

EMC OPTIMIZED CAN TRANSCEIVER

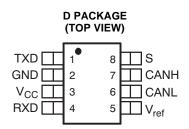
Check for Samples : SN65HVD1050-EP

FEATURES

- Controlled Baseline
 - One Assembly/Test Site, One Fabrication Site
- Enhanced Diminishing Manufacturing Sources (DMS) Support
- Enhanced Product-Change Notification
- Qualification Pedigree (1)
- Improved Replacement for the TJA1050
- High Electromagnetic Immunity (EMI)
- Very Low Electromagnetic Emissions (EME)
- Meets or Exceeds the Requirements of ISO 11898-2
- Bus-Fault Protection of –27 V to 40 V
- Dominant Time-Out Function
- Thermal Shutdown Protection
- Power-Up/Down Glitch-Free Bus Inputs and Outputs
 - High Input Impedance With Low V_{CC}
 - Monotonic Outputs During Power Cycling

APPLICATIONS

- Industrial Automation
 - DeviceNET™ Data Buses (Vendor ID #806)
- SAE J2284 High-Speed CAN for Automotive Applications
- SAE J1939 Standard Data Bus Interface
- ISO 11783 Standard Data Bus Interface
- NMEA 2000 Standard Data Bus Interface
- (1) Component qualification in accordance with JEDEC and industry standards to ensure reliable operation over an extended temperature range. This includes, but is not limited to, Highly Accelerated Stress Test (HAST) or biased 85/85, temperature cycle, autoclave or unbiased HAST, electromigration, bond intermetallic life, and mold compound life. Such qualification testing should not be viewed as justifying use of this component beyond specified performance and environmental limits.



DESCRIPTION/ ORDERING INFORMATION

The SN65HVD1050 meets or exceeds the specifications of the ISO 11898 standard for use in applications employing a controller area network (CAN). The device is also qualified for use in automotive applications in accordance with AEC-Q100. (2)

As a CAN transceiver, this device provides differential transmit capability to the bus and differential receive capability to a CAN controller at signaling rates up to 1 megabit per second (Mbps)⁽³⁾.

Designed for operation in especially harsh environments, the SN65HVD1050 features cross-wire, overvoltage, and loss of ground protection from -27 V to 40 V, overtemperature protection, a -12-V to 12-V common-mode range, and withstands voltage transients from -200 V to 200 V, according to ISO 7637.

Pin 8 provides for two different modes of operation: high-speed or silent mode. The high-speed mode of operation is selected by connecting S (pin 8) to around.

- (2) The device is available with Q100 qualification as the SN65HVD1050Q (Product Preview).
- (3) The signaling rate of a line is the number of voltage transitions that are made, per second, expressed in the units bps (bits per second).

ORDERING INFORMATION

| PART NUMBER | PACKAGE | MARKED AS | ORDERING NUMBER |
|--------------|---------|-----------|-------------------------|
| SN65HVD1050M | SOIC-8 | 1050EP | SN65HVD1050MDREP (reel) |

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Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

DESCRIPTION/ORDERING INFORMATION (CONTINUED)

If a high logic level is applied to the S pin of the SN65HVD1050, the device enters a listen-only silent mode, during which the driver is switched off while the receiver remains fully functional.

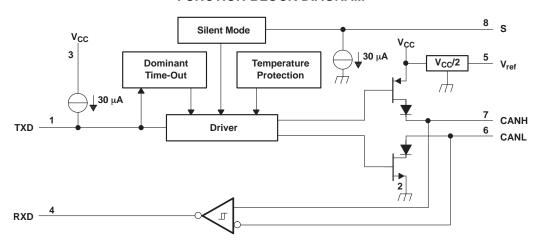
In silent mode, all bus activity is passed by the receiver output to the local protocol controller. When data transmission is required, the local protocol controller reverses this low-current silent mode by placing a logic low on the S pin to resume full operation.

A dominant-time-out circuit in the SN65HVD1050 prevents the driver from blocking network communication with a hardware or software failure. The time-out circuit is triggered by a falling edge on TXD (pin 1). If no rising edge is seen before the time-out constant of the circuit expires, the driver is disabled. The circuit is then reset by the next rising edge on TXD.

V_{ref} (pin 5) is available as a V_{CC}/2 voltage reference.

The SN65HVD1050M is characterized for operation from -55°C to 125°C.

