms | | |
| 1000 | 64 M | 268 ms | | |
| 1001 | 128 M | 536 ms | | |
| 1010 | 256 M | 1.1 s | | |
| 1011 | 512 M | 2.2 s | | |
| 1100 | RESERVED | _ | | |
| 1101 | RESERVED | - | | |
| 1110 | RESERVED | - | | |
| 1111 | RESERVED | _ | | |

 Table 10. Time Constant of Offset Correction Algorithm

54



SLWS211B-JULY 2008-REVISED OCTOBER 2008

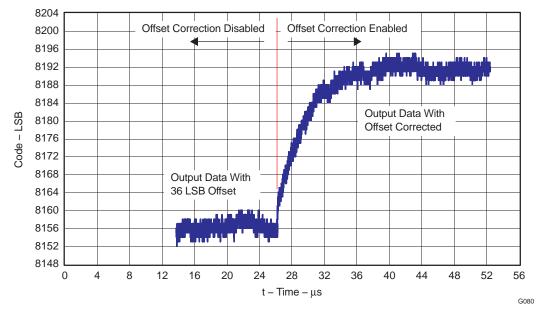


Figure 105. Output Code Time Response With Offset Correction Enabled

POWER DOWN

ADS614X/2X has three power down modes – power down global, standby and output buffer disable.

Power Down Global

In this mode, the entire chip including the A/D converter, internal reference and the output buffers are powered down resulting in reduced total power dissipation of about 20 mW. The output buffers are in high impedance state. The wake-up time from global power down to data becoming valid in normal mode is typically 25 µs.

This can be controlled using register bit **<PDN GLOBAL>** or using SDATA pin (in parallel configuration mode).

Standby

Here, only the A/D converter is powered down and internal references are active, resulting in fast wake-up time of 300 ns. The total power dissipation in standby is about 120 mW.

This can be controlled using register bit **<STANDBY>**.

Output Buffer Disable

The output buffers can be disabled and put in high impedance state – wakeup time from this mode is fast, about 40 ns. This can be controlled using register bit **<PDN OBUF>**.

Input Clock Stop

In addition to the above, the converter enters a low-power mode when the input clock frequency falls below 1 MSPS. The power dissipation is about 120 mW.

POWER SUPPLY SEQUENCE

During power-up, the AVDD and DRVDD supplies can come up in any sequence. The two supplies are separated in the device. Externally, they can be driven from separate supplies or from a single supply.

DIGITAL OUTPUT INFORMATION

ADS614X/2X provides 14-bit/12-bit data and an output clock synchronized with the data.

ADS6149/ADS6129 ADS6148/ADS6128 SLWS211B-JULY 2008-REVISED OCTOBER 2008



Output Interface

Two output interface options are available – Double Data Rate (DDR) LVDS and parallel CMOS. They can be selected using the serial interface register bit **<ODI>** or using DFS pin in parallel configuration mode.

DDR LVDS Outputs

In this mode, the data bits and clock are output using LVDS (Low Voltage Differential Signal) levels. Two data bits are multiplexed and output on each LVDS differential pair.

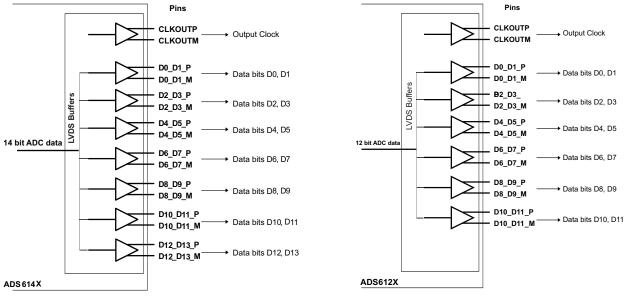


Figure 106. 14-Bit ADC LVDS Outputs

Figure 107. 12-Bit ADC LVDS Outputs

Even data bits D0, D2, D4... are output at the falling edge of CLKOUTP and the odd data bits D1, D3, D5... are output at the rising edge of CLKOUTP. Both the rising and falling edges of CLKOUTP have to be used to capture all of the data bits (see Figure 108).



