# 500kHz, 12-Bit, 6-Channel Simultaneous Sampling ANALOG-TO-DIGITAL CONVERTER 

## FEATURES

- 6 Simultaneous Sampling Channels
- Fully Differential Inputs
- $2 \mu \mathrm{~s}$ Total Throughput per Channel
- No Missing Codes
- Parallel Interface
- 1 MHz Effective Sampling Rate
- Low Power: 50mW
- 6X FIFO


## APPLICATIONS

- Motor Control
- Multi-Axis Positioning Systems
- 3-Phase Power Control


## DESCRIPTION

The ADS7864 is a dual 12-bit, 500 kHz analog-to-digital (A/D) converter with 6 fully differential input channels grouped into three pairs for high speed simultaneous signal acquisition. Inputs to the sample-and-hold amplifiers are fully differential and are maintained differential to the input of the $A / D$ converter. This provides excellent common-mode rejection of 80 dB at 50 kHz which is important in high noise environments.
The ADS7864 offers a parallel interface and control inputs to minimize software overhead. The output data for each channel is available as a 16-bit word (address and data). The ADS7864 is offered in a TQFP-48 package and is fully specified over the $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ operating range.


This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.
ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## ORDERING INFORMATION ${ }^{(1)}$

| PRODUCT | MINIMUM <br> RELATIVE <br> ACCURACY (LSB) | MAXIMUM <br> GAIN <br> ERROR (\%) | PACKAGE- <br> LEAD | PACKAGE <br> DESIGNATOR | SPECIFIED <br> TEMPERATURE <br> RANGE | ORDERING <br> NUMBER |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS7864Y | $\pm 2$ | $\pm 0.75$ | TQFP-48 | PFB | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | ADS7864Y |
| QUANTITY |  |  |  |  |  |  |

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

## ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted)

|  | ADS7864 | UNIT |
| :--- | :---: | :---: |
| Analog Inputs to AGND: Any Channel Input | -0.3 to $\left(+\mathrm{V}_{\mathrm{D}}+0.3\right)$ | V |
| Analog Inputs to AGND: REF | V ( | -0.3 to $\left(+\mathrm{V}_{\mathrm{D}}+0.3\right)$ |
| Digital Inputs to DGND | -0.3 to $\left(+\mathrm{V}_{\mathrm{D}}+0.3\right)$ | V |
| Ground Voltage Differences: AGND, DGND | $\pm 0.3$ | V |
| Ground Voltage Differences: $+\mathrm{V}_{\mathrm{D}}$ to AGND | -0.3 to +6 | V |
| Power Supply Difference: $+\mathrm{V}_{\mathrm{A},}+\mathrm{V}_{\mathrm{D}}$ | $\pm 0.3$ | V |
| Power Dissipation | 325 | V |
| Maximum Junction Temperature | +150 | mW |
| Operating Temperature Range | -40 to +85 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |
| Lead Temperature (soldering, 10 s ) | +300 | ${ }^{\circ} \mathrm{C}$ |

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BASIC OPERATION


## ELECTRICAL CHARACTERISTICS

All specifications $T_{\text {MIN }}$ to $T_{\text {MAX }},+V_{A}=+V_{D}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=$ internal +2.5 V and $\mathrm{f}_{\mathrm{CLK}}=8 \mathrm{MHz}, \mathrm{f}_{\text {SAMPLE }}=500 \mathrm{kHz}$ (unless otherwise noted).