FUNCTION BLOCK DIAGRAM



Absolute Maximum Ratings(1)

| | - | UNIT |
|----------|---|-----------------|
| V_{CC} | Supply voltage ⁽²⁾ | −0.3 V to 7 V |
| | Voltage range at any bus terminal (CANH, CANL, V _{ref}) | –27 V to 40 V |
| Io | Receiver output current | 20 mA |
| V_{I} | Voltage input, transient pulse ⁽³⁾ (CANH, CANL) | –200 V to 200 V |
| V_{I} | Voltage input range (TXD, S) | −0.5 V to 6 V |
| T_{J} | Junction temperature | −55°C to 170°C |

⁽¹⁾ Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

⁽²⁾ All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.

⁽³⁾ Tested in accordance with ISO 7637, test pulses 1, 2, 3a, 3b, 5, 6, and 7



Electrostatic Discharge Protection

over operating free-air temperature range (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | | |
|--|--------------------------|-----------------------|---------|--|
| | Human-Body Model (2) | Bus terminals and GND | ±8 kV | |
| | numan-body woder- | All pins | ±4 kV | |
| Electrostatic discharge ⁽¹⁾ | Charged-Device Model (3) | All pins | ±1.5 kV | |
| | Machine Model | | ±200 V | |

- All typical values at 25°C
- Tested in accordance with JEDEC Standard 22, Test Method A114-A
 Tested in accordance with JEDEC Standard 22, Test Method C101

Recommended Operating Conditions

| | • | | MIN | MAX | UNIT |
|-----------------------------------|-----------------------------|---|------|------|------|
| V _{CC} | Supply voltage | | 4.75 | 5.25 | V |
| V _I or V _{IC} | Voltage at any bus terminal | (separately or common mode) | -12 | 12 | V |
| V _{IH} | High-level input voltage | TXD, S | 2 | 5.25 | V |
| V _{IL} | Low-level input voltage | TXD, S | 0 | 0.8 | V |
| V _{ID} | Differential input voltage | Differential input voltage | | 6 | V |
| | High lovel output ourrent | Driver | -70 | | mA |
| I _{OH} | High-level output current | Receiver | -2 | | MA |
| | Lave lavel avitavit avimont | Driver | | 70 | A |
| I _{OL} | Low-level output current | Receiver | | 2 | mA |
| T _J | Junction temperature | See Thermal Characteristics table, 1-Mbps minimum signaling rate with R_L = 54 Ω | | 150 | °C |

Supply Current

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|------------------------------------|-----------|---|---|-----|-----|-----|------|
| | | Silent mode | S at V _{CC} , V _I = V _{CC} | | 6 | 10 | · |
| I _{CC} 5-V supply current | Dominant | V _I = 0 V, 60-Ω load, S at 0 V | | 50 | 70 | mA | |
| | | Recessive | V _I = V _{CC} , No load, S at 0 V | | 6 | 10 | 1 |

Device Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | MAX | UNIT |
|-----------------------|--|------------------------|-----|-----|------|
| t _{d(LOOP1)} | Total loop delay, driver input to receiver output, recessive to dominant | S at 0 V Saa Figure 0 | 90 | 230 | 5 |
| t _{d(LOOP2)} | Total loop delay, driver input to receiver output, dominant to recessive | S at 0 V, See Figure 9 | 90 | 230 | ns |

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Driver Electrical Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------|--|--|--|--------|------|-------|------|
| V | Due output voltage (deminent) | CANH | $V_I = 0 \text{ V}, \text{ S at } 0 \text{ V}, \text{ R}_L = 60 \Omega,$ | 2.9 | 3.4 | 4.5 | V |
| $V_{O(D)}$ | Bus output voltage (dominant) | CANL | See Figure 1 and Figure 2 | 0.8 | | 1.5 | V |
| V _{O(R)} | Bus output voltage (recessive) | | $V_I = 3 \text{ V, S at } 0 \text{ V, R}_L = 60 \Omega,$ See Figure 1 and Figure 2 | 2 | 2.3 | 3 | ٧ |
| V | Differential output voltage (domin | ant) | $V_I = 0 \text{ V}, R_L = 60 \Omega, S \text{ at } 0 \text{ V},$ See Figure 1, Figure 2, and Figure 3 | 1.5 | | 3 | V |
| $V_{OD(D)}$ | Differential output voltage (domin | iaiii) | $V_I = 0 \text{ V}, R_L = 45 \Omega, \text{ S at } 0 \text{ V},$ See Figure 1, Figure 2, and Figure 3 | 1.4 | | 3 | V |
| $V_{OD(R)}$ | Differential output voltage (reces | sive) | V _I = 3 V, S at 0 V, See Figure 1 and Figure 2 | -0.012 | | 0.012 | V |
| - () | | | V _I = 3 V, S at 0 V, No load | -0.5 | | 0.05 | |
| V _{OC(ss)} | Steady-state common-mode out | out voltage | | 2 | 2.3 | 3 | V |
| $\Delta V_{OC(ss)}$ | Change in steady-state common output voltage | -mode | S at 0 V, See Figure 8 | | 30 | | mV |
| I _{IH} | High-level input current, TXD inp | ut | V _I at V _{CC} | -2 | | 2 | |
| I _{IL} | Low-level input current, TXD inp | ut | V _I at 0 V | -50 | | -10 | μΑ |
| I _{O(off)} | Power-off TXD output current | | V _{CC} at 0 V, TXD at 5 V | | | 1 | |
| | | | V _{CANH} = -12 V, CANL open, See Figure 11 | -105 | -72 | | |
| | Chart aircuit ataady atata autaut | arant | V _{CANH} = 12 V, CANL open, SeeFigure 11 | | 0.36 | 1 | A |
| I _{OS(ss)} | Short-circuit steady-state output | current | V _{CANL} = -12 V, CANH open, See Figure 11 | -1 | -0.5 | | mA |
| | <u> </u> | V _{CANL} = 12 V, CANH open, See Figure 11 | | 71 | 105 | 1 | |
| Co | Output capacitance | | See receiver input capacitance | | | | |