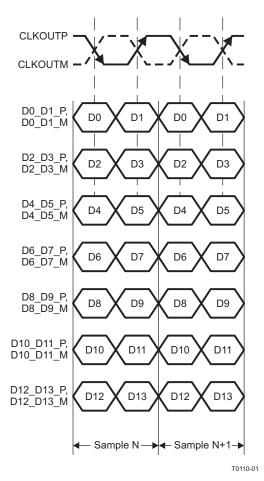


Figure 108. DDR LVDS Interface

LVDS Buffer

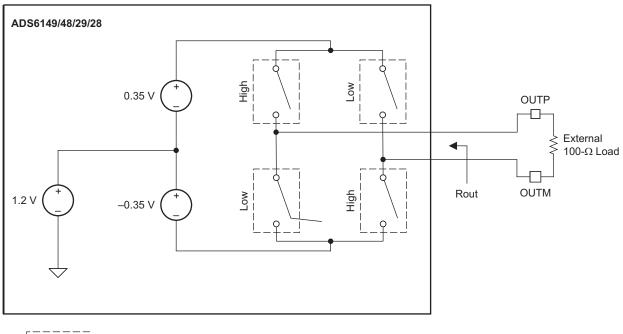
The equivalent circuit of each LVDS output buffer is shown in Figure 109. The buffer is designed to present an output impedance of 100 Ω (Rout). The differential outputs can be terminated at the receive end by a 100 Ω termination. The buffer output impedance behaves like a source-side series termination. By absorbing reflections from the receiver end, it helps to improve signal integrity. Note that this internal termination cannot be disabled and its value cannot be changed.

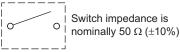
ADS6149/ADS6129 ADS6148/ADS6128

SLWS211B-JULY 2008-REVISED OCTOBER 2008



www.ti.com





When the High switches are closed, OUTP = 1.375 V, OUTM = 1.025 V When the Low switches are closed, OUTP = 1.025 V, OUTM = 1.375 V When the High (or Low) switches are closed, Rout = 100 Ω

S0374-01

Figure 109. LVDS Buffer Equivalent Circuit

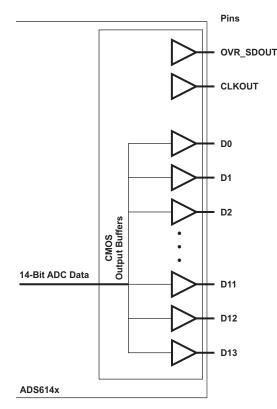
Parallel CMOS Interface

In the CMOS mode, each data bit is output on separate pin as CMOS voltage level, every clock cycle. The rising edge of the output clock CLKOUT can be used to latch data in the receiver *(for sampling frequencies up to 150 MSPS)*.

Up to 150 MSPS, the setup and hold timings of the output data with respect to CLKOUT are specified. It is recommended to minimize the load capacitance seen by data and clock output pins by using short traces to the receiver. Also, match the output data and clock traces to minimize the skew between them.

For sampling frequencies > 150 MSPS, it is recommended to use an external clock to capture data. The delay from input clock to output data and the data valid times are specified for the higher sampling frequencies. These timings can be used to delay the input clock appropriately and use it to capture the data (see Figure 4).







Output Buffer Strength Programmability

Switching noise (caused by CMOS output data transitions) can couple into the analog inputs during the instant of sampling and degrade the SNR. The coupling and SNR degradation increases as the output buffer drive is made stronger. To minimize this, the CMOS output buffers are designed with controlled drive strength to get best SNR. The default drive strength also ensures wide data stable window for load capacitances up to 5 pF.

CMOS Interface Power Dissipation

With CMOS outputs, the DRVDD current scales with the sampling frequency and the load capacitance on every output pin. The maximum DRVDD current occurs when each output bit toggles between 0 and 1 every clock cycle. In an actual application, the DRVDD current would be determined by the average number of output bits switching, which is a function of the sampling frequency and the nature of the analog input signal.

Digital current due to CMOS output switching = $C_L \times DRVDD \times (N \times F_{AVG})$,

where

 C_L = load capacitance,

N x F_{AVG} = average number of output bits switching.

Figure 91 shows the current across sampling frequencies at 2 MHz analog input frequency.

Output Data Format

Two output data formats are supported – 2s complement and offset binary. They can be selected using the serial interface register bit **<DATA FORMAT>** or controlling the DFS pin in parallel configuration mode.

In the event of an input voltage overdrive, the digital outputs go to the appropriate full scale level. For a positive overdrive, the output code is 0x3FFF in offset binary output format, and 0x1FFF in 2s complement output format. For a negative input overdrive, the output code is 0x0000 in offset binary output format and 0x2000 in 2s complement output format.