| PARAMETER | TEST CONDITIONS | ADS7864Y |  |  | ADS7864YB |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | TYP | MAX | MIN | TYP | MAX |  |
| Resolution |  |  |  | 12 |  |  | 12 | Bits |
| Analog Input |  |  |  |  |  |  |  |  |
| Input Voltage Range-Bipolar | $\mathrm{V}_{\text {CENTER }}=+2.5 \mathrm{~V}$ | $-\mathrm{V}_{\text {REF }}$ |  | $+\mathrm{V}_{\text {REF }}$ | $-\mathrm{V}_{\text {REF }}$ |  | $+\mathrm{V}_{\text {REF }}$ | V |
| Absolute Input Range | $+\mathrm{IN}$ | -0.3 |  | $+\mathrm{V}_{\mathrm{A}}+0.3$ |  |  |  | V |
|  | -IN | -0.3 |  | $+\mathrm{V}_{\mathrm{A}}+0.3$ |  |  |  | V |
| Input Capacitance |  |  | 15 |  |  | 15 |  | pF |
| Input Leakage Current | CLK = GND |  | $\pm 1$ |  |  | $\pm 1$ |  | $\mu \mathrm{A}$ |
| System Performance |  |  |  |  |  |  |  |  |
| No Missing Codes |  | 12 |  |  | 12 |  |  | Bits |
| Integral Linearity |  |  | $\pm 0.75$ | 2 |  | $\pm 0.5$ | $\pm 1$ | LSB |
| Integral Linearity Match |  |  | 0.5 |  |  | 0.5 |  | LSB |
| Differential Linearity |  | -0.9 | $\pm 0.6$ |  | -0.9 | $\pm 0.4$ |  | LSB |
| Bipolar Offset Error | Referenced to REF ${ }_{\text {IN }}$ |  | $\pm 0.75$ | $\pm 4$ |  | $\pm 0.5$ | $\pm 3$ | LSB |
| Bipolar Offset Error Match |  |  |  | 3 |  |  | 3 | LSB |
| Positive Gain Error | Referenced to REF ${ }_{\text {IN }}$ |  | $\pm 0.15$ | $\pm 0.75$ |  | $\pm 0.1$ | $\pm 0.5$ | \% of FSR |
| Positive Gain Error Match |  |  |  | 3 |  |  | 3 | LSB |
| Negative Gain Error | Referenced to REFIN |  | $\pm 0.15$ | $\pm 0.75$ |  | $\pm 0.1$ | $\pm 0.5$ | \% of FSR |
| Negative Gain Error Match |  |  |  | 3 |  |  | 3 | LSB |
| Common-Mode Rejection Ratio | At DC |  | 84 |  |  | 84 |  | dB |
|  | $\mathrm{V}_{\text {IN }}= \pm 1.25 \mathrm{~V}_{\mathrm{PP}}$ at 50 kHz |  | 80 |  |  | 80 |  | dB |
| Noise |  |  | 120 |  |  | 120 |  | $\mu \mathrm{V}_{\text {RMS }}$ |
| Power Supply Rejection Ratio |  |  | 0.3 | 2 |  | 0.3 | 2 | LSB |
| Sampling Dynamics |  |  |  |  |  |  |  |  |
| Conversion Time per A/D |  |  | 1.75 |  |  | 1.75 |  | $\mu \mathrm{s}$ |
| Acquisition Time |  |  | 0.25 |  |  | 0.25 |  | $\mu \mathrm{s}$ |
| Throughput Rate |  | 500 |  |  | 500 |  |  | kHz |
| Aperture Delay |  |  | 3.5 |  |  | 3.5 |  | ns |
| Aperture Delay Matching |  |  | 100 |  |  | 100 |  | ps |
| Aperture Jitter |  |  | 50 |  |  | 50 |  | ps |
| Small-Signal Bandwidth |  |  | 40 |  |  | 40 |  | MHz |
| Dynamic Characteristics |  |  |  |  |  |  |  |  |
| Total Harmonic Distortion | $\mathrm{V}_{\text {IN }}= \pm 2.5 \mathrm{~V}_{\mathrm{PP}}$ at 100 kHz |  | -75 |  |  | -75 |  | dB |
| SINAD | $\mathrm{V}_{\text {IN }}= \pm 2.5 \mathrm{~V}_{\mathrm{PP}}$ at 100 kHz |  | 71 |  |  | 71 |  | dB |
| Spurious Free Dynamic Range | $\mathrm{V}_{\text {IN }}= \pm 2.5 \mathrm{~V}_{\mathrm{PP}}$ at 100 kHz |  | 78 |  |  | 78 |  | dB |
| Channel-to-Channel Isolation | $\mathrm{V}_{\text {IN }}= \pm 2.5 \mathrm{~V}_{\mathrm{PP}}$ at 50 kHz |  | -76 |  |  | -76 |  | dB |
| Voltage Reference |  |  |  |  |  |  |  |  |
| Internal Reference Voltage |  | 2.475 | 2.5 | 2.525 | 2.475 | 2.5 | 2.525 | V |
| Internal Drift |  |  | 10 |  |  | 10 |  | $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |
| Internal Noise |  |  | 50 |  |  | 50 |  | $\mu \mathrm{V}_{\mathrm{PP}}$ |
| Internal Source Current |  |  | 2 |  |  | 2 |  | mA |
| Internal Load Rejection |  |  | 0.005 |  |  | 0.005 |  | $\mathrm{mV} / \mu \mathrm{A}$ |
| Internal PSRR |  |  | 80 |  |  | 80 |  | dB |
| External Reference Voltage Range |  | 1.2 | 2.5 | 2.6 | 1.2 | 2.5 | 2.6 | V |
| Input Current |  |  |  | 100 |  |  | 100 | $\mu \mathrm{A}$ |
| Input Capacitance |  |  | 5 |  |  | 5 |  | pF |

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## ELECTRICAL CHARACTERISTICS (continued)

All specifications $T_{\text {MIN }}$ to $T_{\text {MAX }},+V_{A}=+V_{D}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=$ internal +2.5 V and $\mathrm{f}_{\text {CLK }}=8 \mathrm{MHz}, \mathrm{f}_{\text {SAMPLE }}=500 \mathrm{kHz}$ (unless otherwise noted).