⁽¹⁾ All typical values are at 25°C, with a 5-V supply.

Driver Switching Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT | |
|--------------------|---|---------------------------------|-----|-----|-----|------|--|
| t _{PLH} | Propagation delay time, low- to high-level output | S at 0 V Saa Figure 4 | 25 | 65 | 120 | 20 | |
| t _{PHL} | Propagation delay time, high- to low-level output | S at 0 V, See Figure 4 | 25 | 45 | 120 | ns | |
| t _r | Differential output signal rise time | S at 0 V, See Figure 4 | | 25 | | | |
| t _f | Differential output signal fall time | S at 0 V, See Figure 4 | | 50 | | ns | |
| t _{en} | Enable time from silent mode to dominant | See Figure 7 | | | 1 | μs | |
| t _(dom) | Dominant time-out | ↓V _I , See Figure 10 | 300 | 450 | 700 | μs | |

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Receiver Electrical Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP (1) | MAX | UNIT |
|---------------------|--|--|-----|---------|-----|------|
| V_{IT+} | Positive-going input threshold voltage | S at 0 V, See Table 3 | | 800 | 900 | mV |
| V _{IT} | Negative-going input threshold voltage | S at 0 V, See Table 3 | 500 | 650 | | mV |
| V_{hys} | Hysteresis voltage (V _{IT+} – V _{IT-}) | | 100 | 125 | | mV |
| V_{OH} | High-level output voltage | I _O = -2 mA, See Figure 6 | 4 | 4.6 | | V |
| V _{OL} | Low-level output voltage | I _O = 2 mA, See Figure 6 | | 0.2 | 0.4 | V |
| I _{I(off)} | Power-off bus input current | CANH or CANL = 5 V, Other pin at 0 V, V _{CC} at 0 V, TXD at 0 V | | 165 | 250 | μΑ |
| I _{O(off)} | Power-off RXD leakage current | V _{CC} at 0 V, RXD at 5 V | | | 20 | μΑ |
| Cı | Input capacitance to ground (CANH or CANL) | TXD at 3 V, V _I = 0.4 sin (4E6πt) + 2.5 V | | 13 | | pF |
| C _{ID} | Differential input capacitance | TXD at 3 V, $V_I = 0.4 \sin (4E6\pi t)$ | | 5 | | pF |
| R _{ID} | Differential input resistance | TXD at 3 V, S at 0 V | 30 | | 80 | kΩ |
| R _{IN} | Input resistance (CANH or CANL) | TXD at 3 V, S at 0 V | 15 | 30 | 40 | kΩ |
| R _{I(m)} | Input resistance matching [1 – (R _{IN (CANH)} / R _{IN (CANL)})] ×100% | $V_{O(CANH)} = V_{O(CANL)}$ | -3% | 0% | 3% | |

⁽¹⁾ All typical values are at 25 C with a 5-V supply.