Copyright © 2008, Texas Instruments Incorporated

TEXAS INSTRUMENTS

www.ti.com

BOARD DESIGN CONSIDERATIONS

Grounding

A single ground plane is sufficient to give good performance, provided the analog, digital, and clock sections of the board are cleanly partitioned. See the EVM User Guide (SLWU061) for details on layout and grounding.

Supply Decoupling

As the ADS61x9/x8 already includes internal decoupling, minimal external decoupling can be used without loss in performance. Note that decoupling capacitors can help filter external power supply noise, so the optimum number of capacitors would depend on the actual application. The decoupling capacitors should be placed close to the converter supply pins.

Exposed Pad

In addition to providing a path for heat dissipation, the pad is also electrically connected to digital ground internally. So, it is necessary to solder the exposed pad to the ground plane for best thermal and electrical performance.

For detailed information, see the application notes for QFN Layout Guidelines (SLOA122) and QFN/SON PCB Attachment (SLUA271).



DEFINITION OF SPECIFICATIONS

S6149/ADS6129

Analog Bandwidth – The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low frequency value.

Aperture Delay – The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs. This delay will be different across channels. The maximum variation is specified as aperture delay variation (channel-channel).

Aperture Uncertainty (Jitter) – The sample-to-sample variation in aperture delay.

Clock Pulse Width/Duty Cycle – The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse width) to the period of the clock signal. Duty cycle is typically expressed as a percentage. A perfect differential sine-wave clock results in a 50% duty cycle.

Maximum Conversion Rate – The maximum sampling rate at which certified operation is given. All parametric testing is performed at this sampling rate unless otherwise noted.

Minimum Conversion Rate – The minimum sampling rate at which the ADC functions.

Differential Nonlinearity (DNL) – An ideal ADC exhibits code transitions at analog input values spaced exactly 1 LSB apart. The DNL is the deviation of any single step from this ideal value, measured in units of LSBs.

Integral Nonlinearity (INL) – The INL is the deviation of the ADC's transfer function from a best fit line determined by a least squares curve fit of that transfer function, measured in units of LSBs.

Gain Error – Gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range. Gain error has two components: error due to reference inaccuracy and error due to the channel. Both these errors are specified independently as E_{GREF} and E_{GCHAN} .

To a first order approximation, the total gain error will be $E_{TOTAL} \sim E_{GREF} + E_{GCHAN}$.

For example, if $E_{TOTAL} = \pm 0.5\%$, the full-scale input varies from (1-0.5/100) x FS_{ideal} to (1 + 0.5/100) x FS_{ideal}.

Offset Error – The offset error is the difference, given in number of LSBs, between the ADC's actual average idle channel output code and the ideal average idle channel output code. This quantity is often mapped into mV.

Temperature Drift – The temperature drift coefficient (with respect to gain error and offset error) specifies the change per degree Celsius of the parameter from T_{MIN} to T_{MAX} . It is calculated by dividing the maximum deviation of the parameter across the T_{MIN} to T_{MAX} range by the difference T_{MAX} - T_{MIN} .

Signal-to-Noise Ratio – SNR is the ratio of the power of the fundamental (PS) to the noise floor power (PN), excluding the power at DC and the first nine harmonics.

SNR = 10Log¹⁰
$$\frac{P_s}{P_N}$$

(3)

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

Signal-to-Noise and Distortion (SINAD) – SINAD is the ratio of the power of the fundamental (P_S) to the power of all the other spectral components including noise (P_N) and distortion (P_D), but excluding dc.

$$SINAD = 10Log^{10} \frac{P_S}{P_N + P_D}$$
(4)

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

Effective Number of Bits (ENOB) – The ENOB is a measure of the converter performance as compared to the theoretical limit based on quantization noise.

Copyright © 2008, Texas Instruments Incorporated

ADS6149/ADS6129 ADS6148/ADS6128

 $\mathsf{ENOB} = \frac{\mathsf{SINAD} - 1.76}{6.02}$

first nine harmonics (PD).

THD = 10Log¹⁰ $\frac{P_S}{P_N}$

SLWS211B-JULY 2008-REVISED OCTOBER 2008

INSTRUMENTS

EXAS

(6)

(7)

THD is typically given in units of dBc (dB to carrier).

Spurious-Free Dynamic Range (SFDR) – The ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier).

Total Harmonic Distortion (THD) - THD is the ratio of the power of the fundamental (Ps) to the power of the

Two-Tone Intermodulation Distortion – IMD3 is the ratio of the power of the fundamental (at frequencies f1 and f2) to the power of the worst spectral component at either frequency 2f1–f2 or 2f2–f1. IMD3 is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

DC Power Supply Rejection Ratio (DC PSRR) – The DC PSSR is the ratio of the change in offset error to a change in analog supply voltage. The DC PSRR is typically given in units of mV/V.