| PARAMETER | TEST CONDITIONS | ADS7864Y |  | ADS7864YB |  |  | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | TYP MAX | MIN | TYP | MAX |  |
| Digital Input/Output |  |  |  |  |  |  |  |
| Logic Family |  | CMOS |  | CMOS |  |  |  |
| Logic Levels: |  |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{IH}}$ | $\mathrm{I}_{\mathrm{H}}=+5 \mu \mathrm{~A}$ | 3.0 | $+\mathrm{V}_{\mathrm{D}}+0.3$ | 3.0 |  | $+\mathrm{V}_{\mathrm{D}}+0.3$ | V |
| $\mathrm{V}_{\text {IL }}$ | $\mathrm{I}_{\mathrm{LL}}=+5 \mu \mathrm{~A}$ | -0.3 | 0.8 | -0.3 |  | 0.8 | V |
| $\mathrm{V}_{\mathrm{OH}}$ | $\mathrm{I}_{\mathrm{OH}}=-500 \mu \mathrm{~A}$ | 3.5 |  | 3.5 |  |  | V |
| $\mathrm{V}_{\text {OL }}$ | $\mathrm{l}_{\mathrm{OL}}=-500 \mu \mathrm{~A}$ |  | 0.4 |  |  | 0.4 | V |
| External Clock |  | 0.2 | 8 | 0.2 |  | 8 | MHz |
| Data Format |  | Binary Two's Complement |  | Binary Two's Complement |  |  |  |
| Power-Supply Requirements |  |  |  |  |  |  |  |
| Power Supply Voltage, $+\mathrm{V}_{\mathrm{A}}$, $+\mathrm{V}_{\mathrm{D}}$ |  | 4.75 | $5 \quad 5.25$ | 4.75 | 5 | 5.25 | V |
| Quiescent Current, $+\mathrm{V}_{\mathrm{A}},+\mathrm{V}_{\mathrm{D}}$ |  |  | 10 |  |  | 10 | mA |
| Power Dissipation |  |  | 50 |  |  | 50 | mW |

## PIN CONFIGURATIONS



PIN DESCRIPTIONS

| PIN | NAME | DESCRIPTION |
| :---: | :---: | :---: |
| 1 | $+\mathrm{V}_{\text {A }}$ | Analog Power Supply. Normally +5V. |
| 2 | AGND | Analog Ground |
| 3 | DB15 | Data Valid Output: '1' for data valid; '0' for invalid data. |
| 4 | DB14 | Channel Address Output Pin (see Table_2) |
| 5 | DB13 | Channel Address Output Pin (see Table_2) |
| 6 | DB12 | Channel Address Output Pin (see Table_2) |
| 7 | DB11 | Data Bit 11 - MSB |
| 8 | DB10 | Data Bit 10 |
| 9 | DB9 | Data Bit 9 |
| 10 | DB8 | Data Bit 8 |
| 11 | DB7 | Data Bit 7 |
| 12 | DB6 | Data Bit 6 |
| 13 | DB5 | Data Bit 5 |
| 14 | DB4 | Data Bit 4 |
| 15 | DB3 | Data Bit 3 |
| 16 | DB2 | Data Bit 2 |
| 17 | DB1 | Data Bit 1 |
| 18 | DB0 | Data Bit 0 - LSB |
| 19 | BUSY | Low when a conversion is in progress. |
| 20 | DGND | Digital Ground |
| 21 | $+\mathrm{V}_{\mathrm{D}}$ | Digital Power Supply, +5VDC |
| 22 | CLOCK | An external clock must be applied to the CLOCK input. |
| 23 | RD | RD Input. Enables the parallel output when used in conjunction with chip select. |
| 24 | $\overline{C S}$ | Chip Select |
| 25 | HOLDC | Places Channels C0 and C1 in hold mode. |
| 26 | HOLDB | Places Channels B0 and B1 in hold mode. |
| 27 | HOLDA | Places Channels A0 and A1 in hold mode. |
| 28 | BYTE | $2 \times 8$ Output Capability. Active high. |
| 29 | A2 | A2 Address/Mode Select Pin (see Table_31). |
| 30 | A1 | A1 Address/Mode Select Pin (see Table 31). |
| 31 | A0 | A0 Address/Mode Select Pin (see Table_3). |
| 32 | RESET | Reset Pin |
| 33 | REFOUT | Reference Out |
| 34 | REFIN | Reference In |
| 35 | AGND | Analog Ground |
| 36 | $+\mathrm{V}_{\mathrm{A}}$ | Analog Power Supply. Normally +5V. |
| 37 | CH A1+ | Noninverting Input Channel A1 |
| 38 | CH A1- | Inverting Input Channel A1 |
| 39 | CH B1+ | Noninverting Input Channel B1 |
| 40 | CH B1- | Inverting Input Channel B1 |
| 41 | CH C1+ | Noninverting Input Channel C1 |
| 42 | CH C1- | Inverting Input Channel C1 |
| 43 | CH C0- | Inverting Input Channel C0 |
| 44 | $\mathrm{CH} \mathrm{CO}+$ | Noninverting Input Channel C0 |
| 45 | CH B0- | Inverting Input Channel B0 |
| 46 | CH B0+ | Noninverting Input Channel B0 |
| 47 | $\mathrm{CH} \mathrm{AO}-$ | Inverting Input Channel A0 |
| 48 | CH A0+ | Noninverting Input Channel A0 |

## TYPICAL CHARACTERISTICS

All specifications $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{A}}=+\mathrm{V}_{\mathrm{D}}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=$ internal +2.5 V and $\mathrm{f}_{\mathrm{CLK}}=8 \mathrm{MHz}, \mathrm{f}_{\text {SAMPLE }}=500 \mathrm{kHz}$ (unless otherwise noted)

FREQUENCY SPECTRUM
(4096 Point FFT; $\mathrm{f}_{\mathrm{IN}}=99.9 \mathrm{kHz},-0.2 \mathrm{~dB}$ )


Figure 1.
SIGNAL-TO-NOISE RATIO AND SIGNAL-TO-(NOISE+DISTORTION) vs INPUT FREQUENCY


Figure 3.