Receiver Switching Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|------------------|---|--|-----|-----|-----|------|
| t _{PLH} | Propagation delay time, low- to high-level output | Cat O Van V | 60 | 100 | 130 | 9 |
| t _{PHL} | Propagation delay time, high- to low-level output | S at 0 V or V _{CC} , See Figure 6 | 45 | 70 | 130 | ns |
| t _r | Output signal rise time | Cat O V an V Can Figure C | | 8 | | 50 |
| t _f | Output signal fall time | S at 0 V or V _{CC} , See Figure 6 | | 8 | | ns |

S-Pin Characteristics

over recommended operating conditions (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------|--------------------------|-----------------|-----|-----|-----|------|
| I_{IH} | High-level input current | S at 2 V | 20 | 40 | 70 | μΑ |
| I_{IL} | Low-level input current | S at 0.8 V | 5 | 20 | 30 | μΑ |

V_{ref}-PIN Characteristics

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------|--------------------------|---------------------------------|---------------------|---------------------|---------------------|------|
| V_{O} | Reference output voltage | –50 μA < I _O < 50 μA | 0.4 V _{CC} | 0.5 V _{CC} | 0.6 V _{CC} | V |

Thermal Characteristics

over operating free-air temperature range (unless otherwise noted)

| | perating free-air temperature range (ur | , | | | | |
|----------------------|---|---|-----|-----|-----|------|
| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
| θ_{JA} | Junction to Air | Low-K thermal resistance ⁽¹⁾ | | | | °C/W |
| UJA | Junction to All | High-K thermal resistance | | 131 | | C/VV |
| θ_{JB} | Junction-to-board thermal resistance | | | 53 | | °C/W |
| θ_{JC} | Junction-to-case thermal resistance | | | 79 | | °C/W |

Product Folder Link(s): SN65HVD1050-EP

(1) Tested in accordance with the Low-K or High-K thermal metric definitions of EIA/JESD51-3 for leaded surface-mount packages



Thermal Characteristics (continued)

over operating free-air temperature range (unless otherwise noted)

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------|------------------------------|--|-----|-----|-----|------|
| _ | Average power discinction | V_{CC} = 5 V, T _J = 27°C, R _L = 60 Ω , S at 0 V, Input to TXD a 500-kHz, 50% duty-cycle square wave, C _L at RXD = 15 pF | | 112 | | ~\^/ |
| P _D | Average power dissipation | V_{CC} = 5.5 V, T _j = 130°C, R _L = 45 Ω , S at 0 V, Input to TXD a 500-kHz, 50% duty-cycle square wave, C _L at RXD = 15 pF | | mW | | |
| | Thermal shutdown temperature | | | 190 | | °C |

FUNCTION TABLES

Table 1. DRIVER

| INP | UTS | OUTF | DUC CTATE | |
|--------------------|------------------|-------------------------|-----------|-----------|
| TXD ⁽¹⁾ | S ⁽¹⁾ | S (1) CANH (1) CANL (1) | | BUS STATE |
| L | L or Open | L or Open H | | Dominant |
| Н | X | Z | Z | Recessive |
| Open | X | Z | Z | Recessive |
| X | Н | Z | Z | Recessive |

(1) H = high level, L = low level, X = irrelevant, Z = high impedance

Table 2. RECEIVER

| DIFFERENTIAL INPUTS V _{ID} = V _(CANH) - V _(CANL) | OUTPUT RXD (1) | BUS STATE |
|---|----------------|-----------|
| V _{ID} ≥ 0.9 V | L | Dominant |
| 0.5 V < V _{ID} < 0.9 V | ? | ? |
| V _{ID} ≤ 0.5 V | Н | Recessive |
| Open | Н | Recessive |

(1) H = high level, L = low level, X = irrelevant, ? = indeterminate



PARAMETER MEASUREMENT INFORMATION

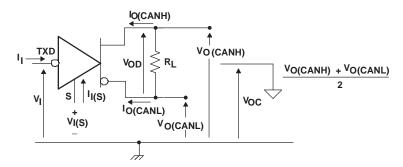


Figure 1. Driver Voltage, Current, and Test Definition

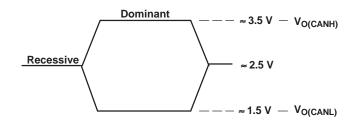


Figure 2. Bus Logic State Voltage Definitions

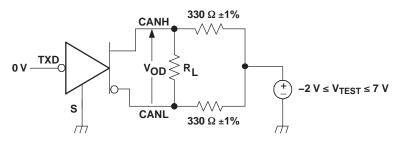


Figure 3. Driver V_{OD} Test Circuit

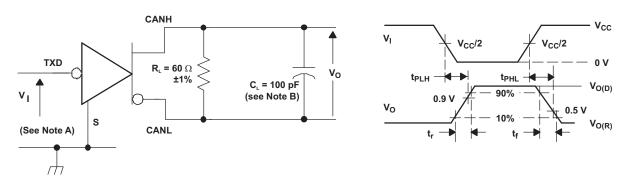


Figure 4. Driver Test Circuit and Voltage Waveforms



PARAMETER MEASUREMENT INFORMATION (continued)