AC Power Supply Rejection Ratio (AC PSRR) – AC PSRR is the measure of rejection of variations in the supply voltage by the ADC. If ΔV_{SUP} is the change in supply voltage and ΔV out is the resultant change of the ADC output code (referred to the input), then

PSRR = 20Log¹⁰ $\frac{\Delta V_{OUT}}{\Delta V_{SUP}}$ (Expressed in dBc)

Voltage Overload Recovery – The number of clock cycles taken to recover to less than 1% error after an overload on the analog inputs. This is tested by separately applying a sine wave signal with 6dB positive and negative overload. The deviation of the first few samples after the overload (from their expected values) is noted.

Common Mode Rejection Ratio (CMRR) – CMRR is the measure of rejection of variation in the analog input common-mode by the ADC. If ΔVcm_{in} is the change in the common-mode voltage of the input pins and ΔV_{OUT} is the resultant change of the ADC output code (referred to the input), then

$$CMRR = 20Log^{10} \frac{\Delta V_{OUT}}{\Delta V_{CM}}$$
 (Expressed in dBc) (8)

Cross-Talk (only for multi-channel ADC)– This is a measure of the internal coupling of a signal from adjacent channel into the channel of interest. It is specified separately for coupling from the immediate neighboring channel (near-channel) and for coupling from channel across the package (far-channel). It is usually measured by applying a full-scale signal in the adjacent channel. Cross-talk is the ratio of the power of the coupling signal (as measured at the output of the channel of interest) to the power of the signal applied at the adjacent channel input. It is typically expressed in dBc.



PACKAGING INFORMATION

| Orderable Device | Status (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan | Lead finish/ Ball material | MSL Peak Temp | Op Temp (°C) | Device Marking (4/5) | Samples |
|------------------|---------------|--------------|--------------------|------|----------------|--------------|-------------------------------|---------------------|--------------|-------------------------|---------|
| | (.) | | Ū | | | (=) | (6) | (0) | | (| |
| ADS6128IRGZR | ACTIVE | VQFN | RGZ | 48 | 2500 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6128 | Samples |
| ADS6128IRGZT | ACTIVE | VQFN | RGZ | 48 | 250 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6128 | Samples |
| ADS6129IRGZR | ACTIVE | VQFN | RGZ | 48 | 2500 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6129 | Samples |
| ADS6129IRGZT | ACTIVE | VQFN | RGZ | 48 | 250 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6129 | Samples |
| ADS6148IRGZR | ACTIVE | VQFN | RGZ | 48 | 2500 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6148 | Samples |
| ADS6148IRGZT | ACTIVE | VQFN | RGZ | 48 | 250 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6148 | Samples |
| ADS6149IRGZR | ACTIVE | VQFN | RGZ | 48 | 2500 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6149 | Samples |
| ADS6149IRGZT | ACTIVE | VQFN | RGZ | 48 | 250 | RoHS & Green | NIPDAU | Level-3-260C-168 HR | -40 to 85 | AZ6149 | Samples |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



10-Dec-2020

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer:The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