FREQUENCY SPECTRUM
(4096 Point FFT; $\mathrm{f}_{\mathrm{IN}}=199.9 \mathrm{kHz},-\mathbf{0 . 2 d B}$ )


Figure 2.
CHANGE IN SIGNAL-TO-NOISE RATIO AND SIGNAL-TO-(NOISE+DISTORTION) vs TEMPERATURE


Figure 4.

## TYPICAL CHARACTERISTICS (continued)

All specifications $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{A}}=+\mathrm{V}_{\mathrm{D}}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=$ internal +2.5 V and $\mathrm{f}_{\text {CLK }}=8 \mathrm{MHz}, \mathrm{f}_{\text {SAMPLE }}=500 \mathrm{kHz}$ (unless otherwise noted)


Figure 5.
NEGATIVE GAIN MATCH vs TEMPERATURE (Maximum Deviation for All Six Channels)


Figure 7.


Figure 9.

POSITIVE GAIN MATCH vs TEMPERATURE (Maximum Deviation for All Six Channels)


Figure 6.

REFERENCE VOLTAGE vs TEMPERATURE


Figure 8.
BIPOLAR ZERO MATCH vs TEMPERATURE


Figure 10.

## TYPICAL CHARACTERISTICS (continued)

All specifications $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{A}}=+\mathrm{V}_{\mathrm{D}}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=$ internal +2.5 V and $\mathrm{f}_{\text {CLK }}=8 \mathrm{MHz}, \mathrm{f}_{\text {SAMPLE }}=500 \mathrm{kHz}$ (unless otherwise noted)


Figure 11.
INTEGRAL LINEARITY ERROR MATCH
vs TEMPERATURE
Channel AO/Channel C1
(Different Converter, Different Channels)


Figure 13.

INTEGRAL LINEARITY ERROR vs CODE


Figure 12.

INTEGRAL LINEARITY ERROR vs TEMPERATURE


Figure 14.

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## TYPICAL CHARACTERISTICS (continued)

All specifications $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C},+\mathrm{V}_{\mathrm{A}}=+\mathrm{V}_{\mathrm{D}}=+5 \mathrm{~V}, \mathrm{~V}_{\text {REF }}=$ internal +2.5 V and $\mathrm{f}_{\text {CLK }}=8 \mathrm{MHz}, \mathrm{f}_{\text {SAMPLE }}=500 \mathrm{kHz}$ (unless otherwise noted)


Figure 15.
INTEGRAL LINEARITY ERROR MATCH vs CODE Channel A0/Channel B1
(Different Converter, Different Channels)


Figure 17.

INTEGRAL LINEARITY ERROR MATCH vs CODE Channel A0/Channel BO (Same Converter, Different Channels)


Figure 16.


Figure 18.
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## APPLICATIONS INFORMATION

## INTRODUCTION

The ADS7864 is a high speed, low power, dual 12-bit analog-to-digital converter (ADC) that operates from a single +5 V supply. The input channels are fully differential with a typical common-mode rejection of 80 dB . The part contains dual $2 \mu \mathrm{~s}$ successive approximation ADCs, six differential sample-and-hold amplifiers, an internal +2.5 V reference with $\mathrm{REF}_{\text {IN }}$ and REF ${ }_{\text {out }}$ pins and a high speed parallel interface. There are six analog inputs that are grouped into three channels ( $\mathrm{A}, \mathrm{B}$ and C ). Each A/D converter has three inputs (A0/A1, B0/B1 and C0/C1) that can be sampled and converted simultaneously, thus preserving the relative phase information of the signals on both analog inputs. Each pair of channels has a hold signal (HOLDA, HOLDB, HOLDC) to allow simultaneous sampling on all six channels. The part accepts an analog input voltage in the range of $-\mathrm{V}_{\text {REF }}$ to $+\mathrm{V}_{\text {REF }}$, centered around the internal +2.5 V reference. The part will also accept bipolar input ranges when a level shift circuit is used at the front end (see Figure 25).
A conversion is initiated on the ADS7864 by bringing the HOLDX pin low for a minimum of 15 ns . HOLDX low places both sample-and-hold amplifiers of the X channels in the hold state simultaneously and the conversion process is started on both channels. The BUSY output will then go low and remain low for the duration of the conversion cycle. The data can be read from the parallel output bus following the conversion by bringing both $\overline{R D}$ and $\overline{C S}$ low.
Conversion time for the ADS7864 is $1.75 \mu \mathrm{~s}$ when an 8 MHz external clock is used. The corresponding acquisition time is $0.25 \mu \mathrm{~s}$. To achieve maximum output rate $(500 \mathrm{kHz})$, the read function can be performed during at the start of the next conversion.
NOTE: This mode of operation is described in more detail in the Timing and Control section of this data sheet.