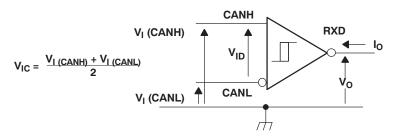
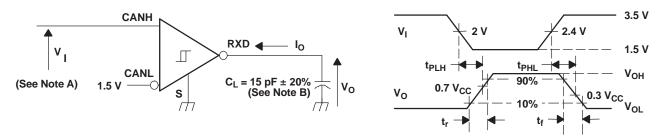


Figure 5. Receiver Voltage and Current Definitions



- A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 125 kHz, 50% duty cycle, $t_f \leq$ 6 ns, $t_f \leq$ 6 ns, $t_G =$ 50 Ω .
- B. C_L includes instrumentation and fixture capacitance within ±20%.

Figure 6. Receiver Test Circuit and Voltage Waveforms

Table 3. Differential Input Voltage Threshold Test

| | OUT | PUT | | | |
|-------------------|-------------------|-----------------|---|-----------------|--|
| V _{CANH} | V _{CANL} | V _{ID} | R | | |
| –11.1 V | –12 V | 900 mV | L | | |
| 12 V | 11.1 V | 900 mV | L | ., | |
| -6 V | –12 V | 6 V | L | V _{OL} | |
| 12 V | 6 V | 6 V | L | | |
| –11.5 V | –12 V | 500 mV | Н | | |
| 12 V | 11.5 V | 500 mV | Н | | |
| –12 V | −6 V | 6 V | Н | V _{OH} | |
| 6 V | 12 V | 6 V | Н | | |
| Open | Open | X | Н | | |



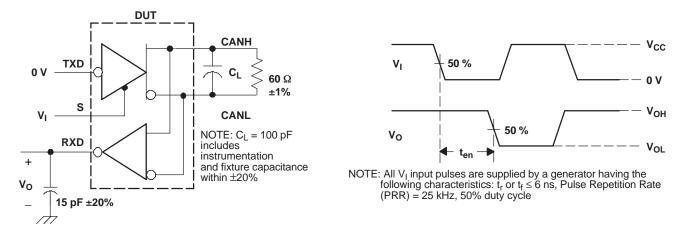
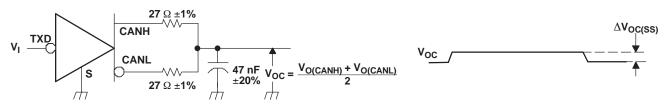
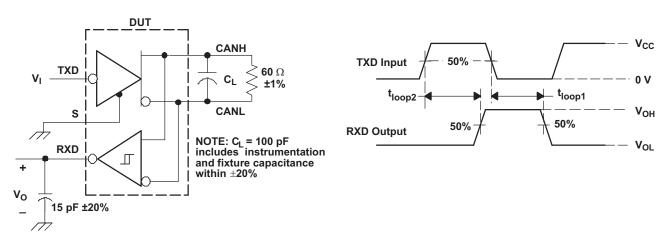


Figure 7. t_{en} Test Circuit and Waveforms



NOTE: All V_1 input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or $t_f \le 6$ ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

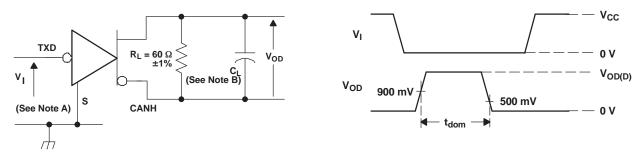
Figure 8. Common-Mode Output Voltage Test and Waveform



A. All V_1 input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or $t_f \le 6$ ns. Pulse Repetition Rate (PRR) = 125 kHz, 50% duty cycle.

Figure 9. t_(LOOP) Test Circuit and Waveform





- A. All V_1 input pulses are from 0 V to V_{CC} and supplied by a generator having the following characteristics: t_r or $t_f \le 6$ ns. Pulse Repetition Rate (PRR) = 500 Hz, 50% duty cycle.
- B. $C_L = 100 \text{ pF}$ includes instrumentation and fixture capacitance within $\pm 20\%$.