RGZ 48

7 x 7, 0.5 mm pitch

GENERIC PACKAGE VIEW

VQFN - 1 mm max height

PLASTIC QUADFLAT PACK- NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



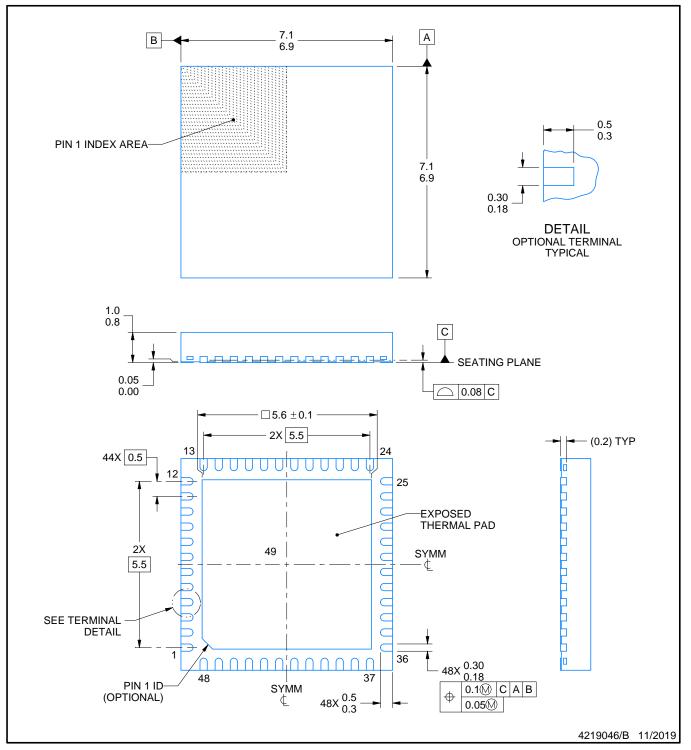
RGZ0048D



PACKAGE OUTLINE

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

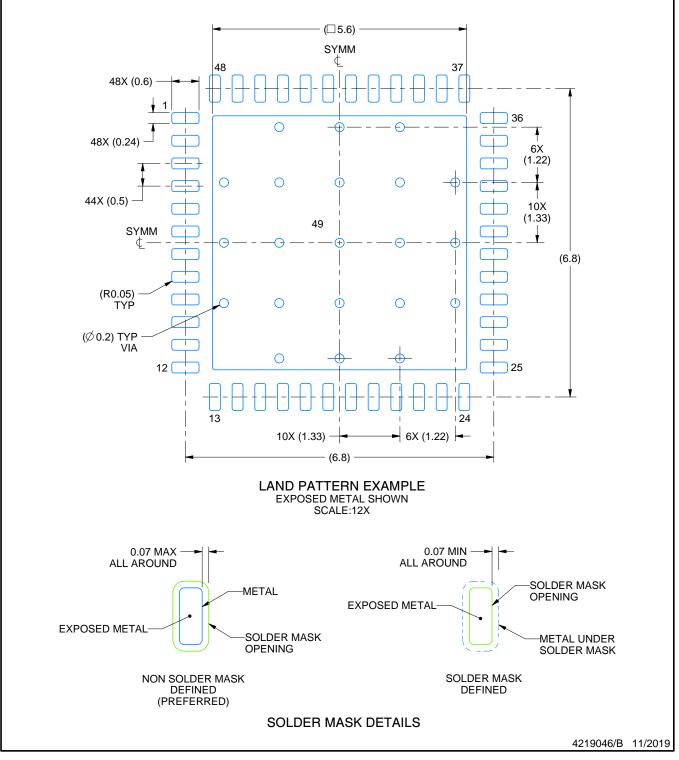


RGZ0048D

EXAMPLE BOARD LAYOUT

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

 This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

 Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

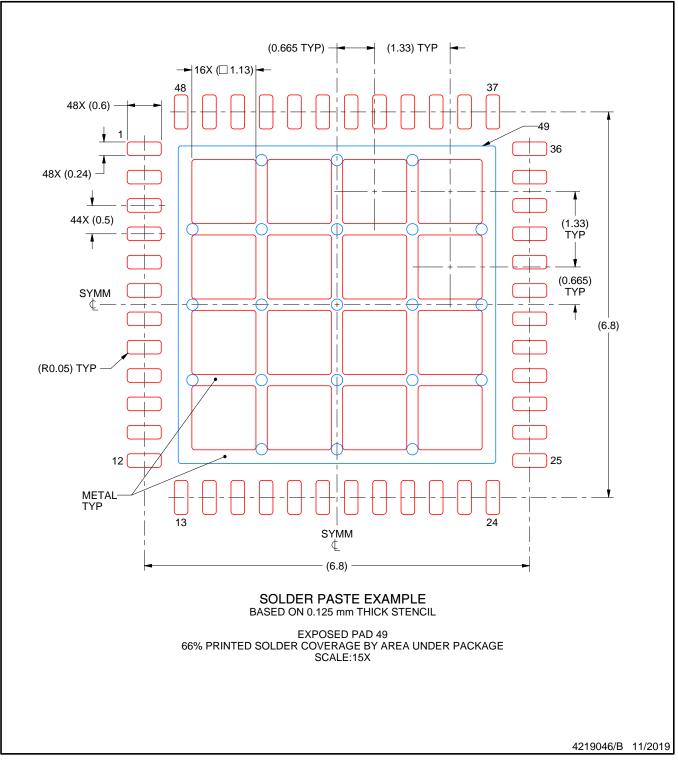


RGZ0048D

EXAMPLE STENCIL DESIGN

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale (https://www.ti.com/legal/termsofsale.html) or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2021, Texas Instruments Incorporated