## SAMPLE-AND-HOLD SECTION

The sample-and-hold amplifiers on the ADS7864 allow the ADCs to accurately convert an input sine wave of full-scale amplitude to 12 -bit accuracy. The input bandwidth of the sample-and-hold is greater than the Nyquist rate of the ADC (Nyquist equals one-half of the sampling rate) even when the ADC is operated at its maximum throughput rate of 500 kHz . The typical small-signal bandwidth of the sample-and-hold amplifiers is 40 MHz .
Typical aperture delay time, or the time it takes for the ADS7864 to switch from the sample to the hold mode following the negative edge of the HOLDX
signal, is 5 ns . The average delta of repeated aperture delay values is typically 50ps (also known as aperture jitter). These specifications reflect the ability of the ADS7864 to capture AC input signals accurately at the exact same moment in time.

## REFERENCE

Under normal operation, the REF ${ }_{\text {OUt }}$ pin (pin 2) should be directly connected to the REF ${ }_{\text {IN }}$ pin (pin 1) to provide an internal +2.5 V reference to the ADS7864. The ADS7864 can operate, however, with an external reference in the range of 1.2 V to 2.6 V for a corresponding full-scale range of 2.4 V to 5.2 V .
The internal reference of the ADS7864 is double-buffered. If the internal reference is used to drive an external load, a buffer is provided between the reference and the load applied to pin 33 (the internal reference can typically source 2 mA of cur-rent-load capacitance should not exceed 100 pF ). If an external reference is used, the second buffer provides isolation between the external reference and the CDAC. This buffer is also used to recharge all of the capacitors of both CDACs during conversion.

## ANALOG INPUT

The analog input is bipolar and fully differential. There are two general methods of driving the analog input of the ADS7864: single-ended or differential (see Figure 19 and Figure 2d). When the input is single-ended, the -IN input is held at the com-mon-mode voltage. The +IN input swings around the same common voltage and the peak-to-peak amplitude is the (common-mode $+\mathrm{V}_{\text {REF }}$ ) and the (common-mode $-\mathrm{V}_{\text {REF }}$ ). The value of $\mathrm{V}_{\text {REF }}$ determines the range over which the common-mode voltage may vary (see Figure 211).


Figure 19. Methods of Driving the ADS7864 Single-Ended or Differential


NOTES: Common-Mode Voltage (Differential Mode) $=\frac{(\mathrm{IN}+)-(\mathrm{IN}-)}{2}$, Common-Mode Voltage (Single-Ended Mode) $=\mathrm{IN}-$.
The maximum differential voltage between $+\mathbb{N}$ and $-\mathbb{N}$ of the ADS7864 is $\mathrm{V}_{\text {REF }}$. See Figures 21 and 22 for a further explanation of the common voltage range for single-ended and differential inputs.

Figure 20. Using the ADS7864 in the Single-Ended and Differential Input Modes


Figure 21. Single-Ended Input: Common-Mode Voltage Range vs $\mathrm{V}_{\mathrm{REF}}$


Figure 22. Differential Input: Common-Mode
Voltage Range vs $\mathrm{V}_{\mathrm{REF}}$

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When the input is differential, the amplitude of the input is the difference between the +IN and -IN input, or: $(+\mathbb{N})-(-I N)$. The peak-to-peak amplitude of each input is $\pm 1 / 2 \mathrm{~V}_{\text {REF }}$ around this common voltage. However, since the inputs are $180^{\circ}$ out of phase, the peak-to-peak amplitude of the differential voltage is $+\mathrm{V}_{\text {REF }}$ to $-\mathrm{V}_{\text {REF }}$. The value of $\mathrm{V}_{\text {REF }}$ also determines the range of the voltage that may be common to both inputs (see Eigure 22).

In each case, care should be taken to ensure that the output impedance of the sources driving the +IN and -IN inputs are matched. Otherwise, this may result in offset error, which will change with both temperature and input voltage.
The input current on the analog inputs depend on a number of factors: sample rate, input voltage, and source impedance. Essentially, the current into the ADS7864 charges the internal capacitor array during the sampling period. After this capacitance has been fully charged, there is no further input current. The source of the analog input voltage must be able to charge the input capacitance ( 15 pF ) to a 12 -bit settling level within two clock cycles. When the converter goes into the hold mode, the input impedance is greater than $1 \mathrm{G} \Omega$.

Care must be taken regarding the absolute analog input voltage. The +IN and -IN inputs should always remain within the range of GND -300 mV to $\mathrm{V}_{\mathrm{DD}}+$ 300 mV .

## TRANSITION NOISE

Figure 23 shows a histogram plot for the ADS7864 following 8,000 conversions of a DC input. The DC input was set at output code 2046. All but one of the conversions had an output code result of 2046 (one of the conversions resulted in an output of 2047). The histogram reveals the excellent noise performance of the ADS7864.