Figure 10. Dominant Time-Out Test Circuit and Waveforms

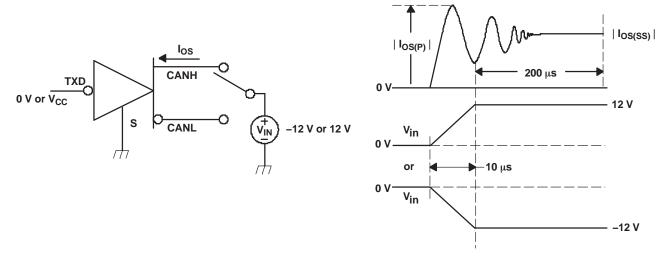


Figure 11. Driver Short-Circuit Current Test and Waveforms



DEVICE INFORMATION

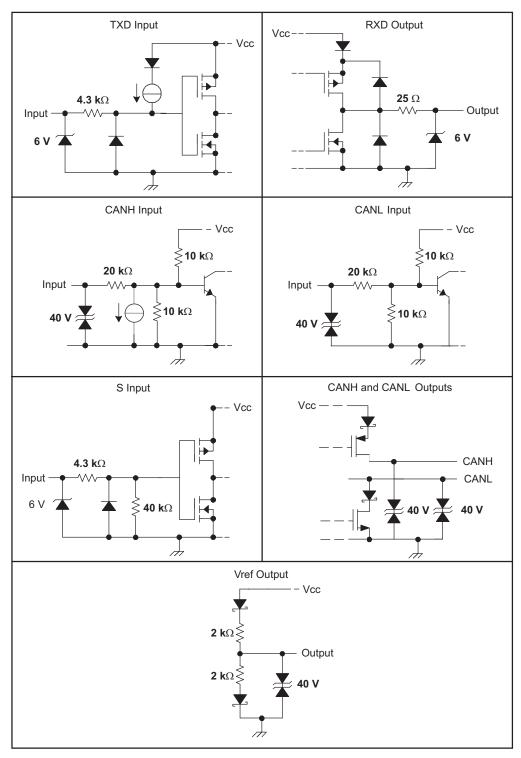
Table 4. Parametric Cross-Reference With the TJA1050