Figure 23. Histogram of 8,000 Conversions of a DC Input


Voltage Waveforms for DATA Rise and Fall Times $t_{R}$, and $t_{F}$.

Figure 24. Test Circuits for Timing Specifications

Hold signals. The FIFO mode will allow the six registers to be used by a single channel pair, and therefore three locations for CH XO and three locations for CH X1 can be acquired before they are read from the part.

## EXPLANATION OF CLOCK, RESET AND BUSY PINS

CLOCK-An external clock has to be provided for the ADS7864. The maximum clock frequency is 8 MHz . The minimum clock cycle is 125 ns (see Fiqure 26. $\mathrm{t}_{5}$ ), and the clock has to remain high (see Eigure 26, $\mathrm{t}_{6}$ ) or low (see Eigure 26, $\mathrm{t}_{7}$ ) for at least 40 ns.


Figure 26. Start of the Conversion
RESET—Bringing reset low will reset the ADS7864. It will clear all the output registers, stop any actual conversions and will close the sampling switches. Reset has to stay low for at least 20ns (see Figure 26, $t_{8}$ ). The reset should be back high for at least 20ns (see Figure 26, $\mathrm{t}_{9}$ ), before starting the next conversion (negative hold edge).

BUSY-Busy goes low when the internal A/D converters start a new conversion. It stays low as long as the conversion is in progress (see Figure 27, 13 clock-cycles, $\mathrm{t}_{10}$ ) and rises again after the data is latched to the output register. With Busy going high, the new data can be read. It takes at least 16 clock cycles (see Figure 27, $t_{11}$ ) to complete conversion.

## START OF A CONVERSION

By bringing one or all of the HOLDX signals low, the input data of the corresponding channel X is immediately placed in the hold mode (5ns). The conversion of this channel $X$ follows as soon as the A/D converter is available for the particular channel. If

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other channels are already in the hold mode but not converted, then the conversion of channel X is put in the queue until the previous conversion has been completed. If more than one channel goes into hold mode within one clock cycle, then channel A will be converted first if HOLDA is one of the triggered hold signals. Next, channel B will be converted, and last, channel C . If it is important to detect a hold command during a certain clock cycle, then the falling edge of the hold signal has to occur at least 10 ns before the falling edge of the clock. (see Figure 26, $t_{1}$ ). The hold signal can remain low without initiating a new conversion. The hold signal has to be high for at least 15 ns (see Figure 26, $\mathrm{t}_{2}$ ) before it is brought low again and hold has to stay low for at least 20ns (see Figure_26, $t_{3}$ ).
In the example of Figure 26, the signal HOLDB goes low first and channel B0 and B1 will be converted first. The falling edges of HOLDA and HOLDC occur within the same clock cycle. Therefore, the channels A0 and A1 will be converted as soon as the channels B0 and B1 are finished (plus acquisition time). When the A-channels are finished, the C-channels will be converted. The second HOLDA signal is ignored, as the A-channels are not converted at this point in time.

Once a particular hold signal goes low, further impulses of this hold signal are ignored until the conversion is finished or the part is reset. When the conversion is finished (BUSY signal goes high), the sampling switches will close and sample the selected channel. The start of the next conversion must be delayed to allow the input capacitor of the ADS7864 to be fully charged. This delay time depends on the driving amplifier, but should be at least 175ns (see Eiqure 27, $\mathrm{t}_{4}$ ).

The ADS7864 can also convert one channel continuously, as it is shown in Eigure 27 with channel B. Therefore, HOLDA and HOLDC are kept high all the time. To gain acquisition time, the falling edge of HOLDB takes place just before the falling edge of clock. One conversion requires 16 clock cycles. Here, data is read after the next conversion is initiated by HOLDB. To read data from channel B, A1 is set high and A2 is low. As A0 is low during the first reading ( $\mathrm{A} 2 \mathrm{~A} 1 \mathrm{~A} 0=010$ ) data B 0 is put to the output. Before the second $\overline{\mathrm{RD}}, \mathrm{A} 0$ switches high (A2 A1 A0 $=011$ ) so data from channel B1 is read.

Table 1. Timing Specifications

| SYMBOL | DESCRIPTION | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{1}$ | HOLD ( $\mathrm{A}, \mathrm{B}, \mathrm{C}$ ) before falling edge of clock | 10 |  |  | ns |
| $\mathrm{t}_{2}$ | HOLD high time to be recognized again | 15 |  |  | ns |
| $\mathrm{t}_{3}$ | HOLD low time | 20 |  |  | ns |
| $\mathrm{t}_{4}$ | Input capacitor charge time | 175 |  |  | ns |
| $t_{5}$ | Clock period | 125 |  |  | ns |
| $\mathrm{t}_{6}$ | Clock high time | 40 |  |  | ns |
| $\mathrm{t}_{7}$ | Clock low time | 40 |  |  | ns |
| $\mathrm{t}_{8}$ | Reset pulse width | 20 |  |  | ns |
| $\mathrm{t}_{9}$ | First hold after reset | 20 |  |  | ns |
| $\mathrm{t}_{10}$ | Conversion time |  | $12.5 \times \mathrm{t}_{5}$ |  | ns |
| $\mathrm{t}_{11}$ | Successive conversion time ( $16 \times \mathrm{t}_{5}$ ) | 2 |  |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{12}$ | Address setup before $\overline{\mathrm{RD}}$ | 10 |  |  | ns |
| $\mathrm{t}_{13}$ | CS before end of RD | 30 |  |  | ns |
| $\mathrm{t}_{14}$ | $\overline{\mathrm{RD}}$ high time | 30 |  |  | ns |