| | R HVD1050 |
|--|--|
| $\begin{array}{c cccc} V_{IL} & Low-level input voltage \\ \hline I_{IH} & High-level input current \\ \hline I_{IL} & Low-level input current \\ \hline \\ \textbf{Bus Section} \\ \hline I_{LI} & Power-off bus input current \\ \hline I_{O(SC)} & Short-circuit output current \\ \hline V_{O(dom)} & Dominant output voltage \\ \hline V_{i(dif)(th)} & Differential input voltage \\ \hline V_{i(dif)(hys)} & Differential input hysteresis \\ \hline \end{array}$ | |
| $\begin{array}{ccc} I_{lH} & \text{High-level input current} \\ I_{lL} & \text{Low-level input current} \\ \hline \textbf{Bus Section} \\ I_{LI} & \text{Power-off bus input current} \\ I_{O(SC)} & \text{Short-circuit output current} \\ V_{O(dom)} & \text{Dominant output voltage} \\ V_{i(dif)(th)} & \text{Differential input voltage} \\ V_{i(dif)(hys)} & \text{Differential input hysteresis} \\ \end{array}$ | Recommended V _{IH} |
| $\begin{array}{lll} I_{IL} & \text{Low-level input current} \\ \hline \textbf{Bus Section} \\ I_{LI} & \text{Power-off bus input current} \\ I_{O(SC)} & \text{Short-circuit output current} \\ V_{O(dom)} & \text{Dominant output voltage} \\ V_{i(dif)(th)} & \text{Differential input voltage} \\ V_{i(dif)(hys)} & \text{Differential input hysteresis} \\ \hline \end{array}$ | Recommended V _{IL} |
| $\begin{tabular}{l l l l l l l l l l l l l l l l l l l $ | Driver I _{IH} |
| $\begin{array}{c c} I_{LI} & Power-off bus input curren \\ I_{O(SC)} & Short-circuit output current \\ V_{O(dom)} & Dominant output voltage \\ V_{i(dif)(th)} & Differential input voltage \\ V_{i(dif)(hys)} & Differential input hysteresis \\ \end{array}$ | Driver I _{IL} |
| $\begin{array}{c} I_{O(SC)} & Short\text{-circuit output current} \\ V_{O(dom)} & Dominant output voltage \\ V_{i(dif)(th)} & Differential input voltage \\ V_{i(dif)(hys)} & Differential input hysteresis \\ \end{array}$ | |
| $\begin{array}{c} V_{O(dom)} & \text{Dominant output voltage} \\ V_{i(dif)(th)} & \text{Differential input voltage} \\ V_{i(dif)(hys)} & \text{Differential input hysteresis} \end{array}$ | t Receiver I _{I(off)} |
| $ \begin{array}{ll} V_{i(dif)(th)} & \text{Differential input voltage} \\ V_{i(dif)(hys)} & \text{Differential input hysteresis} \end{array} $ | Driver I _{OS(SS)} |
| V _{i(dif)(hys)} Differential input hysteresis | Driver V _{O(D)} |
| | Receiver V _{IT} and recommended V _{ID} |
| V _{O(reces)} Recessive output voltage | Receiver V _{hys} |
| · · · · · · · · · · · · · · · · · · · | Driver V _{O(R)} |
| V _{O(dif)(bus)} Differential bus voltage | Driver V _{OD(D)} and V _{OD(R)} |
| R _{i(cm)} CANH, CANL input resista | nce Receiver R _{IN} |
| R _{i(dif)} Differential input resistance | e Receiver R _{ID} |
| R _{i(cm) (m)} Input resistance matching | Receiver R _{I (m)} |
| C _I Input capacitance to groun | d Receiver C _I |
| C _{i(dif)} Differential input capacitan | ce Receiver C _{ID} |
| Receiver Section | |
| I _{OH} High-level output current | Recommended I _{OH} |
| I _{OL} Low-level output current | Recommended I _{OL} |
| V _{ref} -Pin Section | |
| V _{ref} Reference output voltage | Vo |
| Timing Section | |
| t _{d(TXD-BUSon)} Delay TXD to bus active | Driver t _{PLH} |
| t _{d(TXD-BUSoff)} Delay TXD to bus inactive | Driver t _{PHL} |
| t _{d(BUSon-RXD)} Delay bus active to RXD | Receiver t _{PHL} |
| $t_{\text{d(BUSoff-RXD)}}$ Delay bus inactive to RXD | Receiver t _{PLH} |
| $t_{d(TXD\text{-BUSon})} + t_{d(BUSon\text{-RXD})}$ | Device t _{LOOP1} |
| $t_{d(TXD\text{-BUSoff})} + t_{d(BUSoff\text{-RXD})}$ | Device t _{LOOP2} |
| t _{dom(TXD)} Dominant time-out | Driver t _(dom) |
| S-Pin Section | |
| V _{IH} High-level input voltage | Recommended V _{IH} |
| V _{IL} Low-level input voltage | Recommended V _{IL} |
| I _{IH} High-level input current | I _{IH} |
| I _{IL} Low-level input current | I _{IL} |

⁽¹⁾ From TJA1050 Product Specification, Philips Semiconductors, 2002 May 16



Equivalent Input and Output Schematic Diagrams





TYPICAL CHARACTERISTICS

RECESSIVE-TO-DOMINANT LOOP TIME

FREE-AIR TEMPERATURE (Across V_{CC})

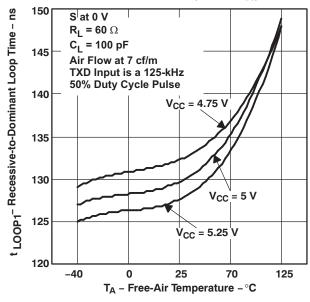


Figure 12.

SUPPLY CURRENT (RMS) vs

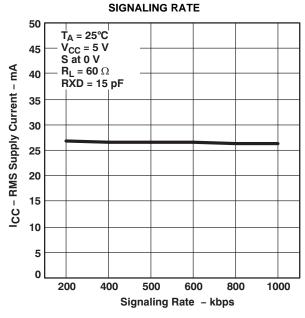


Figure 14.

DOMINANT-TO-RECESSIVE LOOP TIME vs FREE-AIR TEMPERATURE (Across V_{CC})

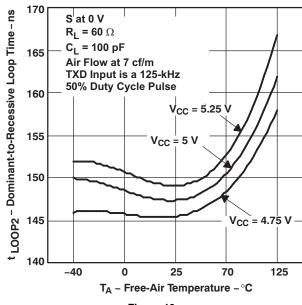


Figure 13.

DRIVER LOW-LEVEL OUTPUT VOLTAGE vs LOW-LEVEL OUTPUT CURRENT

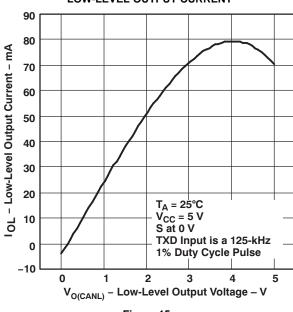


Figure 15.



TYPICAL CHARACTERISTICS (continued)

DRIVER HIGH-LEVEL OUTPUT VOLTAGE VS HIGH-LEVEL OUTPUT CURRENT -80 $T_A = 25^{\circ}C$ $V_{CC} = 5 V$ IOH - High-Level Output Current - mA Sat 0 V -70 TXD Input is a 125-kHz 1% Duty Cycle Pulse -60 -50 -40 -30 -20 -10 -0 0 2 3 4 5 V_{O(CANH)} - High-Level Output Voltage - V

DRIVER OUTPUT CURRENT vs SUPPLY VOLTAGE

Figure 16.

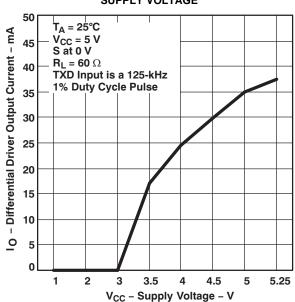
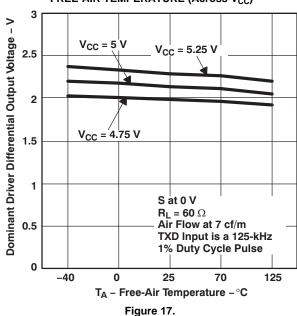


Figure 18.

DRIVER DIFFERENTIAL OUTPUT VOLTAGE vs FREE-AIR TEMPERATURE (Across V_{CC})



RECEIVER OUTPUT VOLTAGE vs DIFFERENTIAL INPUT VOLTAGE

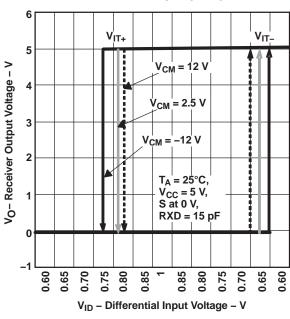
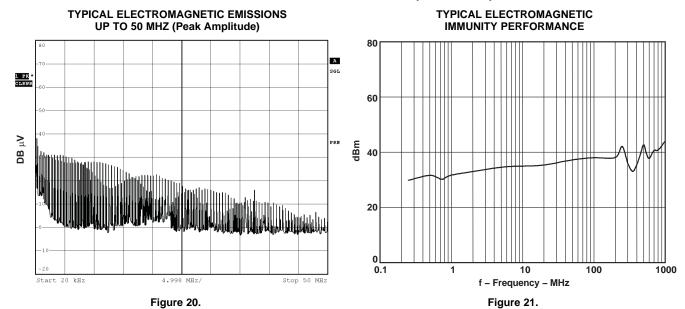


Figure 19.



TYPICAL CHARACTERISTICS (continued)





PACKAGE OPTION ADDENDUM

10-Dec-2020

PACKAGING INFORMATION

| Orderable Device | Status | Package Type | Package Drawing | Pins | Package Qty | Eco Plan | Lead finish/ Ball material | MSL Peak Temp | Op Temp (°C) | Device Marking (4/5) | Samples |
|--------------------|--------|--------------|--------------------|------|----------------|--------------|-------------------------------|--------------------|--------------|-------------------------|---------|
| | | | | | | | (6) | | | | |
| SN65HVD1050MDREP | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -55 to 125 | 1050EP | Samples |
| SN65HVD1050MDREPG4 | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -55 to 125 | 1050EP | Samples |
| V62/07608-01XE | ACTIVE | SOIC | D | 8 | 2500 | RoHS & Green | NIPDAU | Level-1-260C-UNLIM | -55 to 125 | 1050EP | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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PACKAGE OPTION ADDENDUM

10-Dec-2020

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF SN65HVD1050-EP:

• Catalog: SN65HVD1050

• Automotive: SN65HVD1050-Q1

NOTE: Qualified Version Definitions:

- Catalog TI's standard catalog product
- Automotive Q100 devices qualified for high-reliability automotive applications targeting zero defects

PACKAGE MATERIALS INFORMATION

www.ti.com 12-Feb-2019

TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width |
|----|---|
| | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

| Device | Package Type | Package Drawing | | | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|------------------|-----------------|--------------------|---|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| SN65HVD1050MDREP | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |

www.ti.com 12-Feb-2019



*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) | |
|------------------|--------------|-----------------|------|------|-------------|------------|-------------|--|
| SN65HVD1050MDREP | SOIC | D | 8 | 2500 | 350.0 | 350.0 | 43.0 | |



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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