Figure 27. Timing of One Conversion Cycle
READING DATA ( $\overline{\operatorname{RD}}, \overline{\mathbf{C S}}$ ) - In general, the channel/data outputs are in tristate. Both $\overline{\mathrm{CS}}$ and $\overline{\mathrm{RD}}$ have to be low to enable these outputs. $\overline{R D}$ and $\overline{C S}$ have to stay low together for at least 30ns (see Eigure_28, $t_{13}$ ) before the output data is valid. $\overline{R D}$ has to remain high for at least 30ns (see Figure 28, $\mathrm{t}_{14}$ ) before bringing it back low for a subsequent read command.
12.5 clock-cycles after the start of a conversion (BUSY going low), the new data is latched into its output register. If a read process is initiated around 12.5 clock cycles after BUSY went low, $\overline{R D}$ and $\overline{C S}$ should stay low for at least 50ns to get the new data stored to its register and switched to the output.
$\overline{\mathrm{CS}}$ being low tells the ADS7864 that the bus on the board is assigned to the ADS7864. If an A/D converter shares a bus with digital gates, there is a possibility that digital (high frequency) noise may be coupled into the A/D converter. If the bus is just used by the ADS7864, $\overline{\mathrm{CS}}$ can be hardwired to ground. Reading data at the falling edge of one of the hold signals might cause distortion of the hold value.


Figure 28. Timing for Reading Data

## OUTPUT CODE (DB15...DB0)

The ADS7864 has a 16 -bit output word. DB15 is ' 1 ' if the output contains valid data. This is important for the FIFO mode. Valid Data can be read until DB15 switches to 0. DB14, DB13 and DB12 store channel information as indicated in Table_2 (Channel Truth Table). The 12-bit output data is stored from DB11 (MSB) to DB0 (LSB).
BYTE-If there is only an 8-bit bus available on a board, then Byte can be set high (see Figure 29 and Figure 30). In this case, the lower eight bits can be read at the output pins DB7 to DB0 at the first $\overline{R D}$ signal, and the higher bits after the second $\overline{\mathrm{RD}}$ signal.

Table 2. Channel Truth Table

| DATA CHANNEL | DB14 | DB13 | DB12 |
| :---: | :---: | :---: | :---: |
| A0 | 0 | 0 | 0 |
| A1 | 0 | 0 | 1 |
| B0 | 0 | 1 | 0 |
| B1 | 0 | 1 | 1 |
| C0 | 1 | 0 | 0 |
| C1 | 1 | 0 | 1 |



Figure 29. Reading Data in Cycling Mode


Figure 30. Reading Data in Cycling Mode
from channel $A 0$ is read on the first $\overline{R D}$ signal, then A1 on the second, followed by B0, B1, C0 and finally C 1 before reading A 0 again. Data from channel A 0 is brought to the output first after a reset-signal or after powering the part up.

The third mode is a FIFO mode that is addressed with (A2 A1 A0 = 111). Data of the channel that is converted first will be read first. So, if a particular channel is most interesting and is converted more frequently (e.g., to get a history of a particular channel) then there are three output registers per channel available to store data. When the ADS7864 is operated in the FIFO mode, an initial $\overline{R D} / \overline{C S}$ is necessary (after power up and after reset), so that the internal address is set to '111', before the first conversion starts.

If a read process is just going on ( $\overline{R D}$ signal low) and new data has to be stored, then the ADS7864 will wait until the read process is finished ( $\overline{R D}$ signal going high) before the new data gets latched into its output register.

At time $\mathrm{t}_{\mathrm{A}}$ (see Figure 31) the ADS7864 resets. With the reset signal, all conversions and scheduled conversions are cancelled. The data in the output registers are also cleared. With a reset, a running conversion gets interrupted and all channels go into the sample mode again.

With $(A 2 A 1 A 0)=110$ the interface is running in a
cycle mode (see Figure 29 and Figure 30). Here, data
With $(A 2 A 1 A 0)=110$ the interface is running in a
cycle mode (see Figure 29 and Eigure_30). Here, data

## GETTING DATA

The ADS7864 has three different output modes that are selected with A2, A1 and A0. A2A1A0 are only active when $\overline{\mathrm{RD}}$ and $\overline{\mathrm{CS}}$ are both low. After a reset occurs, A2A1A0 are set to 000.

With $(A 2 A 1 A 0)=000$ to 101 a particular channel can directly be addressed (see Table 3 and Eigure 27). The channel address should be set at least 10ns (see Figure 28, $t_{12}$ ) before the falling edge of $\overline{R D}$ and should not change as long as $\overline{R D}$ is low.

Table 3. Address/Mode Truth Table

| CHANNEL <br> SELECTED/ <br> MODE | A2 | A1 | A0 |
| :---: | :---: | :---: | :---: |
| A0 | 0 | 0 | 0 |
| A1 | 0 | 0 | 1 |
| B0 | 0 | 1 | 0 |
| B1 | 0 | 1 | 1 |
| C0 | 1 | 0 | 0 |
| C1 | 1 | 0 | 1 |
| Cycle Mode | 1 | 1 | 0 |
| FIFO Mode | 1 | 1 | 1 |



Figure 31. Example of Hold Signals

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At time $t_{B}$ a HOLDB signal occurs. With the next falling clock edge ( $\mathrm{t}_{\mathrm{C}}$ ) the ADS7864 puts channel B into the loop to be converted next. As the reset signal occurred at $t_{A}$, the conversion of channel $B$ will be started with the next rising edge of the clock after $\mathrm{t}_{\mathrm{C}}$.
Within the next clock cycle ( $\mathrm{t}_{\mathrm{C}}$ to $\mathrm{t}_{\mathrm{F}}$ ), $\overline{\text { HOLDC }}\left(\mathrm{t}_{\mathrm{D}}\right)$ and HOLDA ( $\mathrm{t}_{\mathrm{E}}$ ) occur. If more than one hold signals get active within one clock cycle, channel $A$ will be converted first. Therefore, as soon as the conversion of channel $B$ is done, the conversion of channel $A$ will be initiated. After this second conversion, channel C will be converted.

The 16 bit output word has following structure:

| Valid Data | 3-Bit Channel <br> Information | 12-Bit Data Word |
| :---: | :---: | :---: |

Bit 15 shows if the FIFO is empty (low) or if it contains channel information (high). Bits 12 to 14 contain the Channel for the 12-bit data word (Bit 0 to 11). If the data is from channel $A 0$, then bits 14 to 12 are '000'. The Channel bit pattern is outlined in Table_2 (Channel Truth Table).

New data is always written into the next available register. At $t_{0}$ (see Figure 32), the reset deletes all the existing data. At $t_{1}$ the new data of the channels A0 and A1 are put into registers 0 and 1 . On $t_{2}$ the read process of channel A0 data is finished. Therefore, this data is dumped and A1 data is shifted to register 0 . At $t_{3}$ new data is available, this time from channel B 0 and B1. This data is written into the next available registers (register 1 and 2). The new data of channel C0 and C1 at $\mathrm{t}_{4}$ is put on top (registers 3 and 4).


Figure 32. Functionality Diagram of FIFO Registers
$10 \mu \mathrm{~F}$ capacitor is recommended. If needed, an even larger capacitor and a $5 \Omega$ or $10 \Omega$ series resistor may be used to low-pass filter a noisy supply. On average, the ADS7864 draws very little current from an external reference as the reference voltage is internally buffered. If the reference voltage is external and originates from an op amp, make sure that it can drive the bypass capacitor or capacitors without oscillation. A bypass capacitor must not be used when using the internal reference (tie pin 33 directly to pin 34). The AGND and DGND pins should be connected to a clean ground point. In all cases, this should be the 'analog' ground. Avoid connections which are too close to the grounding point of a microcontroller or digital signal processor. If required, run a ground trace directly from the converter to the power supply entry point. The ideal layout will include an analog ground plane dedicated to the converter and associated analog circuitry.

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## PACKAGING INFORMATION

| Orderable Device | Status <br> (1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan <br> (2) | Lead finish/ Ball material (6) | MSL Peak Temp <br> (3) | Op Temp ( ${ }^{\circ} \mathrm{C}$ ) | Device Marking (4/5) | Samples |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS7864Y/250 | ACTIVE | TQFP | PFB | 48 | 250 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | ADS7864Y | Samples |
| ADS7864Y/250G4 | ACTIVE | TQFP | PFB | 48 | 250 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR | -40 to 85 | ADS7864Y | Samples |
| ADS7864Y/2K | ACTIVE | TQFP | PFB | 48 | 2000 | RoHS \& Green | NIPDAU | Level-2-260C-1 YEAR |  | ADS7864Y | Samples |
| ADS7864YB/250 | ACTIVE | TQFP | PFB | 48 | 250 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR |  | ADS7864Y B | Samples |
| ADS7864YB/250G4 | ACTIVE | TQFP | PFB | 48 | 250 | RoHS \& Green | Call TI | Level-2-260C-1 YEAR |  | ADS7864Y B | Samples |
| ADS7864YB/2K | ACTIVE | TQFP | PFB | 48 | 2000 | RoHS \& Green | NIPDAU | Level-2-260C-1 YEAR |  | ADS7864Y B | Samples |

${ }^{(1)}$ The marketing status values are defined as follows:
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LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but Tl does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. Tl may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption
Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the $<=1000 \mathrm{ppm}$ threshold requirement
${ }^{(3)}$ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature
${ }^{(4)}$ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
${ }^{(5)}$ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
${ }^{(6)}$ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Falls within JEDEC MS-026

PFB (S-PQFP-G48)


NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC-7351 is recommended for alternate designs.
D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525.
E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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